

* . † . ** . *** ? 村秀男****

Simulator Development for the Aerodynamic Characteristics of a Wing in Ground

Tae-Ho Kim, Heuy-Dong Kim, Myeong-Ho Lee, Myong-Hwan Shon and Hideo Kashimura

Key Words : Aerodynamic Characteristics (), Ground Effect(), Lift to Drag Ratio(), WIG(), Wing Aerodynamics()

Abstract

A new ground transportation system is often simulated by the wing in ground effect(WIG). Recently, several kinds of experimental and computational studies are being carried out to investigate the WIG aerodynamic characteristics which are of practical importance to develop the new ground transportation vehicle system. These works are mainly based on conventional wind tunnel tests, but many problems associated with the WIG aerodynamic characteristics can not be satisfactorily resolved. In order to develop the new ground transportation vehicle system the WIG should be further investigated. To do this, it is necessary to develop a simulator appropriate to the WIG aerodynamics. The objective of the present study is to clarify the aerodynamic characteristics of the WIG and to develop a new experimental test rig for the investigation of the WIG aerodynamics. Some preliminary experiments are performed to investigate the usefulness of the WIG simulator.

Rec

c [mm] 1.
 C_L
 C_D
 D [N] (ground effect),
 F [N]
 h [mm]
 L [N]
 M [Nm], (wing in ground effect,
 n [rpm] WIG),
 S [mm²] 가,
 V [m/s] 가 WIG
 α [degree]
 ρ [kg/m³] WIG

†

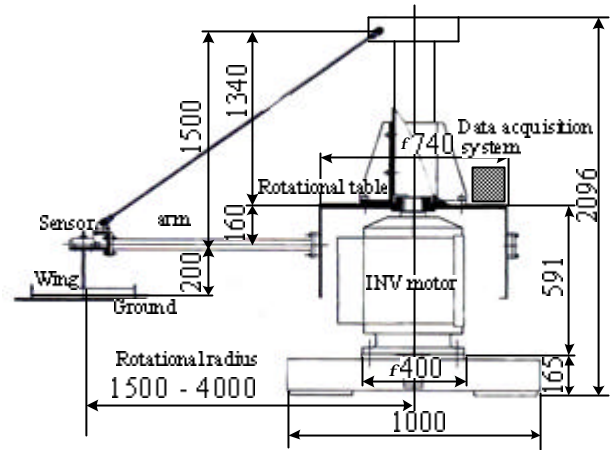
E-mail: kimhd@andong.ac.kr, **Tel.:** 054-820-5600

*

**

**** 北力州大

가
WIG
가
가 (1.3)
가 (4.5)
WIG
WIG
WIG



(b) Simulator for the WIG test

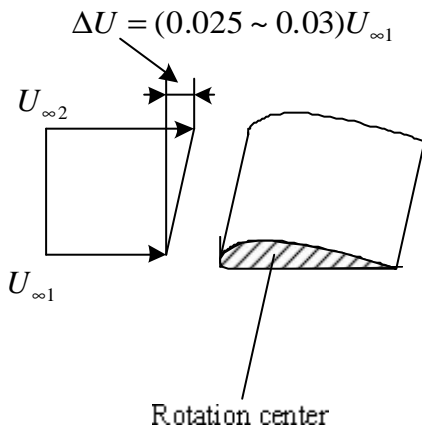
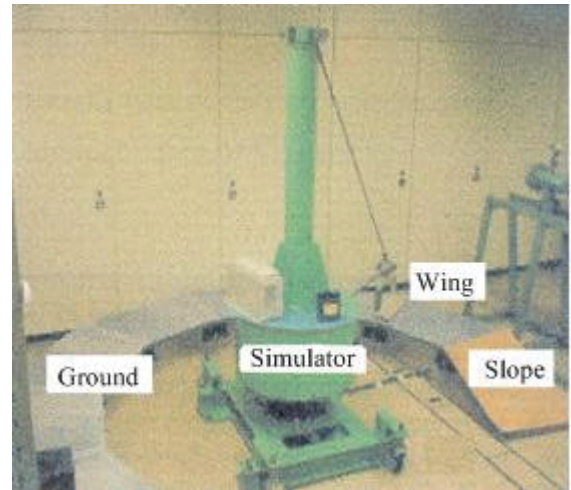
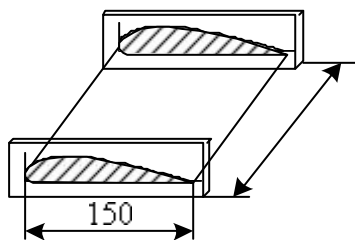


Fig.1 Velocity distribution over the WIG used



(c) Picture of the test rig

Fig.2 Schematic diagram of experimental apparatus (unit: mm)



(a) Shape of the WIG used

Fig.2 –continued –

가 WIG
2.
2.1
Fig.1

$U_{\infty 1}$
 $U_{\infty 2}$

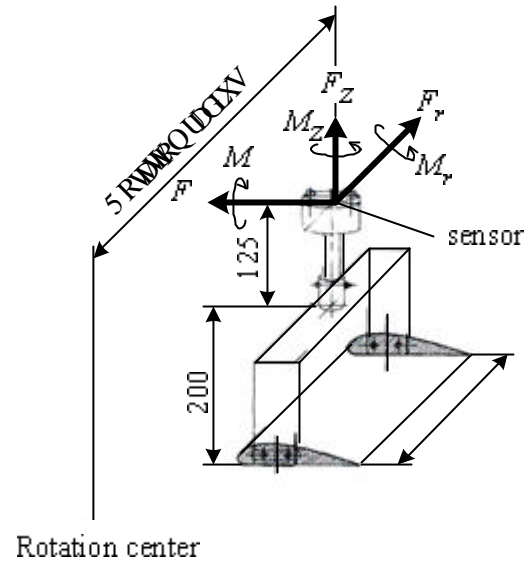
가
(20-40rpm)
(ΔU) 2.5-3%

Fig.2

Fig.2(a)
150mm

(SYM-1B) WIG

가
WIG
400mm,
WIG
(Fig.2(b))



arm

WIG

4m,

10kg

10

m/s

, arm

(h/c) 0-

1 가

2.2

Fig.2

WIG

가 Fig.3

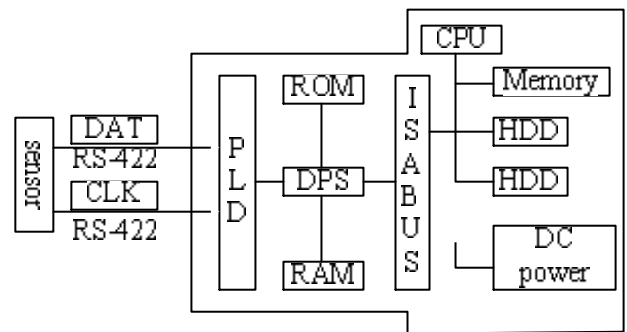
q,

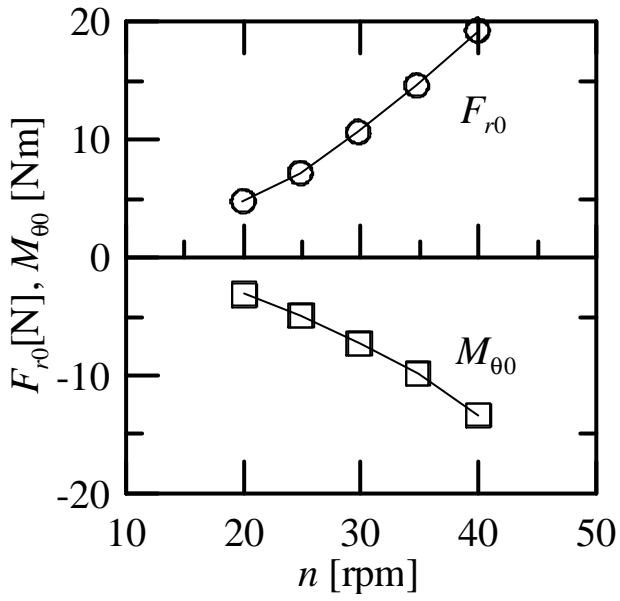
r, z
F M

$$L = C_L \cdot \frac{1}{2} \rho V^2 \cdot S \quad (1)$$

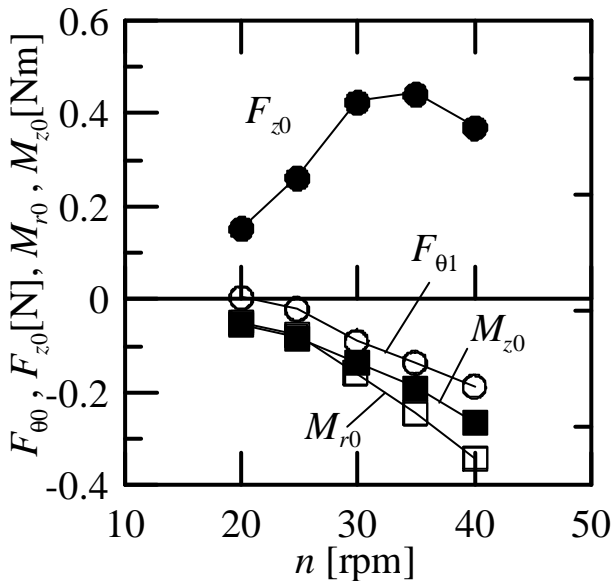
$$D = C_D \cdot \frac{1}{2} \rho V^2 \cdot S \quad (2)$$

, L, D, CL, V, CD, r





(a) F_{r0} and $M_{\theta0}$ vs n



(b) F_r, F_z, M_r and M_z vs n

Fig. 5 Forces and moments with variations in n

3.1 가
 Fig.5(a) n Fig.5
 F_{r0}
 $M_{\theta0}$, Fig.5(b)
 F_{z0}, F_{z0}
 M_r, M_z Fig.5(a)
 F_{r0} $M_{\theta0}$ n
 WIG 가
 F_{z0} Fig.5(b)
 $n > 30$ rpm
 가
 3.2 WIG 가
 WIG 가
 Fig.1
 가
 Fig.2(c) 2/3
 가
 Fig.6 $h=10$ mm, $a=8^\circ$, $n=40$ rpm

,A/D
 6 8kHz 가 가
 Fig.4
 RS-422

F_z A
 ,B
 가
 Fig.6
 Fig.7
 F_y, F_z

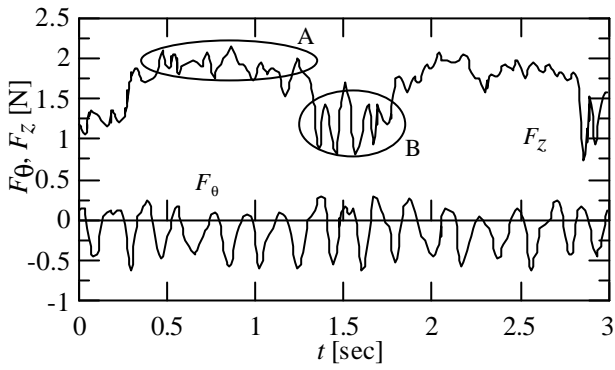


Fig. 6 Force variations with time on the WIG

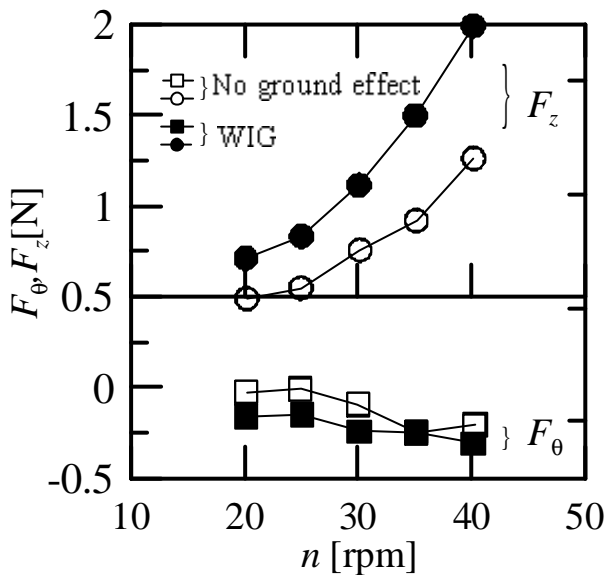


Fig. 7 Aerodynamic characteristics of the WIG with the variations in n ($h=10$ mm, $\alpha=8^\circ$)

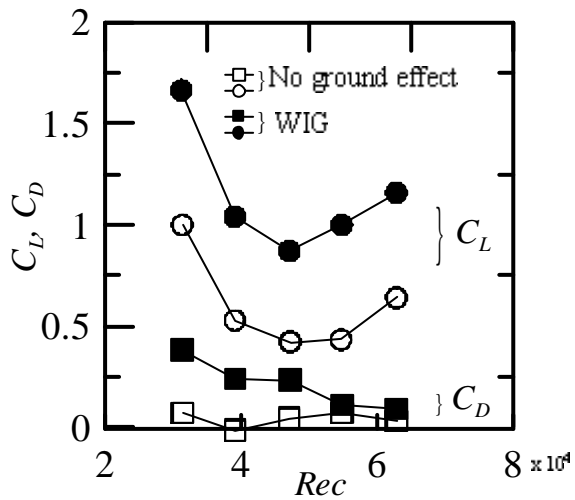


Fig. 8 Aerodynamic characteristics of the WIG with the variations in Rec ($h=10$ mm, $\alpha=8^\circ$)

Fig.6 A, B

1.5

n 가

Fig.8

C_L, C_D (1), (2)

C_L

(F_z , Fig.7) 가
(F_θ , Fig.5)

C_D

가

가

가

가

4.

가

(1)

가

(2)

가

1.5

가

가
가 4×10^4

, 0.5-0.7

(3)

が

- (1) 小濱泰昭, 1993, “エネルギー耕作形社会交通システム, 日本機会学会誌,” Vol.102, No.964, pp.93-95.
- (2) 小濱泰昭, 河原進, 渡? 英夫, 菊池?, 大田福男, 都丸裕司, 1999, “空力浮上式高速鐵道の可能性,” 第 37 回飛行機シンポジウム講演集, pp.45-48.
- (3) Ollila, R.G, 1980, “Historical Review of WIG Vehicles,” J. Hydronautics, Vol.14, No.3, pp.65-76.
- (4) 都丸裕司, 小濱泰昭, 1991, “翼型の地面効果特性に関する実験的研究,” ながれ, Vol.10, pp.47-60.
- (5) 小濱泰昭, 彦坂智和, 渡? 英夫, 1999, “空力浮上形輸送システムの空力特性と安全性に関する研究,” 日本航空宇宙学会論文集, Vol.47, No.541, pp.27-35.
- (6) 山名正夫, 伊藤光, 1977, “最大揚力係数の大きな翼型,” Vol.25, No.279, pp.201-207.
- (7) 安田知央, 砂田茂, 安田邦男, 河内啓, 田中誠, 1999, “低レイノルズ数における翼型特性,” 第 37 回飛行機シンポジウム講演集, pp.265-268.