Autonomous Indoor Lighting Device Control System Based on Wireless Sensor Network

Mr. Tahidul Islam, Insoo Koo

Abstract In this paper, we propose an autonomous Indoor lighting control system in which indoor lighting devices are autonomously controlled such that electricity bills are minimized in our daily life. Our focus is to utilize Passive Infrared (PIR) sensors to detect the presence of human being indoor and automatically to control indoor lighting electric devices. A control algorithm is also devised to control the whole system. We justify the proposed system by demonstrating specific applications in our everyday life. Cost survey and experimental results also demonstrate the efficiency of the proposed system in real life.

Key Words: Indoor lighting device, autonomous control system, passive infrared sensor, wireless sensor network.

I. Introduction

A wireless Sensor Network (WSN) is a wireless network that consists of several sensors to monitor physical or environmental conditions such as temperature, lighting, sound, vibration, pressure, motion or pollutant at different locations. Wide varieties of these applications have been enabled by the promise of inexpensive networks of wireless sensors. Dramatic advances in communication systems, micro-electro mechanical systems (MEMS), and Integrated Circuit (IC) design reduce the cost of sensor nodes, which in turn enables the use of large scale WSN for a variety of monitoring and controlling of applications [1].

In recent time, WSNs have been applied to energy conservation applications such as light control [2] - [5]. In the reference [2], authors proposed a light control system that considers both users’ preferences and energy conservation. However, in the system the basic limitation is that users must carry light sensors to measure their current light intensities.
In the reference\textsuperscript{[3]}, a WSN-based intelligent light control system for indoor environments is intended. The whole system that was proposed in the reference\textsuperscript{[3]} also requires control hosts to control the system, which are complicated and costly. Other possible applications of WSN include smart home applications\textsuperscript{[6]}, living space\textsuperscript{[7]}, environmental monitoring\textsuperscript{[8][9]}, etc. There are some alternatives such as vibration sensors, thermal sensors, etc. for detecting human presence in indoor environment. Unfortunately, such approaches still cannot provide satisfactory solutions to consider both user comfort and cost minimization so far.

This paper presents application of WSN to control indoor electric devices at home, office or similar environment. Based on the controlling of electricity, this scheme provides the service of saving our electricity. For example, we have considered an environment of one room having two doors. A system model of this environment is shown in Fig. 1. At every door, two PIR sensors are set up, where one for detecting peoples’ entering into the room and another is to detect peoples’ exiting from the room. After getting the signal, all signals sensed by the sensors are sent to central sensor and central sensor sends signal to micro-controller to control the electric devices by a control algorithm.

Rest of the paper is structured as follows. Section II introduces the system model. Section III presents our control algorithm, Section IV deduces cost minimization, and Section V contains simulation result. Conclusions are drawn in Section VI.

\section*{II. System Model}

In order to illustrate the proposed system model, we consider a room having \(n\) number of doors. Each door has total two sensors. Thus the entire number of sensors is two times of total number of doors in the room, i.e. (2\(n\)). Each sensor has a response to indicate the number of people in the room. Overall, we define a general matrix \(\mathbf{D}\) to summarize the responses of all sensors of the room, which is as follows:

\[
\mathbf{D} = \begin{bmatrix}
    d_{11} & d_{12} \\
    d_{21} & d_{22} \\
    d_{31} & d_{32} \\
    \vdots & \vdots \\
    d_{n1} & d_{n2}
\end{bmatrix}
\]  

(1)

The matrix has \((i, j)\) entry where \((i = 1 \text{ to } n)\) and \((j = 1 \text{ to } 2)\). In matrix \(\mathbf{D}\), the \((i, 1)^{th}\) entry designates
$1^{st}$ sensor ($S1$) and the $(i,2)^{th}$ entry specifies $2^{nd}$ sensor ($S2$) at the $i^{th}$ door. Since every door has two sensors, we utilized the $S1$ of each door to detect entering of people into the room and the $S2$ to detect exiting of people from the room (sensor’s detecting procedure will be clarified in later section). The response of $S1$ at all doors, which is denoted by $D(i,1)$ can have the value zero for no signal or greater than zero for any signal such that $D(i,1) \geq 0$. On the other hand, the response of $S2$ at all doors, which is denoted by $D(i,2)$ can have the value zero for no signal or smaller than zero for any signal such that $D(i,1) \leq 0$.

To demonstrate a simplified model, we assume two doors ($n=2$) in the room. Therefore, the simplified form can be articulated by the following matrix,

$$D = \begin{bmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{bmatrix}$$ (2)

If any person enters into the room by $door1$, then the response of $S1$ of $door1$ i.e. $d_{11}$ will be one, for two people’s entering in the room by $door1$ i.e. $d_{11}$ will be two and so on. Again, if any person exits by $door1$ then the response of $S2$ of $door1$ i.e. $d_{12}$ will be one, for two people’s exiting from the room $d_{12}$ will be two and so on. Moreover, if any person enters by $door2$ then the response of $S1$ of $door2$ i.e. $d_{21}$ will be one, for two people’s entering into the room $d_{21}$ will be two and so on. Furthermore, if any person exits by $door2$ then the response of $S2$ of $door2$ i.e. $d_{22}$ will be one, for two people’s exiting from the room $d_{22}$ will be two and so on.

For the above example, no people’s entering into the room can be expressed by the following summation,

$$\sum_{i=1}^{2} \sum_{j=1}^{2} D(i,j) = 0$$ (3)

In addition, for one or more people’s entering into the room the response can be conveyed by the following summation,

$$\sum_{i=1}^{2} \sum_{j=1}^{2} D(i,j) > 0$$ (4)

For example, let us assume that, one person enters through $door2$, so $d_{21} = 1$ and if that person exits through $door1$ then $d_{12} = -1$, which forms the matrix we get,

$$D = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$ (5)

For the above case the response of all sensors,

$$\sum_{i=1}^{2} \sum_{j=1}^{2} D(i,j) = 0$$, which indicates no person is at room.
In addition to that, let us assume that two people enter through the door2, thus $d_{21} = 2$. If one person exits through the door1 then $d_{12} = -1$. In this case the matrix is

$$D = \begin{bmatrix} 0 & -1 \\ 2 & 0 \end{bmatrix}$$  \hspace{1cm} (6)

Here $\sum_{i=1}^{2} \sum_{j=1}^{2} D(i, j) = 1$, which indicates one person is still now at room.

In general, people's absence for all doors can be stated as,

$$\sum_{i=1}^{n} \sum_{j=1}^{2} D(i, j) = 0$$  \hspace{1cm} (7)

Furthermore, for one or more peoples presence at home for all doors can be stated as,

$$\sum_{i=1}^{n} \sum_{j=1}^{2} D(i, j) > 0$$  \hspace{1cm} (8)

### III. Control Algorithm

In this model, Passive infrared (PIR) sensor is utilized. All objects constantly exchange thermal energy in the form of electromagnetic radiations with their surroundings. The characteristics of the radiations depend on the object and its surroundings' absolute temperature and can be analyzed using black body radiations curve governed by Plank's law \(^{[11]}\). Human bodies also emit radiation and the wavelength of these radiations can be calculated using Wien's law, which is given by (9),

$$\lambda = 2898 \text{ microns} / T$$  \hspace{1cm} (9)

where $\lambda$ is wavelength of the emission in nanometer, $T$ is absolute temperature in K. Substituting $T= 310$ K (370 C normal human body temperature) in (9), yields a value for $\lambda$ of 9348 nm or approximately 10 $\mu$m. In fact, radiation from the human body is considered to lie in the range of 8-14 $\mu$m, hence infrared sensors that are sensitive in this range would be able to detect humans within their
detection area. The standard infrared detectors photodiodes, phototransistors etc. work well outside this range, hence not suitable for human detection. A patterned fresnel lens or a mirror is placed in front of the infrared sensor that is sensitive to the radiations emitted by human bodies. The passive infrared sensor works on the principle of pyro-electricity. The principle is based on the fact that certain crystals become electrically charged when their temperature changes. They are essentially capacitors whose dielectric is made from a crystal that has been spontaneously polarized. When the dielectric absorbs infrared radiations, increase in temperature reduces the polarization and the voltage across the sensor changes [10].

As stated before, there are two sensors at every door. The $S_1$ at every door is set up near the outer position of door and the $S_2$ is set up near the inner position of door by keeping small distance between them. When any person enters through the door, $S_1$ gets the signal first and $S_2$ gets the signal after few milliseconds (according to the velocity of person). By comparing the both signals in time delay the $S_1$ decides that any person enters through the door, So $S_1$ value increased by 1 i.e. the response of $S_1$ at any door, $d_{n1} = 1$ (n=1 for door1 or 2 for door2). If another person enters then there is a very small gap between two persons, thus sensors do not get signal in this gap and sensors decide that again another person enters. So $S_1$ value increased by one again i.e. the response of $S_1$ at any door, $d_{i1} = 2$ (i=1 and 2 for door1 and door2 respectively and so on). Now when any person exits, $S_2$ gets the signal first and $S_1$ gets the signal later. By comparing the signals of both sensor, $S_2$ detects that one-person exits i.e. $d_{i2} = -1$ (i=1 for door1 or 2 for door2 and so on).

There is a central sensor at every room. The topology that is used here is star topology. If any sensor gets the signal, it sends to central sensor and it decides by summing the results of every sensor (as stated before), therefore central sensor sends signal to micro-controller, which controls the electric device/devices. If any person stops at door and does not enter, by comparing the signals (with 1st and 2nd sensors) sensors can apprehend the person’s not entering through the door.

According to the Eqn.(1), from all sensors if central sensor gets $\sum_{i=1}^{n} \sum_{j=1}^{2} D(i,j) = 0$, then it decides that, no people is in the room. Thus, it sends signal to micro-controller, and the micro-controller controls the electric devices to switch off.

In addition to that, from all sensors if central sensor gets $\sum_{i=1}^{n} \sum_{j=1}^{2} D(i,j) > 0$ then it decides that, one or more people is in the room. Therefore, the signal is transmitted to micro-controller and devices are switched on by getting this signal.

IV. Cost minimization

A 100-watt bulb when used for 10 hours consumes 1 Kilo Watt/Hour or one unit of electricity (100 watt*10 hours =1000 watt/H =1K Watt/H=1Unit). It is assumed that for domestic consumer, 1 Unit costs 0.05172 $ and for commercial user 1 Unit costs 0.08714 $ including vat. If we properly and economically use our household electrical appliances, we can save our electricity bill by minimum 20%. Again, our household equipment will last more. The load shedding will be minimized and the country as a whole will be benefited.

In our model it is supposed a building that has six floors, every floor has five flats, every flat has three rooms and each room has two electric bulb of each 100 watt/H and one electric fan of 100 watt/H. According to the above measurement it is obtained 270 electric devices at every building each consuming 100 watt/H. Every day (in 24 hours), it is considered that device active time is 20 hours i.e. in 24 hours the devices are used for 20 hours. Therefore, the total
electricity consumption in a day by all devices in a building is 540 K. Watt/H. The electricity consumption is clarified in the Table 1: The electricity bill (US$) measurement is also illustrated in Table 2:

**Table 1. Electricity consumption measurement**

<table>
<thead>
<tr>
<th>Day</th>
<th>Electricity Consumption</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>270*2=540 K. Watt/H</td>
</tr>
<tr>
<td>7</td>
<td>540*7=3780 K. Watt/H</td>
</tr>
<tr>
<td>30</td>
<td>540*30=16200 K. Watt/H</td>
</tr>
<tr>
<td>60</td>
<td>540*60=32400 K. Watt/H</td>
</tr>
<tr>
<td>365</td>
<td>540*365=197100 K. Watt/H</td>
</tr>
</tbody>
</table>

Therefore, the 20% of total consumption in year is 38420 K. Watt/H.

**Table 2. Electricity bill measurement.**

<table>
<thead>
<tr>
<th>Day</th>
<th>Electricity Bill (US$)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>270<em>2=540</em>0.67554=364.791 US$</td>
</tr>
<tr>
<td>7</td>
<td>540<em>7=3780</em>0.67554=2553.54 US$</td>
</tr>
<tr>
<td>30</td>
<td>540<em>30=16200</em>0.67554=10943.75 US$</td>
</tr>
<tr>
<td>60</td>
<td>540<em>60=32400</em>0.67554=21884.26 US$</td>
</tr>
<tr>
<td>365</td>
<td>540<em>365=197100</em>0.67554=133148.94 US$</td>
</tr>
</tbody>
</table>

Therefore, the 20% of total consumption in year is 26629.79 US$.

**V. Simulation Result**

We exploit some simulations to verify our result. In Fig. 4, it is shown electricity consumption, as stated before, in our system it is considered only 3 electric devices, each having power consumption of 100 Watt/H. There are total 270 electric devices in a building, each having power consumption of 100 Watt/H.

There are three curves in Fig. 4 where first one (with blue color) indicates usual electricity consumption without controlling electricity wastage, 2nd curve (with cyan color) points up reduced electricity consumption if wastage is controlled and the 3rd curve (with red color) illustrates total power saving at different duration in a building. From the Fig. 4, it is explicated apparently that electricity consumption is saved by the amount of 108 K. Watt/H, 756 K. Watt/H, 3240 K. Watt/H and 38420 K. Watt/H in a day, a week, one month and one year respectively.

**Fig. 5. Electricity bill of the proposed system.**

Fig. 5 illustrates calculation of electricity bill in US$ at different schemes. The Fig. 5 contains three curves as well, where first one (with blue color) exemplifies usual electricity bill without controlling electricity devices, 2nd curve (with cyan color) indicates reduced
electricity bill if wastage is controlled and the 3rd curve (with red color) illustrates total electricity bill at different duration in a building. From the Fig. 5, it is clear that electricity consumption in a building is saved by the amount of 72.95 US$, 510.708 US$, 2188.4256 US$ and 26625.844 US$ in a day a week, one month and one year respectively.

VI. Conclusion

We have demonstrated an autonomous electric device control system for indoor environment by using PIR sensor. Control algorithm is proposed for controlling the system. We evaluate our simulation result for usual electricity consumption and saving under different configurations, which demonstrates the efficiency of the system. If we properly and economically use our household electrical appliances, we can save our electricity bill minimum 20% by using the proposed system.

References

저자 소개

Mr. Tahidul Islam 이슬람 엠디 타히둘(준회원)
- 2008년 International Islamic University Chittagong (IIUC) 졸업 (학사)
- 2011년 ~ 현재 : 울산대학교 전기공학부 석박사통합과정
  <주관심분야 : 사물간통신, 스마트그리드>

구 인 수 (정회원)
- 1996년 : 건국대학교 전자공학과 졸업 (학사)
- 1998년 : 광주과학기술원 정보통신공학과 졸업(석사)
- 2002년 : 광주과학기술원 정보통신공학과 졸업(박사)
- 2005년 ~ 현재 : 울산대학교 전기공학부 교수
  <주관심분야 : 무선센서네트워크, 무선인지시스템>