

User Selection Algorithms for MU-MIMO Systems with Coordinated Beamforming

Fermín Marcelo Maciel-Barboza, Leonel Soriano-Equigua, Jaime Sánchez-García, Francisco Rubén Castillo-Soria, and Victor Hugo Castillo Topete

In this paper, we propose two novel user selection algorithms for multiuser multiple-input and multiple-output downlink wireless systems, in which both a base station (BS) and mobile stations (MSs) are equipped with multiple antennas. Linear transmit beamforming at the BS and receive combining at the MSs are used to avoid interference between users and find a better sum-rate capacity performance. An optimal technique for selecting users would entail an exhaustive search, which in practice becomes computationally complex for a realistic number of users. Suboptimal algorithms with low complexity are proposed for a coordinated beamforming scheme. Simulation results show that the performance of the proposed algorithms is better than that provided by previous algorithms and is very close to an optimal approach with reduced complexity.

Keywords: User selection, coordinated beamforming, sum-rate capacity.

I. Introduction

Single-user multiple-input and multiple-output communications promise large gains for both channel capacity and reliability, essentially via the use of space-time codes (diversity gain oriented) combined with stream multiplexed transmission (rate maximization oriented) [1]. The situation with multiuser multiple-input and multiple-output (MU-MIMO) techniques is radically different as these techniques imply the use of spatial sharing of the channel by users. The sum-rate capacity in a multiuser broadcast channel is defined to be the maximum aggregation of all user data rates. The optimum transmit strategy for an MU-MIMO downlink involves a theoretical interference precancellation technique, known as dirty paper coding (DPC) [2], combined with an implicit user scheduling and power loading algorithm; DPC achieves the capacity region of MU-MIMO broadcast channels [3].

Since DPC has high implementation complexity, low-complexity linear multiuser methods have been proposed; for example, block diagonalization (BD) [4] and coordinated beamforming (CBF) [5], [6]. A key limitation of these techniques is that, for CBF, the maximum number of users that can be supported cannot exceed the number of transmit antennas; whereas, for BD, the number of transmit antennas must exceed the aggregate number of receive antennas across all users. In the CBF method, the base station (BS) sends a single data stream per user and removes the restriction on the number of receive antennas, existing in the BD scheme. CBF

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performs a joint optimization of beamforming and combining weight vectors to completely remove the interference between users, assuming full channel state information (CSI) at the BS. CSI can be obtained in time division duplex (TDD) systems if the BS estimates forward channels from the reverse ones through channel sounding and reciprocity [7].

Broadly speaking, when the total number of users in an MU-MIMO system is larger than the maximum number of supportable users, a BS is required to select a set of users to maximize the data rate. An optimal selection of users can be achieved via a brute force approach; however, this inevitably carries with it a heavy computational burden. To solve this problem, several user selection algorithms with different cost metrics have been proposed, obtaining a trade-off between complexity and performance [8]–[16]. In [8], the authors proposed an algorithm that builds a set of semi-orthogonal users, semi-orthogonal user selection, for terminals with a single antenna. In [9], two suboptimal algorithms for BD are proposed — c -algorithm and n -algorithm. In each step of the c -algorithm, it is the user that maximizes the sum rate who is selected; whereas, n -algorithm selects the user that maximizes the channel Frobenius norm.

Jin and others [10] proposed a volume-based user selection (VUS) algorithm that maximizes the product of diagonal elements of the upper triangular matrix \mathbf{R} after performing QR factorization. A similar approach was presented in [11]. The difference between these last two approaches lies in the fact that the latter is based on a determinant of a matrix composed of users' channel matrices, so that the orthogonality as well as the channel quality of the selected users is measured. Furthermore, the authors in [12] demonstrated that the maximum energy efficiency and the corresponding sum capacity upper bound are both increasing functions of λ , where

$\lambda = \det(\mathbf{H}\mathbf{H}^H)$ can be viewed as the volume of the channel matrix \mathbf{H} . In [13] and [14], the authors proposed the chordal distance as a measure of orthogonality between channel spaces for user selection; they managed to obtain a performance comparable to that of [11] and a further reduction in complexity. Recently, Gupta and Chaturvedi [15] used the total conditional differential entropy as a measure to select users iteratively, which can be seen as an extension of [11]. The authors in [15] showed that the average sum-rate capacity of their conditional entropy algorithm is strictly better than those of the n -algorithm, volume-algorithm, and chordal-algorithm; even though the sum-rate plots of the c -algorithm and conditional entropy-based algorithm overlap, the flop count of the latter algorithm is significantly lower. None of the proposed algorithms have been developed for the particular case of serving the same number of users as transmit antennas (which have an indistinct

number of receive antennas, as in the case of the CBF scheme).

Our goal is to find low-complexity user selection techniques that come close to attaining the maximum possible sum-rate for the practical case wherein the number of downlink users is the same as the number of transmit antennas at the BS and multiple antennas at the user side. We propose two low-complexity user selection algorithms for CBF systems. The proposed algorithms perform close to an optimal exhaustive search and outperform previous algorithms while maintaining low complexity.

Throughout this paper, uppercase and lowercase boldface letters are used to denote matrices and vectors, respectively. We use $(\cdot)^T$, $(\cdot)^H$, $\|(\cdot)\|$, $\|(\cdot)\|_F$, and $(\cdot)^\dagger$ to indicate the transpose, conjugate transpose, 2-norm, Frobenius-norm and pseudoinverse of (\cdot) , respectively, where (\cdot) can be a matrix or a vector. The l th column vector of \mathbf{A} is represented by $\mathbf{A}(:, l)$. The number of elements of set $\{\cdot\}$ is denoted by $\text{card}(\{\cdot\})$. The ceiling and expectation operations are denoted by $\lceil \cdot \rceil$ and $\mathbb{E}\{\cdot\}$, respectively.

II. System Model and Background

Consider an MU-MIMO downlink system with N_t transmit antennas at the BS and K users that are equipped with N_r receive antennas. We assume highly loaded scenarios (that is, $K \gg N_t$) in which the BS cannot serve all users simultaneously, because of the fact that serving more than N_t users will result in a decreased capacity. Therefore, the system requires user selection to simultaneously attend to a subset of users.

Consider a subset of users, I , which has been scheduled for transmission, where $\text{card}(I) = K_s$ is the total number of selected users to be served simultaneously. Let x_k be the transmit signal of user k ($k \in I$). Each selected user will obtain a single string of data, and a signal, y_k , after applying a combiner vector, \mathbf{w}_k , to user k will be given by

$$y_k = \mathbf{w}_k^H \mathbf{H}_k \mathbf{f}_k x_k + \mathbf{w}_k^H \mathbf{H}_k \sum_{l \in I, l \neq k} \mathbf{f}_l x_l + \mathbf{w}_k^H \mathbf{n}_k, \quad (1)$$

where the first term on the right-hand side of (1) is the desired signal for user k ; the second term is the interference from other users signals, and \mathbf{n}_k is a Gaussian noise vector with zero mean and variance σ_n^2 . The beamforming weight vector is represented by \mathbf{f}_k . The channel between the transmitter and the k th user is represented by the matrix $\mathbf{H}_k \in \mathbb{C}^{N_r \times N_t}$ with independent and identically distributed (i.i.d.) complex Gaussian entries.

1. CBF

In CBF [5], [6], the transmitter chooses \mathbf{f}_k such that the subspace spanned by its columns is in the null space of

$\mathbf{w}_l^H \mathbf{H}_l (\forall l \neq k)$; that is, $\mathbf{w}_l^H \mathbf{H}_l \mathbf{f}_k = 0$ for $l=1, \dots, k-1, k+1, \dots, K$ subject to $\|\mathbf{w}_k\|^2 = 1 (\forall k)$. Therefore, \mathbf{f}_k causes zero interference with the l th user. After removing the interference term in (1), the received signal is represented by

$$y_k = \mathbf{w}_k^H \mathbf{H}_k \mathbf{f}_k x_k + \mathbf{w}_k^H \mathbf{n}_k. \quad (2)$$

At the receiver side, using the technique of maximal-ratio combining (MRC), which means that $\mathbf{w}_k = \mathbf{H}_k \mathbf{f}_k / \|\mathbf{H}_k \mathbf{f}_k\|$, is a reasonable choice for reaching transmission rates close to interference-free capacity.

To compute beamforming vector \mathbf{f}_k , the BS first initializes a combining vector equal to the right singular vector corresponding to the maximum singular value. Let the singular value decomposition (SVD) of \mathbf{H}_k be $\mathbf{H}_k = \mathbf{U}_k \mathbf{\Sigma}_k \mathbf{V}_k^H$, then the combining vector is given for $\mathbf{w}_k(0) = \mathbf{U}_k(:, 1)$. Notation (i) is used for specifying the i th iteration; thus, $\mathbf{w}_k(0)$ is the initial combining vector. Then, the transmitter calculates the beamforming vector as

$$\mathbf{f}_k(i) = \frac{\mathbf{q}_k}{\|\mathbf{q}_k\|} \quad (\forall k), \quad (3)$$

where

$$[\mathbf{q}_1, \dots, \mathbf{q}_K] = \begin{bmatrix} \mathbf{w}_1^H \mathbf{H}_1 \\ \vdots \\ \mathbf{w}_K^H \mathbf{H}_K \end{bmatrix}^\dagger. \quad (4)$$

For iterations $i \geq 2$, if the difference $\|\mathbf{f}_k(i) - \mathbf{f}_k(i-1)\|$ is smaller than a predefined constant, ε , then the algorithm provides the results; otherwise, it moves to the next iteration, $i + 1$, where the combining vector is recalculated by MRC prior to going back to (3). The convergence of the iterative algorithm is not guaranteed, but the method converges in almost all test cases [5]. For this reason, a maximum number of iterations are used; for example, $i_{\max} = 50$ for the case of $N_r = N_t = K_S = 4$. The signal-to-interference-plus-noise ratio (SINR) of user k can be expressed as

$$\text{SINR}_k = \frac{P_k \left| \mathbf{w}_k^H \mathbf{H}_k \mathbf{f}_k \right|^2}{\sigma_n^2}, \quad (5)$$

where P_k represents the transmit power allocated to the k th user. The CBF scheme achieves the following sum-rate capacity:

$$C = E \left\{ \sum_k \log_2 (1 + \text{SINR}_k) \right\}. \quad (6)$$

2. User Preselecting Stage (UPS)

To reduce the complexity of the user selection algorithm, in [16], the authors introduced a metric to evaluate the correlation

among two MIMO channels, \mathbf{H}_i and \mathbf{H}_j . They used the square of the Frobenius norm of the average cross-correlation matrix as an estimate, as follows:

$$\xi_{i,j} = \frac{\|\tilde{\mathbf{H}}_i \mathbf{H}_i \mathbf{H}_j^H \tilde{\mathbf{H}}_j\|_F^2}{(N_{r,i} N_{r,j})}, \quad (7)$$

where $\tilde{\mathbf{H}}$ is the reciprocal of the Euclidean norm of the row vector of matrix $\mathbf{H} \in \mathbb{C}^{N_r \times N_t}$ whose diagonal elements are given by

$$\tilde{\mathbf{H}} = \text{diag} \left\{ \left\| [\mathbf{H}]_1 \right\|^{-1}, \dots, \left\| [\mathbf{H}]_{N_r} \right\|^{-1} \right\}. \quad (8)$$

With the UPS, a large fraction of users can be dropped off at intermediate iterations, which results in reduced processing time when user selection algorithms are applied.

III. Proposed User Selection Algorithms

In this section, we present two novel low-complexity user selection schemes for MU-MIMO downlink channels based on the CBF method mentioned in Section II-1.

Let \mathcal{Q} be the set of users to be served in the system, Γ the set of selected users for simultaneous transmission (whose $\text{card}(\Gamma) = N_t$), and i the i th iteration.

1. Coordinated Effective Channel Gain-Based User Selection (CECUS)

The basic idea of the CECUS algorithm is to greedily maximize the sum of the coordinated effective channel gain corresponding to the selected user subset; however, instead of using the CBF method for computing the weight vectors (which is iterative and does not converge in some cases), we propose to calculate the beamforming and combining weight vectors in a single step within the user selection process. The detailed user selection process is provided below.

- 1) Initialization: let $i = 1$, $\mathcal{Q}_i = \{1, 2, \dots, K\}$, $\Gamma = \emptyset^{N_t \times 1}$ and compute $\pi_k = \|\mathbf{H}_k\|_F^2, \forall k \in \mathcal{Q}_i$.
- 2) Select the first user u_1 with the highest power gain as $u_1 = \arg \max_{k \in \mathcal{Q}_i} \pi_k$ and update $i = i + 1$, $\mathcal{Q}_i = \mathcal{Q}_{i-1} - \{u_{i-1}\}$, $\Gamma = \Gamma + \{u_{i-1}\}$.
- 3) Implement the UPS and obtain the new set $\mathcal{Q} = \{k \in \mathcal{Q}_i \mid \xi_{u_{i-1}, k} < \alpha\}$.
- 4) For $k \in \mathcal{Q}$,
 - i) Let \mathcal{P} be a new provisional set of users $\mathcal{P} = \Gamma + k$, where $\text{card}(\mathcal{P}) = L$.
 - ii) Find the combiner $\mathbf{w}_l = \mathbf{U}_l(:, 1), \forall l \in \mathcal{P}$, and obtain

$[\mathbf{q}_1, \dots, \mathbf{q}_L] = \left[\left[(\mathbf{w}_1^H \mathbf{H}_1)^T, \dots, (\mathbf{w}_L^H \mathbf{H}_L)^T \right]^T \right]^\dagger$. Then,

the normalized beamforming vector is given by $\mathbf{f}_i = \mathbf{q}_i / \|\mathbf{q}_i\|$. Compute the sum of the effective channel gain

$$\text{Eff}_k = \sum_{u \in \Gamma} \left| \mathbf{w}_u^H \mathbf{H}_u \mathbf{f}_u \right|^2 + \left| \mathbf{w}_k^H \mathbf{H}_k \mathbf{f}_k \right|^2.$$

- iii) Select $u_i = \arg \max_{k \in \Omega} \text{Eff}_k$ and update $i = i + 1$, $\Omega_i = \Omega_{i-1} - \{u_{i-1}\}$, $\Gamma = \Gamma + \{u_{i-1}\}$; if $\text{card}(\Gamma) < N_b$ then go to step 3.

- 5) Finish the process of user selection and perform the CBF algorithm described in Section II-2 on the selected user set Γ .

Our first proposal is inspired by the capacity-based suboptimal user selection presented in [9], which was specially designed for BD as a precoding method. The first contrast with our algorithm is found in step 1, where instead of choosing the first user with the highest individual throughput, the first user is selected to maximize the overall energy of the channel; that is, the sum of the eigenvalues of $\mathbf{H}\mathbf{H}^H$ equals $\|\mathbf{H}\|_F^2$.

The second difference is in step 3, where we apply the UPS mentioned in Section II. In this step, we propose to use a threshold value (a positive small number), α , so that Ω_i is nonempty, and $\text{card}(\Gamma)$, the number of selected users, satisfies $\text{card}(\Gamma) = N_b$. It should be taken into consideration that if α is too small, then the multiuser diversity gain decreases; on the other hand, if α is too large, then there is an increase in the complexity. More details are shown in Section V.

It is necessary to observe a change in the dimension of channel matrix \mathbf{H} by using combiners $((\mathbf{w}^H \mathbf{H}) \in \mathbb{C}^{1 \times N_i})$, so they can calculate beamforming vectors using the pseudoinverse, as in the case of [8], for systems with a single antenna; moreover, the combiner vectors need to be calculated only once for the users that are in Ω_i .

2. Frobenius-Norm Grouping-Based User Selection (FGUS)

In this section, to further reduce the complexity of the CECUS algorithm, we propose the FGUS algorithm. In the FGUS algorithm, users are sorted according to the energy of the channel, then rearranged to form a matrix χ containing a user index. The main difference between the algorithms is that instead of performing an iterative search among all remaining users, the searching process only involves users belonging to the i th column of χ , thereby reducing the complexity of the algorithm described in Section III-1. Our algorithm is summarized by the following steps:

- 1) Initialization: let $i = 1$, $\Omega_i = \{1, 2, \dots, K\}$, $\Gamma = \emptyset^{N_i \times 1}$ and compute $\pi_k = \|\mathbf{H}_k\|_F^2, \forall k \in \Omega_i$; sort π_k in descending

order and store the index corresponding to each user in γ . Let $\chi = \text{redim}(\gamma, \lceil K/N_i \rceil, N_i)$, where $\text{redim}(A, b, c)$ returns a matrix of size $b \times c$ rearranging the vector A .

- 2) Select the first user u_1 with the highest power gain as $u_1 = \chi(1, 1)$ and update $i = i + 1$, $\Gamma = \Gamma + \{u_{i-1}\}$.
- 3) For all $k \in \chi(:, i)$,
- i) let a new set of users, $\Psi = \Gamma + \chi(k, i)$.
 - ii) for all $l \in \Psi$, find the combiner $\mathbf{w}_l = \mathbf{U}_l(:, 1)$ and obtain $[(\mathbf{q}_1), \dots, (\mathbf{q}_L)]$; then, the normalized beamforming vector is $\mathbf{f}_i = \mathbf{q}_i / \|\mathbf{q}_i\|$, where $L = \text{card}(\Psi)$.
 - iii) Compute Eff_k just as in the previous algorithm.
- 4) Select the index of user $u_i = \arg \max_{k \in \chi(:, i)} \text{Eff}_k$ and update $i = i + 1$, $\Gamma = \Gamma + \{u_{i-1}\}$; if $\text{card}(\Gamma) = N_b$ then go to step 3; otherwise, terminate and go to step 5.
- 5) Repeat step 5 of the algorithm of Section III-1.

In step 1, the algorithm computes the Frobenius-norm for K users in the cell; users are then sorted in descending order according to the channel energy. The algorithm then divides users into N_i groups. In step 2, the algorithm selects the user with the highest channel energy. In the algorithm presented in this section, the preselection is deleted, because the number of users in each iteration is $\lceil K/N_i \rceil$, thus avoiding the extensive work to find appropriate values of α . In step 3, the algorithm takes the already selected users and users in the i th group to form a new user set, then computes the effective channel gain of the new set. In step 4, the user that maximizes the effective channel gain in the i th group is selected. Steps 3 and 4 are repeated until the selected users are equal to N_b . Finally, in step 5, the algorithm updates the beamforming and combiner vectors using the CBF algorithm described in Section II-2.

IV. Complexity Analysis

For a complex-valued matrix $\mathbf{H} \in \mathbb{C}^{N \times M}$, and vectors $\mathbf{w} \in \mathbb{C}^{N \times 1}$ and $\mathbf{f} \in \mathbb{C}^{M \times 1}$, we evaluate the user selection algorithms quantitatively. The complexity is measured by the number of real floating-point operations, known as flops [17] and denoted by F . Matrix-vector multiplication takes the form $F_{\mathbf{H}\mathbf{f}} = 2NM$. The sesquilinear form of $\mathbf{w}^H \mathbf{H} \mathbf{f}$ is $F_{\mathbf{w}^H \mathbf{H} \mathbf{f}} = 2NM + N - 1$. Each multiplication of non-square matrices $\mathbf{A} \in \mathbb{C}^{N \times M}$ and $\mathbf{B} \in \mathbb{C}^{M \times P}$ has $F_{\mathbf{A}\mathbf{B}} = 2NMP$ flops. The SVD complexity of a complete matrix is $F_{\text{svd}(\mathbf{H})} = 4NM^2 + 8N^2M + 9N^3$, which is between four- and six-times higher than that of a real matrix [18]. A computationally simple and

Table 1. Complexity analysis of matrix operations.

Matrix operations	Flop count approximate
Frobenius norm ($\ \mathbf{H}\ _F^2$)	$4MN$
Pseudoinverse, SVD	$24NM^2 + 48N^2M + 54N^3$
Multiplication by a vector	$2MN$
Multiplication	$2MNP$
Sesquilinear form	$2NM + 2N - 1$

accurate way to calculate the pseudoinverse is by using the SVD; the computational cost for the pseudoinverse is dominated by the cost of the SVD, which is several times higher than that of matrix-matrix multiplication. Table 1 summarizes the flop counts of the various aforementioned matrix operations.

1. Algorithm 1: CECUS

The complexity of the proposed algorithms is divided into three parts — F_a corresponding to the first user selection, F_b to the user selection, and F_c to the extra $\xi_{i,j}$ calculations needed for implementing the UPS strategy. For the CECUS algorithm, we first compute the square Frobenius norm of K users, assuming that after the preselection stage, we have $\text{card}(\Omega) = \beta_i K$ users, where $1 > \beta_1 > \dots > \beta_{K_s} > 0$.

$$F_{\text{Alg1}} = F_a + F_b + F_c,$$

where

$$F_a = 4KN_r N_t,$$

$$F_b = \sum_{i=2}^{K_s} \left\{ (\beta_i K - i + 1) \times (24(i)^2 N_t + 48(i)^2 N_t + 54(i)^3 + \dots + 2N_r N_t + N_r - 1) \right\} + (\beta_1 K + 1) \times (24N_r N_t + 48N_r^2 N_t + \dots + 54N_r^3 + 2N_r N_t),$$

$$F_c = \sum_{i=2}^{K_s} (\beta_{i-1} K - i - 1) \times (8N_r^2 N_t + 8N_r N_t - 2N_r N_t^2).$$

2. Algorithm 2: Frobenius-Norm Grouping-Based User Selection

In the FGUS algorithm, we propose a subgrouping of users to further reduce the complexity of the user selection algorithm. In the CECUS algorithm, F_a is the same as in the FGUS algorithm; nonetheless, in F_b , K is replaced by $\hat{K} = \lceil K/N_t \rceil$ and F_c is not considered in the last algorithm as the UPS is not

applied; thus, we have $\beta_i = 1, \forall i$, and $F_c = 0$.

$$F_{\text{Alg2}} = F_a + F_b,$$

where

$$F_b = \sum_{i=2}^{K_s} \left\{ (\hat{K} - i + 1) \times (24(i)^2 N_t + 48(i)N_t^2 + 54(i)^3 + 2N_r N_t + N_r - 1) \right\} + (K - \hat{K} + 1) \times (24N_r^2 N_t + 48N_r N_t^2 + 54N_r^3 + 2N_r N_t).$$

For completeness of the achievable results, in this section, we present the total flop count of low-complexity algorithms proposed in the literature; that is, for VUS [11], chordal distance-based user selection (ChUS) [14], and conditional entropy-based user selection (CEUS) [15]. The complexity of the volume-based algorithm is as follows:

$$F_{\text{VUS}} \approx \sum_{i=2}^{K_s} \left\{ \left(8N_t^2 N_r + 8N_t N_r^2 + \frac{4}{3} N_r^3 - \frac{3}{2} N_r^2 + \frac{13}{6} N_r \right) \times (K - i + 1) \right\} + \left(8N_t N_r^2 + \frac{4}{3} N_r^3 - \frac{3}{2} N_r^2 + \frac{19}{6} N_r \right) \times K. \quad (9)$$

The complexity of the ChUS algorithm is expressed as

$$F_{\text{ChUS}} \approx \sum_{i=2}^{K_s} \left\{ \left[8(i-1)^2 N_r^2 N_t - 2(i-1)N_r N_t + 7(i-1)N_r N_t^2 \right] + \left[8N_r^2 N_t - 2N_r N_t + 7N_r N_t^2 + 4N_t^2 \right] \times (K - i + 1) \right\} + 4KN_r N_t. \quad (10)$$

The total flop count of the CEUS algorithm is

$$F_{\text{CEUS}} \approx \sum_{i=1}^{K_s} \left\{ F_{\Omega} \times (i-1) + \left[\frac{4}{3} N_r^3 - \frac{3}{2} N_r^2 + \frac{19}{6} N_r + 8N_t^2 N_r + 8N_t N_r^2 \right] \times i \right\} \times (K - i + 1) + K \times F_{\Omega}, \quad (11)$$

where F_{Ω} is defined in [15] as

$$F_{\Omega} = 32N_t^2 N_r + 16N_t N_r^2 + 2N_t^2 + N_r + 4N_r^3 - \frac{1}{2} N_r^2 - \frac{3}{2} N_r. \quad (12)$$

V. Simulation Results

In this section, we show simulation results to compare the performance of the proposed algorithms. In our simulations we take into account the following assumptions: (i) channels between users and between each pair of antennas are

considered independent; (ii) unitary total power and uniform distribution of power between users; (iii) perfect channel estimation at the receiver; and (iv) complete knowledge of user channels in the BS. Unlike the algorithm proposed in [19] for frequency division duplex systems, our proposal is designed for TDD systems that employ reciprocity to estimate forward channels from reverse channels. We compare the performance of the following algorithms:

- Optimal user selection by complete search (optimal-cbf)
- CECUS and FGUS algorithms, described in Section III
- Volume-based user selection (VUS) [11]
- Chordal distance-based user selection (ChUS) [14]
- Conditional entropy-based user selection (CEUS) [15]
- Round-robin algorithm for N_t simultaneous users (RUS, random user selection).

Figure 1 shows the results of the sum-rate capacity against the values of alpha (α) for $N_t = 4$, $N_r = 4$, SNR = 20 dB and the total number of users, K , in the range of 8 to 100. We observe that if α is too small, then the sum-rate decreases due to the loss in the diversity gain. In terms of sum-rate, the optimal value of α for $K \geq 40$ is $\alpha > 0.26$. However, remember that the higher the value of α , the higher the complexity in the user selection algorithm.

Figure 2 shows the results of the sum-rate capacity against the number of users when the number of transmit antennas is four and the number of receive antennas for each user terminal is four. The SNR is 20 dB and $K_S = 4$. It is shown that the sum-rate of the CECUS (*Alg1* for disambiguation) algorithm proposed in this paper is better than the CEUS, ChUS, and VUS algorithms. The FGUS algorithm (*Alg2* for disambiguation) has a lower performance than *Alg1*, but as the number of user's increases, *Alg2* approaches the CEUS algorithm. Unless otherwise stated, in the simulations of *Alg1*, $\beta_i = 1, \forall i$. In the case of *Alg1* with UPS, different α -values are taken for different numbers of users; in Fig. 2, we have $\alpha = \{0.35, 0.32, 0.31, 0.30, 0.29, 0.285, 0.28, 0.27\}$ for $K = \{8, 12, 16, 20, 40, 80, 100\}$. It is of interest to consider solutions to optimize the values of alpha. We defer this, however, to future work.

Figure 3 shows the results of the sum-rate capacity against the number of users when the number of transmit antennas is eight and the number of receive antennas for each user terminal is four. The SNR is 20 dB, $K_S = 8$, and we have $\alpha = \{0.18, 0.175, 0.17, 0.165, 0.16, 0.155, 0.15, 0.145\}$ for $K = \{16, 24, 32, 40, 60, 80, 104, 128, 160\}$. It can be seen, again, that *Alg1* outperforms CEUS, ChUS, and VUS. As the number of users increases, *Alg2* outperforms the VUS algorithm and its performance approaches that of the CEUS algorithm.

Figure 4 compares the number of flops of various low-

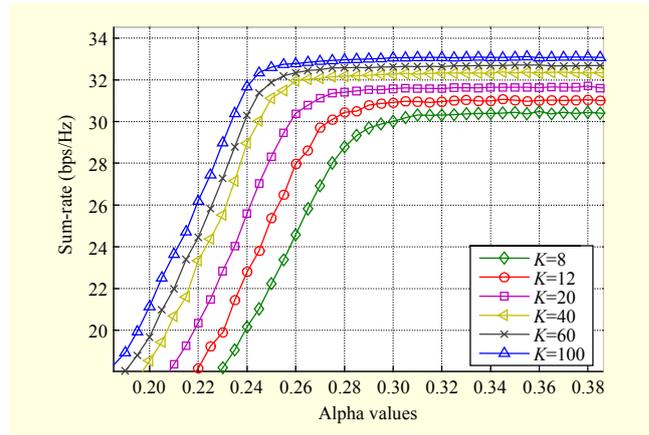


Fig. 1. Sum-rate vs. alpha values (α) when $N_t = 4$, $N_r = 4$.

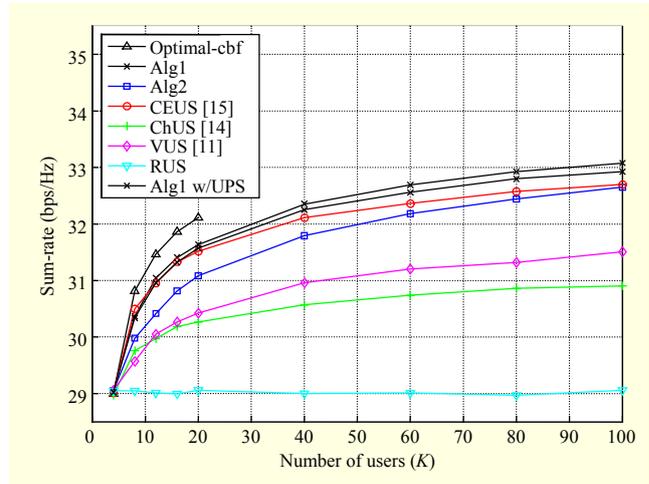


Fig. 2. Sum-rate vs. number of users when $N_t = 4$, $N_r = 4$.

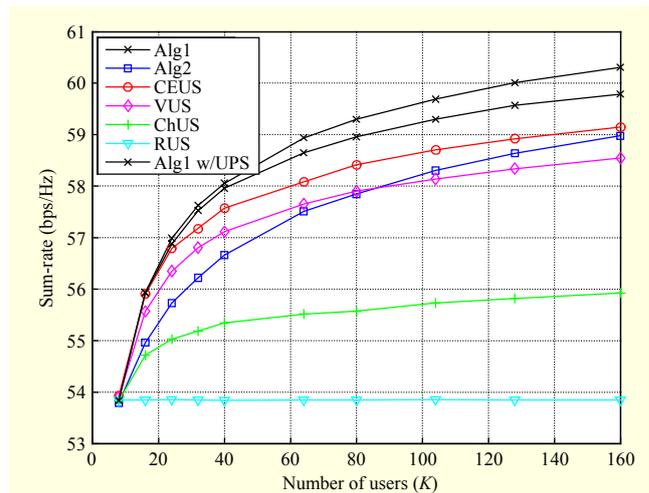


Fig. 3. Sum-rate vs. number of users when $N_t = 4$, $N_r = 8$.

complexity user selection algorithms for $N_t = 4$, $N_r = 4$. It is observed that both the ChUS and the VUS require fewer flops

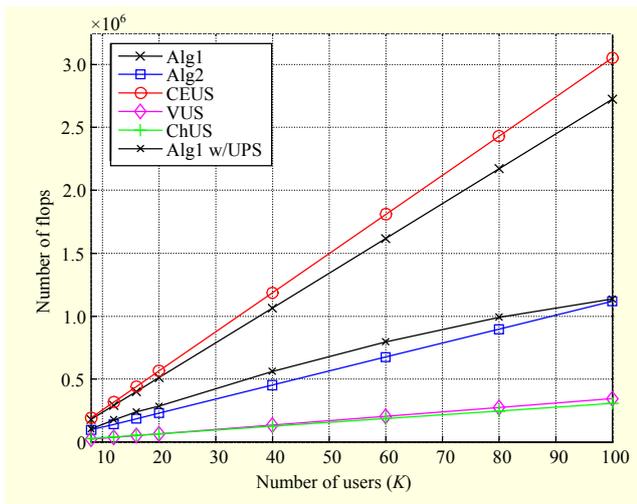


Fig. 4. Number of flops vs. number of users when $N_t = 4$, $N_r = 4$.

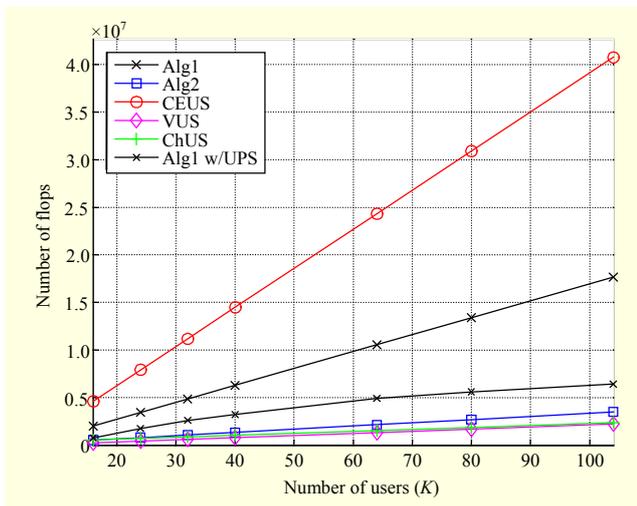


Fig. 5. Number of flops vs. number of users when $N_t = 4$, $N_r = 8$.

among the low-complexity scheduling algorithms; however, recall from Fig. 2 that they present poor performance in terms of sum-rate. Our proposed Alg1 and Alg2 require fewer flops than the CEUS algorithm. An interesting result is observed by Alg1 with UPS, where the number of flops approaches Alg2. This is because when increasing the number of users, the optimal value of α decreases (as seen from Fig. 1); thus, in this way, the complexity is decreased yet the algorithm still provides a good sum-rate performance.

Figure 5 shows the number of flops of the scheduling algorithms with respect to the total number of users in a system with eight transmit antennas and four receive antennas. It is observed that when $N_t > N_r$, the proposed algorithms achieve a better trade-off between complexity and performance. It appears that the proposed Alg2 (FGUS) is a good option when the system has a large number of users and a strategy of low

complexity is sought for practical implementation of next-generation wireless systems such as 3GPP LTE Advanced.

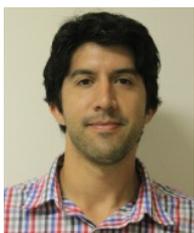
VI. Conclusion

In this paper, two suboptimal user selection algorithms for MU-MIMO systems based on a coordinated beamforming criterion were proposed. The core idea behind the proposed algorithms is to maximize the sum of the coordinated effective channel gain of a set of selected users. Simulation results show that the behavior of the proposed algorithms for a reasonable number of users (< 200) is comparable to the performance obtained by a full search, and the sum-rate capacity is better than that provided by previous algorithms proposed in the literature; moreover, our proposal has some advantages — maintaining low complexity (it is also proved that a trade-off between low complexity and high sum-rate upon applying the UPS step can be found), no restrictions for selecting the number of receiving antennas, and the ability to cater to a number of users equal to the number of transmit antennas.

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