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Impact response analysis of delaminated composite laminates using analytical solution

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Key Words : Analytical Solution(), Impact(), Linearized stiffness()

Abstract

An analytical solution has been developed for the impact response of delaminated composite plates. The analysis is based on an expansion of loads, displacements, and rotations in a Fourier series which satisfies the end boundary conditions of simply-supported. The analytical formulation adopts the Laplace transformation technique, requiring a linearization of contact deformation. In this paper, the nonlinear contact stiffness is replaced by a linearized stiffness, to provide an estimate of the additional compliance due to contact area deformation effects. It has been shown that defects such as delaminations may be modeled as spring stiffness. The change in the impact characteristics as this spring stiffness has been investigated theoretically. Predicted impact responses using analytical solution are compared with the numerical ones from the 3-D non-linear finite element model. From the results, it is shown that analytical solution was found to be reliable for predicting the impact response.

가

K_e :

K_e :

$F(t)$:

1.

(delamination)

가

가

가

X-

†

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*

**

(impactor)

(impact sound)

가

(adhesive)

$$u = u^0(x, y, z) + z\psi_x(x, y, z)$$

[1].

$$v = v^0(x, y, z) + z\psi_y(x, y, z)$$

(1)

Cawley[2]

(tapping)

$$w = w(x, y, z)$$

u, v, w

u^0, v^0, w
 ψ_x, ψ_y

x, y

Whitney Pagano 가

가

$$(B_{ij} = 0, A_{16} = A_{26} = D_{16} = D_{26} = 0)$$

(finite

element method)

$$D_{11}\psi_{x,xx} + D_{66}\psi_{x,yy} + (D_{12} + D_{66})\psi_{y,xy}$$

Shivakumar [3]

$$-kA_{55}\psi_x - kA_{55}w_x = \frac{\rho h^3}{12}\psi_{x,tt}$$

$$(D_{12} + D_{66})\psi_{x,xy} + D_{66}\psi_{y,xx} + D_{22}\psi_{y,yy}$$

(2)

$$-kA_{44}(\psi_y + w_y) = \frac{\rho h^3}{12}\psi_{y,tt}$$

(indentation)

$$kA_{55}(\psi_{x,x} + w_{x,x}) + kA_{44}(\psi_{y,y} + w_{y,y})$$

가

$$+ q(x, y, z) = \rho h w_{,tt}$$

(isotropic)

h

t

ρ

Choi[4]

k

가 a, b

Swanson[5]

Christoforou
(Laplace transform)

$$w = \psi_{x,x} = 0 \quad \text{at} \quad x = 0, a$$

(3)

$$w = \psi_{y,y} = 0 \quad \text{at} \quad y = 0, b$$

3.

3

(Fourier series)

가

1

가

2.

가

Whitney Pagano[6]

$$q(x, y, t) = \sum_m \sum_n Q_{mn}(t) \sin \frac{m\pi x}{a} \sin \frac{n\pi y}{b} \quad (4)$$

$$\begin{aligned}\psi_x &= \sum_m \sum_n A_{mn}(t) \cos \frac{m\pi x}{a} \sin \frac{n\pi y}{b} \\ \psi_y &= \sum_m \sum_n B_{mn}(t) \sin \frac{m\pi x}{a} \cos \frac{n\pi y}{b} \\ w &= \sum_m \sum_n B_{mn}(t) \sin \frac{m\pi x}{a} \cos \frac{n\pi y}{b}\end{aligned}\quad (5)$$

(4) (5)

가 (ξ, η)

(6)

$$Q_{mn}(t) = \frac{4F(t)}{ab} \sin \frac{m\pi\xi}{a} \sin \frac{n\pi\eta}{b} \quad (6)$$

F(t) a, b

(4) (5) (2)

3

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{12} & C_{22} & C_{23} \\ C_{13} & C_{23} & C_{33} \end{bmatrix} \begin{bmatrix} A_{mn}(t) \\ B_{mn}(t) \\ W_{mn}(t) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \left(\frac{Q_{mn}(t)}{\rho h W_{mn}(t)} \right) \end{bmatrix} \quad (7)$$

C_{ij}

$$C_{11} = D_{11} \left(\frac{m\pi}{a} \right)^2 + D_{66} \left(\frac{n\pi}{b} \right)^2 + kA_{55}$$

$$C_{12} = (D_{12} + D_{66}) \left(\frac{m\pi}{a} \right) \left(\frac{n\pi}{b} \right)$$

$$C_{13} = kA_{55} \left(\frac{m\pi}{a} \right)$$

$$C_{22} = D_{66} \left(\frac{m\pi}{a} \right)^2 + D_{22} \left(\frac{n\pi}{b} \right)^2 + kA_{44}$$

$$C_{23} = kA_{44} \left(\frac{n\pi}{b} \right)$$

$$C_{33} = kA_{55} \left(\frac{m\pi}{a} \right)^2 + kA_{44} \left(\frac{n\pi}{b} \right)^2$$

(7)

1

$$A_{mn}(t) = K_A W_{mn}(t) \quad ; \quad B_{mn}(t) = K_B W_{mn}(t) \quad (9)$$

$$K_A = \frac{C_{12}C_{23} - C_{13}C_{22}}{C_{11}C_{22} - C_{12}^2} \quad (10)$$

$$K_B = \frac{C_{12}C_{13} - C_{11}C_{23}}{C_{11}C_{22} - C_{12}^2}$$

(6) (7)

$$W_{mn}(t) + \omega_{mn}^2 W_{mn}(t) = \frac{Q_{mn}(t)}{\rho h} \quad (11)$$

$$\omega_{mn}^2 = \frac{C_{13}K_A + C_{23}K_B + C_{33}}{\rho h} \quad (12)$$

가 0 (11)

(convolution integral)

$$W_{mn}(t) = \frac{1}{\rho h \omega_{mn}} \int_0^t Q_{mn}(\tau) \sin \omega_{mn}(t-\tau) d\tau \quad (13)$$

$$W_{mn}(t) = \int_0^t Q_{mn}(\tau) \sin \omega_{mn}(t-\tau) d\tau \quad (4) \quad (6)$$

$$w(x, y, t) = \frac{4K_c}{\rho h}$$

$$\sum_m \sum_n K_{mn} \frac{\sin \left(\frac{m\pi\xi}{a} \right) \sin \left(\frac{n\pi\eta}{b} \right) \sin \left(\frac{m\pi x}{a} \right) \sin \left(\frac{n\pi y}{b} \right)}{\omega_{mn}} \int_0^t F(\tau) \sin \omega_{mn}(t-\tau) d\tau$$

(14)

K_c K_{mn}

$$K_C = \frac{1}{ab} \quad K_{mn} = 1$$

3.1

$$w\left(\frac{a}{2}, \frac{b}{2}, t\right) = V_0 t - \frac{1}{m_0} \int_0^t F(\tau) \sin \omega_{mn}(t-\tau) - \frac{F(t)}{K_e} \quad (15)$$

$$w(a/2, b/2, t) = \frac{V_0}{m_0} \quad \text{가}$$

$$F(t) = K_e \alpha$$

Choi

$$F = K_e \alpha \quad (16)$$

$$K_e = F_m^{1/3} k^{2/3} \quad (17)$$

$$k = \frac{4}{3} \frac{R^{1/2}}{1 - \nu_r^2 + \frac{1}{E_r} + \frac{1}{E_p}} \quad (18)$$

$$(16) \quad k_e \quad \alpha$$

$$(17) \quad F_m$$

k Hertz

$$(18) \quad R, \nu_r$$

$$E_r, E_p \quad (\text{young's modulus}) \quad (14)$$

(15)

$$\frac{F(\tau)}{K_e} = \nu_0 t - \frac{1}{m_0} \int_0^t F(\tau)(t - \tau) d\tau - \frac{4K_c}{\rho h} \sum_m \sum_n \frac{K_{mn}}{\omega_{mn}} \sin^2\left(\frac{m\pi}{2}\right) \sin^2\left(\frac{n\pi}{2}\right) \int_0^t F(\tau) \sin \omega_{mn}(t - \tau) d\tau \quad (19)$$

(19) (Laplace transform)

$$F(s) = \frac{m_0 \nu_0}{\left(1 + \frac{m_0}{K_e} s^2 + 4K_c \frac{m_0}{\rho h} \sum_m \sum_n K_{mn} \sin^2\left(\frac{m\pi}{2}\right) \sin^2\left(\frac{n\pi}{2}\right) \frac{s^2}{s^2 + \omega_{mn}^2}\right)} \quad (20)$$

(Inverse Laplace transform)

$$F(t) = \sum_j \frac{F_j}{\omega_j} \sin(\omega_j t) \quad (21)$$

$$\omega_j \quad (20) \quad (\text{pole})$$

$$F_j = \frac{m_0 \nu_0}{\omega_j \left(\frac{m_0}{K_e} + 4K_c \frac{m_0}{\rho h} \sum_m \sum_n K_{mn} \sin^2\left(\frac{m\pi}{2}\right) \sin^2\left(\frac{n\pi}{2}\right) \frac{\omega^2}{(\omega_{mn}^2 - \omega_j^2)^2} \right)} \quad (22)$$

3.2 (delamination modeling)

[1]

4 가 a 가 h/2

$$k_d = 1.5 \times \frac{D^*}{\alpha a^2} \quad (23)$$

D^*

[7]

$$D^* = \sqrt{D_{11} D_{22} (A+1)/2} \quad (24)$$

$$A = (D_{12} + 2D_{66}) / \sqrt{D_{11} D_{22}}$$

Fig.1

(25)

$$K_{eff} = \left[\frac{1}{k_e} + \frac{1}{k_d} \right]^{-1} \quad (25)$$

k_d

K_e

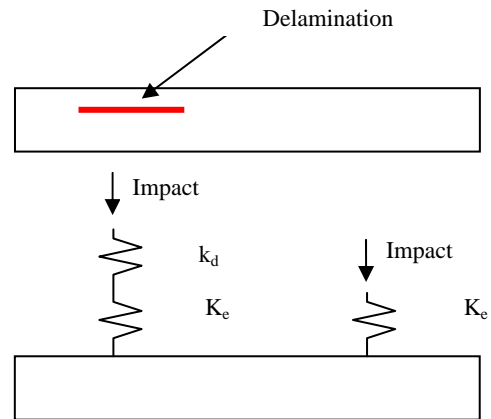


Fig. 1 Delamination model for impact analysis

3.3

Fig.2 NASTRAN

1-D

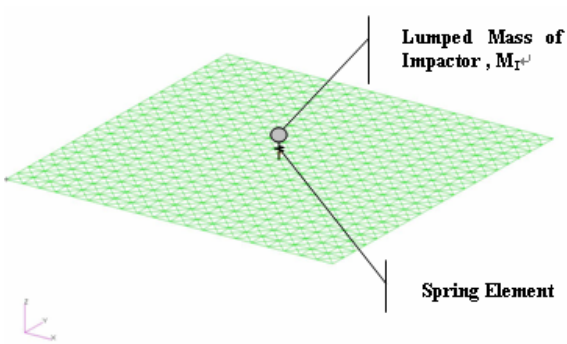


Fig. 2 Spring element model using general-purpose FEM software

3.4

Fig.3 3

Gap

Gap

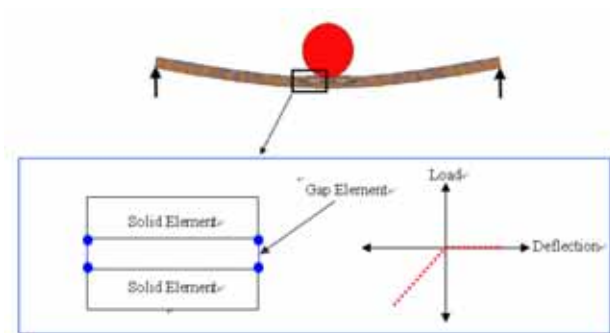


Fig. 3 Laminate with a delamination and gap element stiffness curve used to connect solid element

Fig.4

가 15 x 15 cm², A [0]₈, = 1.0 mm, 4.5 x 4.5cm²

B [0]₄, = 0.5 mm, C [0]₄, = 0.5 mm Table 1

Exploded view for delaminated region

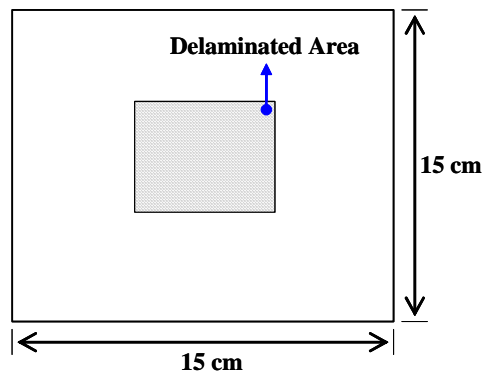
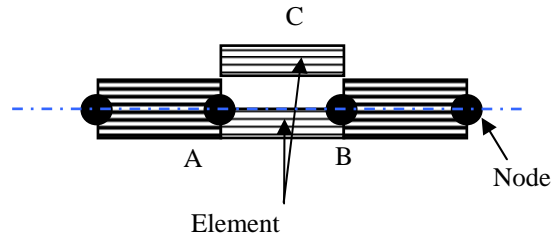


Fig. 4 Configuration of delaminated area

Table 1 Material properties

Material properties Of lamina	$E_1 = 120 \text{ GPa}, E_2 = 7.9 \text{ GPa}$
	$G_{12} = G_{13} = G_{23} = 5.5 \text{ GPa}$
	$\nu_{12} = 0.3$
	$\rho = 1582 \text{ kg/m}^3$
	Thickness = 0.125 mm
Material properties of impactor	$E = 207 \text{ GPa}$
	$\nu = 0.3$

4.

Fig.5

가 Fig.4

(M_I/M_P) 35.0, 0.5 m/sec M_I, M_P, Fig.6, (M_I/M_P) 10.0, 0.5 m/sec

가

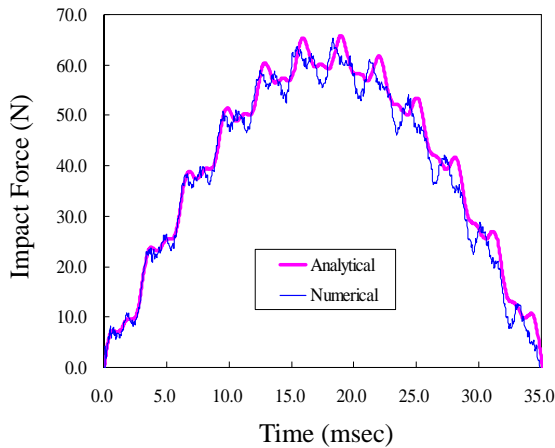


Fig. 5 Impact force histories analyzed using an analytical solution and the 3-D non-linear model when the mass ratio 35.0

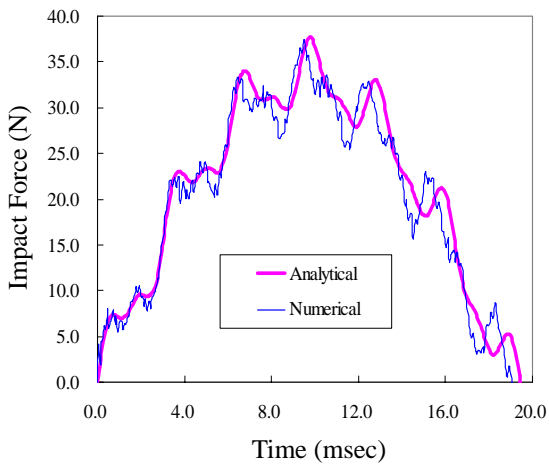


Fig. 6 Impact force histories analyzed using an analytical solution and the 3-D non-linear model when the mass ratio 10.0

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5.

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