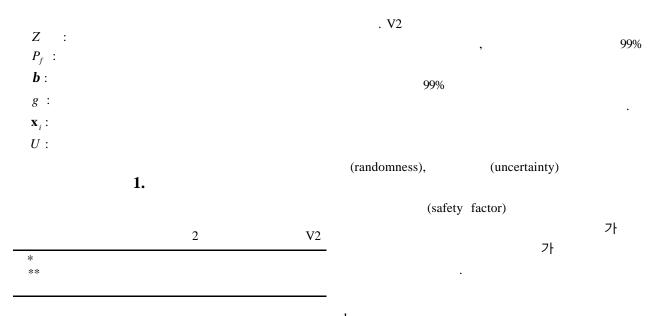
Barrier Function Method in Reliability Based Design Optimization

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Key Words:	ords: Reliability Based Design Optimization (),	Barrier Function
	(), Advanced Mean V	Value Plus Method (),
	FORM(First-Order Second Moment method:),	Reliability Index
	Approach (), Performance Measure	Appro	oach (
) Barrier Function Method ()				

Abstract

The need to increase the reliability of a structural system has been significantly brought in the procedure of real designs to consider, for instance, the material properties or geometric dimensions that reveal a random or incompletely known nature. Reliability based design optimization of a real system now becomes an emerging technique to achieve reliability, robustness and safety of these problems. Finite element analysis program and the reliability analysis program are necessary to evaluate the responses and the probabilities of failure of the system, respectively. Moreover, integration of these programs is required during the procedure of reliability based design optimization. It is well known that reliability based design optimization can often have so many local minima that it cannot converge to the specified probability of failure. To overcome this problem, barrier function method in reliability based design optimization is suggested. To illustrate the proposed formulation, reliability based design optimization of a bracket is performed. AMV and FORM are employed for reliability analysis and their optimization results are compared based on the accuracy and efficiency.



```
0
                                                              2.2
                  가
                                                  가
                                                            (Mean Value method)
                                                                                                           가
                                           가
                               가
                                                                                 가
                                                                                                            (Mean
                                                            Value)
                                                                     (Advanced Mean Value method :AMV)
  가
                                                가
                        (probability of failure)
                                                                          (most probable point : MPP)
                                                                                 (Mean Value First Order Second
                                                           Moment Method: MV FOSM or MV)
                                                               , Taylor
                         가
                                                             AMV
                                                                    Z_{AMV} = Z_{MV} + H(Z_{MV})
                                                                                       MPP
                                                                                           Z
                                                                 MPP
  2.
                                                                         H(Z_{MV})
  2.1
                                                           MPPL
                                                                    Z_{MV}
                                                                        MPPL
                                                                                                          . AMV
                                                                                                         H(Z_{MV})
                                                                        Z_{MV}
                            (R)가
                (S)
                                                            가
                  Z(R, S) = R - S = 0
                                                                                                            MPPL
                                                                                . AMV
                                (Z<0)
(Z > 0)
                                                                           MPP 가
                                                                                                          MPP
                  f_R(r) f_S(s)
                                                                                   AMV
                                                                     CDF
         P_{f} = \iint_{\Omega} f_{R,S}(r,s) dr ds
                                                                                                  . (i) Z_{MV}
                                                (1)
                                                              AMV
                                                                          MPP
                                                                                                      CDF
            f_{R,S}(r,s)
                                                 (joint-
                                                                   . (ii) MPP
                                                                                                       CDF
probability density function)
                                                                      MV
(failure set),
             Z(R, S) \le 0
                                                                                  CDF
                                     S 가
                              R
                                                                             Z_{MV}
                                                                  (n+m+1)
                                                                                                 , m
                                                                                                             CDF
       f_{R,S}(r,s) = f_R(r) f_S(s)
                                                (2)
                                                                            . CDF
                                                                               MPP
                                                                           AMV
        P_f = \iint\limits_{\Omega} f_R(r) f_S(s) dr ds
                                                (3)
```

2

2.3 First Order Reliability Method (FORM)

g(x)가 $f_X(x)$

$$P_f = \int_{g(\mathbf{x}) \le 0} f_X(\mathbf{x}) d\mathbf{x}$$
 (5)

(normal distributed random variable) X_i

$$u_i = \frac{x_i - \mathbf{m}_i}{\mathbf{S}_i} \tag{6}$$

(standard normal distribution) u_{i} (5)

$$g = a_0 + \sum_{i=1}^n a_i (\mathbf{m}_i + \mathbf{s}_i u_i)$$
 (7)

 $\boldsymbol{b} = \frac{\boldsymbol{m}_{G}}{\boldsymbol{s}_{G}} = \frac{\left| g(all \quad u_{i} = 0) \right|}{\sqrt{\sum_{i=1}^{n} \left(\frac{\partial g}{\partial u_{i}} \right)^{2}}}$ (8)

Fig.1

가

가

가

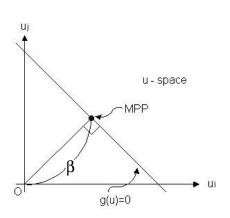


Fig.1 Geometric concept of reliability index

failure point)

MPP

(9)

Taylor

$$\mathbf{m}_{G} = \sum_{i=1}^{n} \frac{\partial g}{\partial x_{i}} \bigg|_{x=x^{*}} (\mathbf{m}_{i} - x_{i}^{*}),$$

$$\mathbf{s}_{G}^{2} = \sum_{i=1}^{n} \left(\frac{\partial g}{\partial x_{i}} \Big|_{x=x^{*}} \right)^{2} \mathbf{s}_{i}^{2}$$
(11)

$$\mathbf{m}_{G} = -\sum_{i=1}^{n} \frac{\partial g}{\partial u_{i}} \bigg|_{u^{*}} u^{*}$$

$$\mathbf{S}_{G}^{2} = \sum_{i=1}^{n} \left(\frac{\partial g}{\partial u_{i}} \Big|_{u^{*}} \right)^{2}$$
 (12)

$$\boldsymbol{b} = \frac{-\sum_{i=1}^{n} \frac{\partial g}{\partial u_{i}} \Big|_{u^{*}} u^{*}}{\sqrt{\sum_{i=1}^{n} \left(\frac{\partial g}{\partial u_{i}} \Big|_{u^{*}}\right)^{2}}}$$
(13)

(10)**MPP Taylor**

$$g(u) \approx \sum_{i=1}^{n} \left. \frac{\partial g}{\partial u_i} \right|_{*} (u_i - u_i^*)$$
 (14)

(13)

(10)**MPP** 가

MV FOSM Hasofer (iteration , MPP method)

가 MPP(most probable point) MPFP(most probable

3

2003

AFOSM(Advanced First-Order Second Moment method) FORM(First-Order Reliability Method) **3.** Min g(U)(Reliability Based design (19) $st \quad \boldsymbol{b} = |U| = \boldsymbol{b}_{\text{target}}$ Optimization: RBDO) 가 가 가 Minimize $Cost(\mathbf{x})$ (15)subject to $P(G(\mathbf{x}) \le 0) - P_f \le 0$ 가 가 가 가 (RIA) 3.1 3.3 Minimize $F(\mathbf{x})$ $subject\ to\ \ \boldsymbol{b}_{j} \geq \boldsymbol{b}_{j, target}$ (16) $\mathbf{x}_L \leq \mathbf{x} \leq \mathbf{x}_U$ (inverse barrier function method) $Min \quad \boldsymbol{b} = |U|$ 가 (feasible (17) $st \quad g(U) = 0$ region) 가 0 MPP 가 가 Minimize $f = F(\mathbf{x}) + \frac{1}{s} \left(-\sum_{i=1}^{p} \frac{1}{g_i(\mathbf{x})} \right)$ 가 가 subject to $\mathbf{x}_L \leq \mathbf{x} \leq \mathbf{x}_U$ (20)where s:scale factor 0 4. Bracket 가 4.1

subject to $g_{j,\text{target}} \ge 0$ (18) t = 1 cm $\mathbf{x}_L \le \mathbf{x} \le \mathbf{x}_U$

(PMA)

3.2

Minimize

 $F(\mathbf{x})$

4

Fig.2

 $E = 210 \, GPa \quad ,$

.(10) Bracket

12

bracket

n = 0.29 ,

502

, Bracket 620MPa . **b** 가 3 0.0013, 0.9987 . d1, d6, d8, d12 4 . (20)

Table.1

 $\begin{array}{ll} \textit{Minimize} & \textit{Volume} \\ \textit{subject to} & P[S_{\text{max}} < 620MPa] \leq P_{\text{target}} = 0.9987 \end{array}$

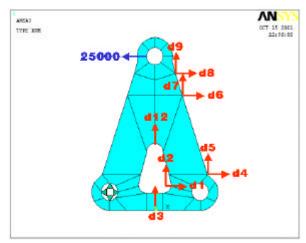


Fig. 2 Geometry and boundary condition of bracket

Table 1 Mean and standard deviation of the design variables

	Lower	Mean	Upper	Std.div.
d1	0.601	1.006	3.006	0.02
d6	0.832	3.332	5.332	0.02
d8	0.535	2.493	4.493	0.02
d12	6.776	7.776	11.176	0.02

4.2

Bracket

ANSYS NESSUS

ModelCenter

DOT

Bracket

Method

Variable Metric Sequential Linear Programming

Bracket Local minimum 가

가

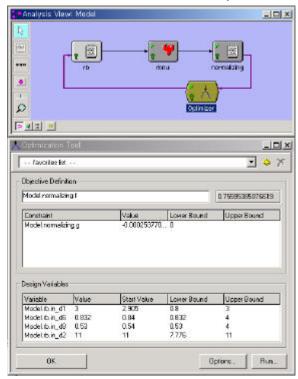


Fig. 3 Integration and automation in ModelCenter

Table 2 RBDO using RIA and BFM

Table 2 KDDO using KIA and Drivi				
Design Parameter	Initial			
DV.d1	1.006	3.0063	2.9050	
DV.d6	3.332	0.8321	0.8323	
DV.d8	2.493	0.4932	0.5328	
DV.d12	7.776	11.1767	10.7653	
smax	24243	58111	54761	
volume	770	441	456	
Probability	1	0.99755	0.99870	

Table 2

가

Table 3

AMV, FORM

Table 3 RBDO using BFM based on AMV and FORM

Design Parameter	AMV	FORM
DV.d1	2.9050	2.9049
DV.d6	0.8323	0.8327
DV.d8	0.5328	0.5316
DV.d12	10.7653	11.1091
smax	54761	54724
volume	456	448
Probability	0.99870	0.99870
u	3.0121	3.0122
Iteration	60	171

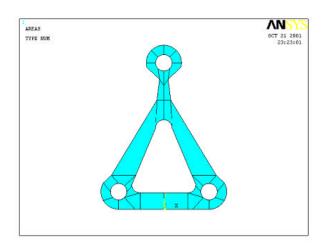


Fig 4 Optimal shape of bracket

AMV

FORM

가

FORM

AMV 가

FORM

AMV

5.

가 가

1) local minimum 가

2)

3)

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