

**THE CURVATURE TENSORS IN THE  
EINSTEIN'S  $*g$ -UNIFIED FIELD THEORY  
II. THE CONTRACTED  
SE-CURVATURE TENSORS OF  $*g$ -SEX $_n$**

KYUNG TAE CHUNG, PHIL UNG CHUNG AND IN HO HWANG

ABSTRACT. Chung and et al. ([2], 1991) introduced a new concept of a manifold, denoted by  $*g$ -SEX $_n$ , in Einstein's  $n$ -dimensional  $*g$ -unified field theory. The manifold  $*g$ -SEX $_n$  is a generalized  $n$ -dimensional Riemannian manifold on which the differential geometric structure is imposed by the unified field tensor  $*g^{\lambda\nu}$  through the SE-connection which is both Einstein and semi-symmetric. In this paper, they proved a necessary and sufficient condition for the unique existence of SE-connection and presented a beautiful and surveyable tensorial representation of the SE-connection in terms of the tensor  $*g^{\lambda\nu}$ . Recently, Chung and et al. ([3], 1998) obtained a concise tensorial representation of SE-curvature tensor defined by the SE-connection of  $*g$ -SEX $_n$  and proved several identities involving it.

This paper is a direct continuation of [3]. In this paper we derive surveyable tensorial representations of contracted curvature tensors of  $*g$ -SEX $_n$  and prove several generalized identities involving them. In particular, the first variation of the generalized Bianchi's identity in  $*g$ -SEX $_n$ , proved in Theorem (2.10a), has a great deal of useful physical applications.

## 1. Preliminaries

This paper is a direct continuation of our previous paper [3], which will be denoted by I in the present paper. All considerations in this paper are based on the results and symbolism of I. Whenever necessary,

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these results will be quoted in the text. In this section, we introduce a brief collection of basic concepts, notations, and results of I, which are frequently used in the present paper.

Let  $X_n$  be an  $n$ -dimensional generalized Riemannian manifold referred to a real coordinate system  $x^\nu$ . In the Einstein's usual  $n$ -dimensional unified field theory, the manifold  $X_n$  is endowed with a real non-symmetric tensor  $g_{\lambda\mu}$ , which may be decomposed into its symmetric part  $h_{\lambda\mu}$  and skew-symmetric part  $k_{\lambda\mu}$ :

$$(1.1a) \quad g_{\lambda\mu} = h_{\lambda\mu} + k_{\lambda\mu},$$

where

$$(1.1b) \quad \det(g_{\lambda\mu}) \neq 0, \quad \det(h_{\lambda\mu}) \neq 0.$$

In our  $n$ -dimensional  $*g$ -unified field theory ( $n$ - $*g$ -UFT hereafter), however, the algebraic structure on  $X_n$  is imposed by the basic real tensor  $*g^{\lambda\nu}$ , defined by

$$(1.2a) \quad g_{\lambda\mu} *g^{\lambda\nu} \stackrel{\text{def}}{=} g_{\mu\lambda} *g^{\nu\lambda} \stackrel{\text{def}}{=} \delta_\mu^\nu.$$

It may be also decomposed into its symmetric part  $*h^{\lambda\nu}$  and skew-symmetric part  $*k^{\lambda\nu}$ :

$$(1.2b) \quad *g^{\lambda\nu} = *h^{\lambda\nu} + *k^{\lambda\nu}.$$

Since  $\det(*h^{\lambda\nu}) \neq 0$ , we may define a unique tensor  $*h_{\lambda\mu}$  by

$$(1.2c) \quad *h_{\lambda\mu} *h^{\lambda\nu} \stackrel{\text{def}}{=} \delta_\mu^\nu.$$

In  $n$ - $*g$ -UFT we use both  $*h^{\lambda\nu}$  and  $*h_{\lambda\mu}$  as tensors for raising and/or lowering indices of all tensors defined in  $X_n$  in the usual manner.

On the other hand, the differential geometric structure on  $X_n$  is imposed by the tensor  $*g^{\lambda\nu}$  by means of a connection  $\Gamma_{\lambda\mu}^\nu$  defined by a system of equations

$$(1.3) \quad D_\omega *g^{\lambda\nu} = -2S_{\omega\alpha}{}^\nu *g^{\lambda\alpha}.$$

Here  $D_\omega$  denotes the symbol of the covariant derivative with respect to  $\Gamma_{\lambda\mu}^\nu$  and  $S_{\lambda\mu}^\nu$  is the torsion tensor of  $\Gamma_{\lambda\mu}^\nu$ . Under certain conditions the system (1.3) admits a unique solutions  $\Gamma_{\lambda\mu}^\nu$ . A connection is said to be *Einstein* if it satisfies (1.3).

A connection  $\Gamma_{\lambda\mu}^\nu$  is said to be *semi-symmetric* if its torsion tensor  $S_{\lambda\mu}^\nu$  is of the form

$$(1.4) \quad S_{\lambda\mu}^\nu = 2\delta_{[\lambda}^\nu X_{\mu]}$$

for an arbitrary vector  $X_\lambda \neq 0$ , which is not a gradient vector. A connection which is both semi-symmetric and Einstein is called a *SE-connection*. An  $n$ -dimensional generalized Riemannian manifold  $X_n$ , on which the differential geometric structure is imposed by the tensor  $*g^{\lambda\nu}$  by means of a SE-connection, is called an  *$n$ -dimensional  $*g\text{-SE-manifold}$* . We denote this manifold by  $*g\text{-SEX}_n$  in our further considerations.

In the present paper, we frequently use the following abbreviations for an arbitrary vector  $Y_\lambda$ , for  $p = 1, 2, 3, \dots$ :

$$(1.5a) \quad (0)*k_\lambda^\nu = \delta_\lambda^\nu, \quad (p)*k_\lambda^\nu = *k_\lambda^\alpha (p-1)*k_\alpha^\nu$$

$$(1.5b) \quad (p)Y^\nu = (p-1)*k^\nu_\alpha Y^\alpha = *k^\nu_\alpha (p-1)Y^\alpha.$$

**THEOREM 1.1.** *The SE-connection  $\Gamma_{\lambda\mu}^\nu$  of  $*g\text{-SEX}_n$  may be given by*

$$(1.6a) \quad \Gamma_{\lambda\mu}^\nu = *\{ \begin{smallmatrix} \nu \\ \lambda\mu \end{smallmatrix} \} + S_{\lambda\mu}^\nu + U^\nu_{\lambda\mu},$$

where  $*\{ \begin{smallmatrix} \nu \\ \lambda\mu \end{smallmatrix} \}$  is the Christoffel symbols defined by  $*h_{\lambda\mu}$ , and

$$(1.6b) \quad S_{\lambda\mu}^\nu = 2\delta_{[\lambda}^\nu X_{\mu]}, \quad U^\nu_{\lambda\mu} = -*h_{\lambda\mu}^{(2)} X^\nu.$$

Let

$$(1.7) \quad S_\lambda \stackrel{\text{def}}{=} S_{\lambda\alpha}^\alpha, \quad U_\lambda \stackrel{\text{def}}{=} U^\alpha_{\lambda\alpha}.$$

THEOREM 1.2. In  $*g\text{-SEX}_n$  under the present conditions<sup>1</sup>, the vectors  $X_\lambda$ ,  $S_\lambda$ , and  $U_\lambda$  are involved in the following identities, for  $p, q = 1, 2, 3, \dots$ :

$$(1.8a) \quad S_\lambda = (1 - n)X_\lambda$$

$$(1.8b) \quad U_\lambda = -^{(2)}X_\lambda = -\frac{1}{2} \partial_\lambda \ln *g, \quad \text{where } *g \stackrel{\text{def}}{=} \frac{\det(*g_{\lambda\mu})}{\det(*h_{\lambda\mu})}$$

$$(1.8c) \quad {}^{(p+1)}S_\lambda = (1 - n) {}^{(p+1)}X_\lambda = (n - 1) {}^{(p)}U_\lambda$$

$$(1.8d) \quad {}^{(p)}U_\alpha {}^{(q)}X^\alpha = (-1)^{p+1} {}^{(p+q-1)*}k_{\beta\gamma} X^\beta X^\gamma$$

$$(1.8e) \quad {}^{(p)}U_\alpha {}^{(q)}X^\alpha = 0, \quad \text{if } p + q - 1 \text{ is odd}$$

$$(1.8f) \quad D_\lambda X_\mu = \nabla_\lambda X_\mu$$

$$(1.8g) \quad D_{[\lambda} X_{\mu]} = \nabla_{[\lambda} X_{\mu]} = \partial_{[\lambda} X_{\mu]}$$

$$(1.8h) \quad \nabla_{[\lambda} U_{\mu]} = 0, \quad D_{[\lambda} U_{\mu]} = 2U_{[\lambda} X_{\mu]} = -2 {}^{(2)}X_{[\lambda} X_{\mu]}$$

where  $\nabla_\lambda$  is the symbolic vector of the covariant derivative with respect to  $*\{\overset{\nu}{\lambda}_\mu\}$ .

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<sup>1</sup>The situation that the conditions in Agreement I.2.5 are imposed on our  $*g\text{-SEX}_n$  are described in this paper by the words “present conditions”.

**THEOREM 1.3.** *Under the present conditions, the SE-curvature tensor  $R_{\omega\mu\lambda}{}^\nu$  of  $*g$ -SEX $_n$  may be given by*

$$(1.9) \quad R_{\omega\mu\lambda}{}^\nu = *H_{\omega\mu\lambda}{}^\nu + M_{\omega\mu\lambda}{}^\nu + N_{\omega\mu\lambda}{}^\nu,$$

where

$$(1.10a) \quad *H_{\omega\mu\lambda}{}^\nu = 2(\partial_{[\mu} * \{ \}_{\omega]\lambda}{}^\nu + * \{ \}_{\alpha[\mu}{}^\nu \} \{ \}_{\omega]\lambda}{}^\alpha),$$

$$(1.10b) \quad M_{\omega\mu\lambda}{}^\nu = 2(\delta_\lambda^\nu \partial_{[\mu} X_{\omega]} + \delta_{[\mu}^\nu \nabla_{\omega]} X_\lambda - *h_{\lambda[\omega} \nabla_{\mu]}^{(2)} X^\nu),$$

$$(1.10c) \quad N_{\omega\mu\lambda}{}^\nu = 2(\delta_{[\mu}^\nu X_{\omega]} X_\lambda + *h_{\lambda[\omega} X_{\mu]}^{(2)} X^\nu).$$

**THEOREM 1.4** (Generalized Bianchi's identity in  $*g$ -SEX $_n$ ). *Under the present conditions, the SE-curvature tensor  $R_{\omega\mu\lambda}{}^\nu$  of  $*g$ -SEX $_n$  satisfies the following identity:*

$$(1.11a) \quad D_{[\xi} R_{\omega\mu]\lambda}{}^\nu = -4X_{[\xi} *H_{\omega\mu]\lambda}{}^\nu + Z_{[\xi\omega\mu]\lambda}{}^\nu,$$

where

$$(1.11b) \quad \begin{aligned} \frac{1}{8} Z_{\xi\omega\mu\lambda}{}^\nu &= \{ \delta_\lambda^\nu X_\xi \partial_\omega X_\mu + X_\xi \delta_\omega^\nu \nabla_\mu X_\lambda \\ &- X_\xi \nabla_\omega (*h_{\mu\lambda}^{(2)} X^\nu) \} - *h_{\lambda\xi} X_\omega^{(2)} X_\mu^{(2)} X^\nu. \end{aligned}$$

## 2. The contracted SE-curvature tensors

This section is devoted to the study of the contracted  $n$ -dimensional SE-curvature tensors, defined by the SE-connection in  $*g$ -UFT under the present conditions, and of some useful identities involving them.

The tensors

$$(2.1) \quad R_{\mu\lambda} \stackrel{\text{def}}{=} R_{\alpha\mu\lambda}{}^\alpha, \quad V_{\omega\mu} \stackrel{\text{def}}{=} R_{\omega\mu\alpha}{}^\alpha$$

are called *the first and the second contracted SE-curvature tensors* of the SE-connection  $\Gamma_{\lambda\mu}^\nu$ , respectively. We see in the following two theorems that they appear as functions of the vectors  $X_\lambda$ ,  $S_\lambda$ ,  $U_\lambda$ , and hence also as functions of  $*g_{\lambda\mu}$  and its first two derivatives in virtue of (1.8a, b) and I (2.25).

**THEOREM 2.1.** *The second contracted SE-curvature tensor  $V_{\omega\mu}$  in  ${}^*g$ -SEX $_n$  under the present conditions is a curl of the vector  $S_\lambda$ . That is,*

$$(2.2) \quad V_{\omega\mu} = 2 \partial_{[\omega} S_{\mu]}.$$

*Proof.* Putting  $\lambda = \nu = \alpha$  in (1.9), we have

$$(2.3) \quad V_{\omega\mu} = {}^*H_{\omega\mu\alpha}{}^\alpha + M_{\omega\mu\alpha}{}^\alpha + N_{\omega\mu\alpha}{}^\alpha.$$

In virtue of I(3.12) and (1.8a, b, h), the relations (1.10a, b, c) give

$${}^*H_{\omega\mu\alpha}{}^\alpha = N_{\omega\mu\alpha}{}^\alpha = 0$$

$$M_{\omega\mu\alpha}{}^\alpha = -2n \partial_{[\omega} X_{\mu]} + 2\nabla_{[\omega} X_{\mu]} = 2(1-n)\partial_{[\omega} X_{\mu]} = 2\partial_{[\omega} S_{\mu]},$$

which together with (2.3) proves our assertion.  $\square$

**THEOREM 2.2.** *The first contracted SE-curvature tensor  $R_{\mu\lambda}$  in  ${}^*g$ -SEX $_n$  under the present conditions may be given by*

$$(2.4) \quad R_{\mu\lambda} = {}^*H_{\mu\lambda} + 2 \partial_{[\mu} X_{\lambda]} + \nabla_\mu T_\lambda - {}^*h_{\mu\lambda}(\nabla_\alpha U^\alpha + U_\alpha U^\alpha) \\ + (1-n)X_\mu X_\lambda + U_\mu U_\lambda,$$

where

$$(2.5a) \quad {}^*H_{\mu\lambda} \stackrel{\text{def}}{=} {}^*H_{\alpha\mu\lambda}{}^\alpha$$

$$(2.5b) \quad T_{\lambda\mu}{}^\nu \stackrel{\text{def}}{=} S_{\lambda\mu}{}^\nu + U^\nu{}_{\lambda\mu}, \quad T_\lambda \stackrel{\text{def}}{=} T_{\lambda\alpha}{}^\alpha = S_\lambda + U_\lambda.$$

*Proof.* Putting  $\omega = \nu = \alpha$  in (1.9) and making use of (2.5a), we have

$$(2.6) \quad R_{\mu\lambda} = {}^*H_{\mu\lambda} + M_{\alpha\mu\lambda}{}^\alpha + N_{\alpha\mu\lambda}{}^\alpha.$$

In virtue of (1.8a, b), it follows from (1.10b) that

$$(2.7a) \quad M_{\alpha\mu\lambda}{}^\alpha = 2 \partial_{[\mu} X_{\lambda]} + (1-n)\nabla_\mu X_\lambda + {}^*h_{\mu\lambda} \nabla_\alpha ({}^2X)^\alpha - \nabla_\mu ({}^2X)_\lambda \\ = 2 \partial_{[\mu} X_{\lambda]} + \nabla_\mu T_\lambda - {}^*h_{\mu\lambda} \nabla_\alpha U^\alpha.$$

On the other hand, in virtue of (1.8b) the relation (1.10c) gives

$$(2.7b) \quad N_{\alpha\mu\lambda}{}^\alpha = (1-n)X_\mu X_\lambda + ({}^2X)_\mu ({}^2X)_\lambda - {}^*h_{\mu\lambda} ({}^2X)_\alpha ({}^2X)^\alpha \\ = (1-n)X_\mu X_\lambda + U_\mu U_\lambda - {}^*h_{\mu\lambda} U_\alpha U^\alpha.$$

Our assertion follows immediately from (2.6) and (2.7a, b).  $\square$

**THEOREM 2.3.** *The tensor  $R_{\mu\lambda}$  is symmetric when  $n = 3$ .*

*Proof.* The relation (2.4) may be written as

$$(2.8) \quad R_{\mu\lambda} = {}^*H_{\mu\lambda} + (3 - n)\nabla_{\mu}X_{\lambda} - 2\nabla_{(\mu}X_{\lambda)} + \nabla_{\mu}U_{\lambda} \\ - {}^*h_{\mu\lambda}(\nabla_{\alpha}U^{\alpha} + U_{\alpha}U^{\alpha}) + (1 - n)X_{\mu}X_{\lambda} + U_{\mu}U_{\lambda},$$

where use has been made of (1.8a, g) and (2.5b). Hence, in virtue of (1.8g, h) we have

$$R_{[\mu\lambda]} = 0 \quad \text{if and only if} \quad (3 - n)\nabla_{[\mu}X_{\lambda]} = (3 - n)\partial_{[\mu}X_{\lambda]} = 0$$

from which our assertion follows. □

**REMARK 2.4.** In the proof of the Theorem (2.3), we excluded the case that  $\partial_{[\mu}X_{\lambda]} = 0$ , because we assumed that  $X_{\lambda}$  is not a gradient vector in the definition of semi-symmetric connection in (1.4). In fact, the assumption that  $X_{\lambda}$  is not a gradient vector is essential in the discussions of the field equations in  $*g$ -SEX $_n$ .

**THEOREM 2.5.** *The contracted SE-curvature tensors in  $*g$ -SEX $_n$  under the present conditions are related by*

$$(2.9) \quad 2R_{[\mu\lambda]} = 4\partial_{[\mu}X_{\lambda]} + V_{\mu\lambda}.$$

*Proof.* In virtue of (1.8a, g, h), the relation (2.9) may be proved from (2.8) as in the following way:

$$2R_{[\mu\lambda]} = 2(3 - n)\partial_{[\mu}X_{\lambda]} \\ = 2(1 - n)\partial_{[\mu}X_{\lambda]} + 4\partial_{[\mu}X_{\lambda]} \\ = 2\partial_{[\mu}S_{\lambda]} + 4\partial_{[\mu}X_{\lambda]} \\ = V_{\mu\lambda} + 4\partial_{[\mu}X_{\lambda]}.$$

□

REMARK 2.6. An alternative proof of the Theorem (2.5) may be obtained as follows: Putting  $\lambda = \nu = \alpha$  in the identity I (4.6)

$$R_{[\omega\mu\lambda]}{}^\nu = 4\delta_{[\lambda}^\nu\partial_{\mu]}X_{\omega]}$$

and using (1.8a), we have

$$V_{\omega\mu} - R_{\mu\omega} + R_{\omega\mu} = 4\partial_{[\omega}S_{\mu]} + 4\partial_{[\omega}X_{\mu]},$$

from which the relation (2.9) follows.

Our next task is to obtain a generalization of the classical identity

$$(2.10) \quad \nabla_\alpha E_\mu{}^\alpha = 0,$$

where

$$(2.11) \quad *H \stackrel{\text{def}}{=} *h^{\alpha\beta} *H_{\alpha\beta}, \quad E_\mu{}^\nu \stackrel{\text{def}}{=} *H_\mu{}^\nu - \frac{1}{2}\delta_\mu^\nu *H.$$

REMARK 2.7. The tensor  $E_\mu{}^\nu$  is called the *Einstein tensor*. This tensor has a great deal of applications in physics. It is of fundamental importance since its divergence vanishes identically as we see in (2.10).

In our further considerations, the quantities

$$(2.12) \quad R \stackrel{\text{def}}{=} *h^{\alpha\beta} R_{\alpha\beta}, \quad G_\mu{}^\nu \stackrel{\text{def}}{=} R_\mu{}^\nu - \frac{1}{2}\delta_\mu^\nu R$$

will be referred to *SE-curvature invariant and SE-Einstein tensor of  $*g$ -SEX<sub>n</sub>*, respectively. The tensor  $G_\mu{}^\nu$  is the generalized concept of  $E_\mu{}^\nu$ . First of all, we need the following two theorems in order to generalize the identity (2.10) in  $*g$ -SEX<sub>n</sub> under the present conditions.

THEOREM 2.8. *In  $*g$ -SEX<sub>n</sub> under the present conditions, we have*

$$(2.13a) \quad D_\omega *h^{\lambda\nu} = 2 *h^{\lambda\nu} X_\omega - 2\delta_\omega^{(\lambda}(X^{\nu)} + {}^{(2)}X^{\nu)}).$$

*In particular,*

$$(2.13b) \quad D_\alpha *h^{\lambda\alpha} = S^\lambda + (n+1)U^\lambda.$$



*Proof.* Substituting (1.4) into (1.3) for  $S_{\omega\alpha}{}^\nu$  and making use of (1.2b) and (1.5b), the relation (2.13a) follows as in the following way:

$$\begin{aligned} D_\omega *h^{\lambda\nu} &= D_\omega *g^{(\lambda\nu)} = -2S_{\omega\alpha}{}^{(\nu} *g^{\lambda)\alpha} \\ &= (\delta_\alpha^\nu X_\omega - \delta_\omega^\nu X_\alpha)(*h^{\lambda\alpha} + *k^{\lambda\alpha}) + (\delta_\alpha^\lambda X_\omega - \delta_\omega^\lambda X_\alpha)(*h^{\nu\alpha} + *k^{\nu\alpha}) \\ &= 2*h^{\lambda\nu}X_\omega - 2\delta_\omega^{(\lambda}(X^{\nu)} + {}^{(2)}X^{\nu)}). \end{aligned}$$

In virtue of (1.8a, b), the relation (2.13b) is a direct consequence of (2.13a).  $\square$

**THEOREM 2.9.** *In  $*g$ -SEX $_n$  under the present conditions, we have*

$$(2.14a) \quad R = *H + (1 - n)(\nabla_\alpha X^\alpha + \nabla_\alpha U^\alpha + U + X),$$

$$(2.14b) \quad D_\alpha R_\mu{}^\alpha = \nabla_\alpha R_\mu{}^\alpha + (U_\alpha - nX_\alpha)R_\mu{}^\alpha + RX_\mu - U^\alpha R_{\alpha\mu},$$

where

$$(2.14c) \quad X \stackrel{\text{def}}{=} X_\alpha X^\alpha, \quad U \stackrel{\text{def}}{=} U_\alpha U^\alpha.$$

*Proof.* In virtue of (2.11), (2.12), and (1.8a, g), the representation (2.14a) follows from (2.4). On the other hand, the representation (2.14b) may be proved as in the following way in virtue of (1.6a, b), (1.7), (1.8a, b), and (2.12):

$$\begin{aligned} D_\alpha R_\mu{}^\alpha &= \partial_\alpha R_\mu{}^\alpha + \Gamma_{\beta\alpha}^\alpha R_\mu{}^\beta - \Gamma_{\mu\alpha}^\beta R_\beta{}^\alpha \\ &= \nabla_\alpha R_\mu{}^\alpha + (S_\beta + U_\beta)R_\mu{}^\beta - S_{\mu\alpha}{}^\beta R_\beta{}^\alpha - U^\beta{}_{\mu\alpha} R_\beta{}^\alpha \\ &= \nabla_\alpha R_\mu{}^\alpha + \{(1 - n)X_\alpha + U_\alpha\}R_\mu{}^\alpha + 2\delta_{[\alpha}^\beta X_{\mu]} R_\beta{}^\alpha - *h_{\mu\alpha} U^\beta R_\beta{}^\alpha \\ &= \nabla_\alpha R_\mu{}^\alpha + (U_\alpha - nX_\alpha)R_\mu{}^\alpha + RX_\mu - U^\alpha R_{\alpha\mu}. \end{aligned} \quad \square$$

Now we are ready to prove the following generalization of (2.10).

**THEOREM 2.10a** (First variation of the generalized Bianchi's identity in  $*g$ -SEX $_n$ ). *The SE-Einstein tensor  $G_\mu^\nu$  satisfies the following identity in  $*g$ -SEX $_n$  under the present conditions:*

$$(2.15a) \quad D_\alpha G_\mu^\alpha = P_\mu - \frac{1}{2} \partial_\mu M,$$

where

$$(2.15b) \quad P_\mu = \nabla_\alpha (R_\mu^\alpha - *H_\mu^\alpha) + (U_\alpha - nX_\alpha) R_\mu^\alpha + R X_\mu - U^\alpha R_{\alpha\mu},$$

$$(2.15c) \quad M = \frac{1-n}{2} (\nabla_\alpha X^\alpha + \nabla_\alpha U^\alpha + U + X).$$

*Proof.* The relation (2.12) gives

$$(2.16) \quad D_\alpha G_\mu^\alpha = D_\alpha R_\mu^\alpha - \frac{1}{2} \partial_\mu R.$$

The proof of the identity (2.15a) immediately follows by substituting (2.14a, b) into (2.16) and making use of (2.15b, c) and the following classical identity:

$$\nabla_\alpha *H_\mu^\alpha = \frac{1}{2} \partial_\mu *H. \quad \square$$

**THEOREM 2.10b** (Second variation of the generalized Bianchi's identity in  $*g$ -SEX $_n$ ). *The SE-Einstein tensor  $G_\mu^\nu$  satisfies the following identity in  $*g$ -SEX $_n$  under the present conditions:*

$$(2.17a) \quad \begin{aligned} 2D_\alpha G_\mu^\alpha = & X^\alpha C_{\mu\alpha} + U^\alpha D_{\mu\alpha} - 2R X_\mu + \partial_\mu R \\ & - 3 *h^{\omega\lambda} Z_{[\beta\omega\mu]\lambda}^\beta + 2 *h^{\omega\lambda} D_\beta (R_{\omega\mu(\lambda\alpha)} *h^{\alpha\beta}), \end{aligned}$$

where  $Z_{\xi\omega\mu\lambda}^\nu$  is given by (1.11b), and

$$(2.17b) \quad C_{\mu\alpha} = (4-n)R_{\mu\alpha} + R_{\alpha\mu} - V_{\alpha\mu} - 8E_{\mu\alpha} - R_{\beta\mu\gamma\alpha} *h^{\gamma\beta},$$

$$(2.17c) \quad D_{\mu\alpha} = -R_{\alpha\mu} + n R_{\mu\alpha} + V_{\alpha\mu} + R_{\beta\mu\gamma\alpha} *h^{\gamma\beta}.$$

*Proof.* The proof of this theorem is based on the generalized Bianchi's identity (1.11). It may be written in the form

$$\begin{aligned} & -D_\xi(R_{\omega\mu\alpha\lambda} *h^{\nu\alpha}) + D_\omega R_{\mu\xi\lambda}{}^\nu + D_\mu R_{\xi\omega\lambda}{}^\nu \\ & = -12 X_{[\xi} *H_{\omega\mu]\lambda}{}^\nu + 3 Z_{[\xi\omega\mu]\lambda}{}^\nu - 2 D_\xi(R_{\omega\mu(\lambda\alpha)} *h^{\nu\alpha}). \end{aligned}$$

If we contract for  $\nu$  and  $\xi$  and multiply  $*h^{\omega\lambda}$  to both sides of the above equation, we have

$$\begin{aligned} (2.18) \quad & - *h^{\omega\lambda} D_\beta(R_{\omega\mu\alpha\lambda} *h^{\alpha\beta}) - *h^{\omega\lambda} D_\omega R_{\mu\lambda} + *h^{\omega\lambda} D_\mu R_{\omega\lambda} \\ & = -12 *h^{\omega\lambda} X_{[\beta} *H_{\omega\mu]\lambda}{}^\beta + 3 *h^{\omega\lambda} Z_{[\beta\omega\mu]\lambda}{}^\beta - 2 *h^{\omega\lambda} D_\beta(R_{\omega\mu(\lambda\alpha)} *h^{\alpha\beta}) \end{aligned}$$

In virtue of (1.8b), (2.1), (2.12), and (2.13a), the terms on the left-hand side of (2.18) are the ones to be rewritten as

(2.19a)

the first term

$$\begin{aligned} & = -D_\beta(R_{\omega\mu\alpha\lambda} *h^{\alpha\beta} *h^{\omega\lambda}) + R_{\omega\mu\alpha\lambda} *h^{\alpha\beta} D_\beta *h^{\omega\lambda} \\ & = -D_\beta R_{\mu}{}^\beta + 2R_{\omega\mu\alpha\lambda} *h^{\alpha\beta} *h^{\omega\lambda} X_\beta - \delta_\beta^{(\omega} (X^\lambda) + {}^{(2)}X^\lambda) \\ & = -D_\alpha R_{\mu}{}^\alpha + 2R_{\mu\alpha} X^\alpha - V_{\alpha\mu}(X^\alpha - U^\alpha) - R_{\beta\mu\gamma\alpha} *h^{\gamma\beta}(X^\alpha - U^\alpha), \end{aligned}$$

(2.19b)

the second term

$$\begin{aligned} & = -D_\omega R_{\mu}{}^\omega + R_{\mu\lambda} D_\omega *h^{\omega\lambda} \\ & = -D_\alpha R_{\mu}{}^\alpha + (1-n)R_{\mu\alpha} X^\alpha + (n+1)R_{\mu\alpha} U^\alpha, \end{aligned}$$

(2.19c)

the third term

$$\begin{aligned} & = D_\mu R - R_{\omega\lambda} D_\mu *h^{\omega\lambda} \\ & = D_\mu R - R_{\omega\lambda} (2 *h^{\omega\lambda} X_\mu - 2 \delta_\mu^{(\omega} (X^\lambda) + {}^{(2)}X^\lambda) \\ & = D_\mu R - 2RX_\mu + R_{\mu\alpha} X^\alpha + R_{\alpha\mu} X^\alpha - R_{\mu\alpha} U^\alpha - R_{\alpha\mu} U^\alpha. \end{aligned}$$

On the other hand, the relations (2.5a) and (2.11) allow the first term on the right-hand side of (2.18) to be expressed in the form

$$(2.19d) \quad -12 *h^{\omega\lambda} X_{[\beta} *H_{\omega\mu]\lambda}{}^\beta = 8X_\alpha E_\mu{}^\alpha.$$

We now substitute (2.19a, b, c, d) into (2.18) to complete the proof of (2.17).  $\square$

REMARK 2.11. Several earlier authors, such as Bose (1953), Einstein (1955), Lichnerowicz (1955), Schrödinger (1949), and Winogradski (1956) tried to generalize (2.10) on a manifold  $X_n$  to which Einstein's connection is connected, but their results are cumbersome. Note that our result (2.15) in Theorem (2.10), which holds on the manifold  $*g$ -SEX $_n$  under the present conditions, is very handy and surveyable tensorial form. On the other hand, comparing the expressions (2.15) and (2.17), we note that the former is more refined. The identity (2.17) contains the last two terms which are too complicated.

## References

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KYUNG TAE CHUNG, DEPARTMENT OF MATHEMATICS, YONSEI UNIVERSITY, SEOUL 120-749, KOREA

PHIL UNG CHUNG, DEPARTMENT OF MATHEMATICS, KANGWON NATIONAL UNIVERSITY, CHUNCHEON 200-701, KOREA

IN HO HWANG, DEPARTMENT OF MATHEMATICS, UNIVERSITY OF INCHON, INCHON 402-749, KOREA

*E-mail:* ho818@lion.inchon.ac.kr