

# Auditory Model Design for Objective Audio Quality Measurement

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**Abstract :** Objective quality measurement schemes that incorporate properties of the human auditory system. The basilar membrane(BM) acts as a spectrum analyzer, spatially decomposing the signal into frequency components. Each filterbank is an implementation of the ERB, gam-machirp function. This filterbank is level-dependent asymmetric compensation filters. And for the validation of the auditory model, we calculate the CPD. Quality measurement is obtained from the result.

## 1. Introduction

Various audio encoding methods remove both redundancy and perceptual irrelevance using the properties of the human auditory system, so that the bit rate required to encode the signal is reduced significantly. Therefore, a simple signal to noise ratio (SNR) measurement is not at all sufficient to assess the audio quality. For this reason, the subjective quality of audio material is measured by mean of subjective tests where a panel of listeners is asked to judge the degree of degradation of processed audio sequences compared to an unprocessed reference signal[1].

Since formal subjective tests are often expensive or impractical, an objective measurement method is needed that will model the sensory and cognitive processes underlying subjective ratings[2]. Objective quality measurement schemes that incorporate properties of the human auditory system. The representation of the human auditory system within the measuring device is more accurate than that within the codec itself. A perceptual model aims to simulate human perception[3]. The task of the perceptual model within any audio assessment algorithm is to simulate the human auditory system.

## 2. THE HUMAN AUDITORY SYSTEM

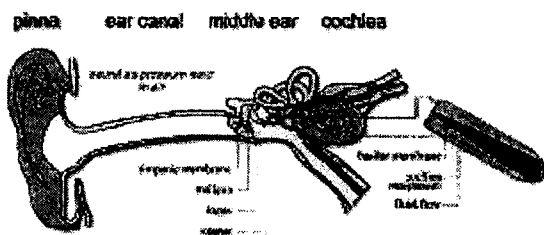


Figure 1. The main components of the human auditory system.

Incoming sounds are funneled into the ear canal by the pinna (also referred to as the concha). This is the flap of cartilage and skin found on each side of the head, which is

the only external part of the ear. The frequency responses of the sound reaching the ear canal (via the pinna), from sources at various angles around a listener are called Head Related Transfer Functions (HRTFs)[4].

Ear Canal is the resonant cavity between the outer and middle ear. It has a resonance at around 3-5 kHz; hence it attenuates higher and lower frequencies. This response contributes to our increased sensitivity to mid-frequency sounds.

The middle ear consists of the tympanic membrane (ear drum), malleus (hammer) and stapes(stirrup). This transmits the sound pressure wave from the ear canal into the cochlea. These three ossicles bones act as a leverage system, converting the weak, high-amplitude oscillatory movement of the eardrum into a stronger, lower-amplitude force at the cochlea. This is transmitted into the cochlea by the pistonic action of the stapes against the oval window.

The fluid-filled cochlea is a coil within the ear, partially protected by bone. The sea water-like fluid vibrates with the incoming sound wave. The cochlea is semi-partitioned along its length by a thin flap called the basilar membrane.

The basilar membrane (BM) vibrates with the incoming sound, and acts as a spectrum analyzer, spatially decomposing the signal into frequency components. The movement of the BM is in the form of a traveling wave. The wave front travels from the oval window, down the BM towards the apex. The amplitude envelope of this traveling wave varies along the BM. The stiffness of the BM decreases along its length. The resonant frequency of a point on the BM varies with stiffness, thus sounds of different frequencies cause different parts of the BM to vibrate.

The inner hair cells on the BM fire when the BM moves upwards, so transducing the sound wave at each point into a signal on the auditory nerve. The signal is effectively half wave rectified. Each cell needs a certain time to recover between firings, so the average response during a steady tone is lower than at its onset. Thus, the inner hair cells act as an automatic gain control. The firing of any individual cell is pseudo-random, modulated by the movement of the BM. However, in combination, signals from large groups of cells can give an accurate indication as to the motion of the BM.

At lower frequencies the firing of the inner hair cells may phase lock to the incoming signal, and the phase of the signal is preserved and transmitted along the auditory nerve. However, above approximately 1.5 kHz; the hair cells do not lock onto individual cycles, and only the amplitude envelope is transmitted. So in particular phase differences, may be discarded without affecting what is heard.

There are approximately 12000 outer hair cells distributed along the length of the BM. They react to feedback from the brainstem, altering their length to change the resonant properties of the BM. This causes the frequency response of the BM to be amplitude dependent.

### 3. GAMMACHIRP FILTER

The complex impulse response of the gammachirp is

$$g_c(t) = at^{n-1} \exp(-2\pi b ERB(f_r)t) \exp(j2\pi f_r t + jc \ln t + j\phi) \quad (1)$$

where time  $t > 0$

$a$  : amplitude

$n$  and  $b$  : parameters defining the envelope of the gamma distribution

$f_r$  : the asymptotic frequency

$c$  : a parameter for the frequency modulation or the chirp rate

$\phi$  : the initial phase

$\ln t$  : a natural logarithm of time

$ERB(f_r)$  : equivalent rectangular bandwidth of an auditory filter at  $f_r$

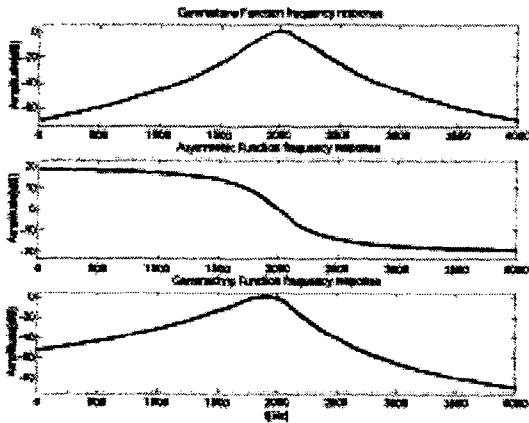


Figure 2. The frequency response of the gammatone, asymmetric function, and gammachirp.

The Fourier transform of the gammachirp is

$$G_c(f) = \frac{a\Gamma(n+jc)e^{j\theta}}{2\pi b ERB(f_r) - j2\pi(f-f_r)^{n+jc}} = \bar{a} \left[ \frac{1}{\{2\pi\sqrt{b^2 + (f-f_r)^2}\}^n} e^{-jn\theta} \right] \cdot \left[ e^{c\theta} \cdot e^{-jc \ln(2\pi\sqrt{b^2 + (f-f_r)^2})} \right] \quad (2)$$

$$\theta = \arctan \frac{f-f_r}{b}$$

$$\bar{a} = a\Gamma(n+jc)e^{j\theta} \text{ and } \bar{b} = bERB(f_r)$$

The first term  $\bar{a}$  is a constant. The second term is known as the Fourier spectrum of the gammatone,  $G_T(f)$ . The third term represents an asymmetric function,  $H_A(f)$ .

When the amplitude is normalized ( $\bar{a} = 1$ ), the frequency response of the gammachirp is

$$G_c(f; n, b, c, f_c) = G_T(f; n, b, f_r) \cdot H_A(f; b, c, f_r) \quad (3)$$

A gammachirp filter can be implemented by cascading a gammatone filter and an asymmetric filter[5], [6].

### 4. AUDITORY MODEL

The model is designed to simulate monaural listening under free field conditions.

#### 4.1 Outer-Middle Ear Filtering

Above  $1 \cdot \phi$  the magnitude response of the outer-middle ear filter is similar to the inverted absolute threshold curve. This is based on the assumption that the inner ear is equally sensitive to all frequencies above  $1 \cdot \phi$ . The absolute threshold curve is probably influenced by the low frequency internal noise of the inner ear and therefore does not reflect the transmission through the outer and middle ear below  $1 \cdot \phi$ . This is reflected shape of an equal-loudness contour at a high loudness level.

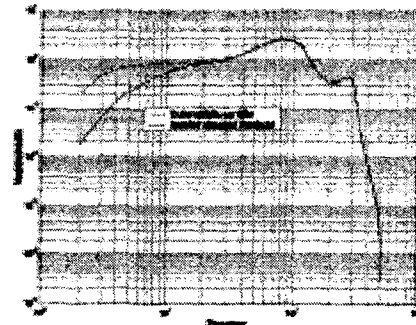


Figure 3. Difference between the outer-middle ear filter and the inverted absolute threshold.

The transfer function of the outer-middle ear filter consists of a cascade of a recursive lowpass filter of order 8 and a parameterized recursive highpass filter of order 2.

$$H_{OM}(z) = H_{LP}(z) * H_{HP}(z) \quad (4)$$

$$H_{LP}(z) = \frac{0.109z^7(z+1)}{z^8 + a_1z^7 + a_2z^6 + a_3z^5 + a_4z^4 + a_5z^3 + a_6z^2 + a_7z^1 + a_8} \quad (5)$$

$$\begin{pmatrix} a_1 = 2.5359, a_2 = 3.9295, a_3 = 4.7532, a_4 = 4.7251 \\ a_5 = 3.5548, a_6 = 2.1396, a_7 = 0.9879, a_8 = 0.2836 \end{pmatrix}$$

$$H_{HP}(z) = \frac{z^2 - 2z + 1}{z^2 - 2Rz + R^2} \quad (6)$$

We are using an outer-middle ear filter with  $R = 0.989$  and we assume the inverted absolute threshold contour with  $R = 0.957$  at the moment. The random firing of the inner hair cells, combined with the blood flow within the ear, gives rise to an internal noise that limits our absolute hearing threshold[7].

### 4.2 Basilar Membrane Filtering

The topic of basilar membrane (BM) filterbanks are non-uniform bandwidth bandpass filterbanks designed to imitate the frequency resolution of human hearing. Classical BM filterbanks include constant-Q filterbanks such as the widely used third-octave filterbank. More recently, constant-Q filterbanks for audio have been devised based on the wavelet transform, including the auditory wavelet filter bank. BM filterbanks have also been based more directly on psychoacoustical measurements, leading to approximations of the auditory filter frequency response in terms of a gaussian function, a "rounded exponential", and more recently the gammatone filterbank. The gammachirp filterbank further adds a level-dependent asymmetric correction to the basic gammatone channel frequency response, thereby providing a more accurate approximation to the auditory frequency response.

Moore and Glasberg suggested that the excitation pattern of a given sound could be thought of as the output of the BM filter as a function of their center frequency. The BM filter shapes for five center frequencies. Each filter is symmetrical on the linear frequency scale used, but the bandwidths of the filters increase with increasing center frequency.

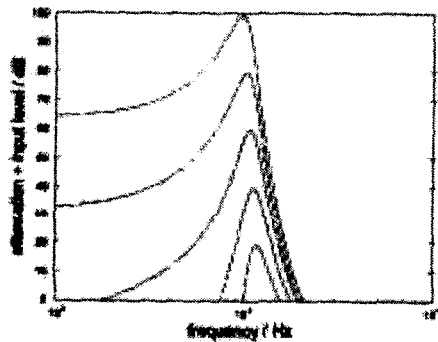


Figure 4. BM filtering via amplitude dependent filterbank.

Moore and Glasberg examined the available data and concluded that the input level to the filter is the primary factor controlling its shape. The BM filter shapes for each center frequency and masker level were calculated according to the assumptions outlined above. The high frequency side of each excitation pattern is determined by the low frequency branches of the BM filters and vice versa. This pattern closely resembles masked audio at similar masker levels, consistent with the idea that the level at the input to each filter determines its shape.

A bank of amplitude dependent filters simulates the response of the BM. Each filter is an IIR implementation of the gammachirp, and simulates the response of the BM at a given point. The filters are linearly spaced on the Bark frequency scale, which itself accurately describes the spacing of resonant frequencies along the BM.

As the BM changes its resonant properties in response to the amplitude of the incoming signal, so the shape of each gammachirp filter is dependent on the signal amplitude at the output of the filter. The envelope of the signal is derived by rectification, and low pass filtering. This envelope is then used to adjust the filter coefficients.

When the sound level is sufficiently high, the cochlear filter has a broad bandwidth and behaves like a passive and linear filter. As the signal level decreases, the filter gain increases and the bandwidth becomes narrower because of the active processes.

### 4.3 Outer Hair Cell

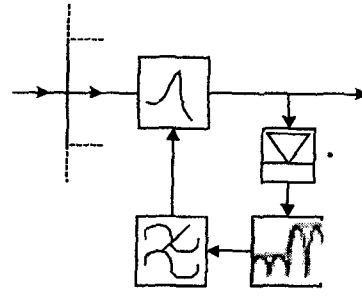


Figure 5. Amplitude dependence processing.

The output of each gammachirp filter is processed to provide the amplitude information necessary to tune the response of that individual filter. This feedback causes the Q of each filter to be proportional to the amplitude of the signal passing through it. This corresponds to the tuning mechanism mediated by the outer hair cells. The process is as follows:

1. Rectification
2. Peak detection and holding
3. Low pass filtering

The value of  $c$  is

$$c(t) = 3.29 - 0.059 \times 20 \log_{10}(\text{env}(t) + ina) \quad (7)$$

$\text{env}(t)$  is the low-pass filtered envelope, and  $ina$  is present to prevent the calculation of  $\log_{10}(0)$  during a silent input signal. The value of  $ina$  is below the minimum audible threshold, and has a negligible effect on supra-absolute-threshold calculations.

### 4.4 Inner Hair Cell

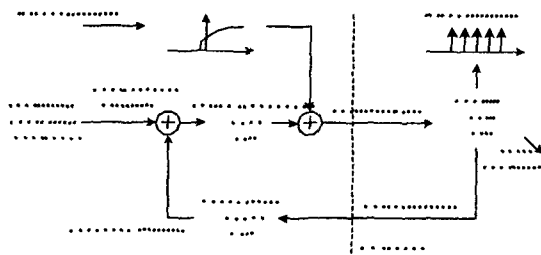


Figure 6. Mathematical processing model.

The hair cell contains a quantity of the "free transmitter",  $q(t)$ , which leaks through a permeable membrane into the synaptic cleft. The permeability,  $k(t)$ , fluctuates as a function of the instantaneous amplitude of the acoustic stimulation,  $s(t)$ , which we linearize for our implementation :

$$k(t) = \begin{cases} 0 & \text{for } s(t) + a \leq 0 \\ s(t) + 32 & \text{for } 0 < s(t) \leq 1348 \\ \frac{s(t)}{8} + \frac{s(t)}{128} + 1200 & \text{for } s(t) + a > 1348 \end{cases} \quad (8)$$

## 5. SIMULATION RESULTS

One possible method of calculating the perceived difference is to simply take the difference between the two sets of outputs from the auditory model. This is a time-varying calculated perceived difference (CPD). The threshold of perceiving a difference between two signals is known for a wide variety of possible signals, from various psychoacoustic experiments using human subjects. If the difference between two signals is greater than this threshold value, then a human listener will perceive a difference. If it is less, then the difference, though present, will be imperceptible [8].

Rather than looking at the difference on a sample-by-sample basis, can be summed over time. Then, using average interval.\*\*

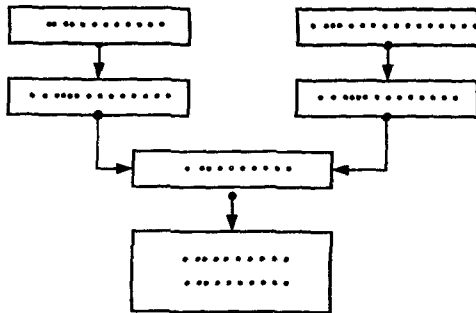


Figure 7. Method for calculating the perceived difference.

To simple test how accurately the model, we will use the model to assess the quality of some audio streams generated by an MPEG-1 layer-2 codec. The audio sample is taken from EBU-SQAM CD, The extract was coded 32 kbps and 256kbps. Each coded stream was analyzed by the auditory model, and compared with the original. Difference result is summed during in 20msec.

Table 1. Simulation result.

Bit-Rate	Number of Bands in which CPD is greater than threshold	Human perceive a difference
256	8	None
160	23	Slight
128	53	Much
64	84	More

The results indicate that, in this particular test, the model predicted human perception well. At the high bit rate the auditory model perceives small difference between the original and coded signals. At the lower bit rates, the model predicts that the difference between the original and coded signals will be well.

## 6. CONCLUSIONS

In this paper, we design the auditory model for objective audio quality measurement. The outer middle ear filter consists of a cascade of recursive lowpass filter and a parameterized recursive highpass filter. The BM filter is implemented using a gammachirp function.

The gammachirp function is approximated by the combination of a gammatone function and an IIR asymmetric compensation filter. This implementation reduces the computational cost for time varying filtering because both of the filters can be implemented with a few filter coefficients.

The output of this model is analyzed to detect perceptible differences between reference signal and test signal.

## Acknowledgments

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