

Cutting Force Models in Circular Milling Processes

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Key Words : Cutting force (), Circular milling (가), Uncut chip thickness ()

Abstract

Circular milling operations are used to enlarge die and cylinder bores, and machine airframe pockets. In this case, cutting force varies as cutting tool position relative to workpiece. This paper presents a mechanistic model of geometric uncut chip thickness by predicting time varying cutter-part intersection as the cutter travels along the circular path. Compared with experimental results, the suggested cutting force model shows a good agreement.

. Kline [1]

, Sutherland

ω : Spindle speed(rad/s)

Devor[2]

Ω : Angular traverse speed along the tool path (rad/s)

. Altintas [3]

N : Spindle speed(rmp)

, Yun

N_p : Angular traverse speed along the tool path (rev/min)

Cho[4]

t : discrete time intervals

θ_0, ϕ_0 : Initial positions of the tool and the first tooth(rad)

ϕ_j : Instantaneous immersion angle of tooth j (rad)

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ϕ_{st}, ϕ_{ex} : Cutting entry and exit angle(rad)

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f_d : Feedrate(mm/flutes)

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h_j : Uncut chip thickness

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2.

2.1

2.2

j

i

$$\phi_j(k) = \phi_1(k) + (j-1) \frac{2\pi}{N_f} + dz \cdot i \cdot \frac{\tan \beta}{R_0}$$

(1)

$$\theta(k) = \theta_0 + \Omega kt$$

$$\phi_1(k) = \phi_{10} + \omega kt$$

$$\omega = \frac{2\pi N}{60}, \quad \Omega = \frac{2\pi N_p}{60}$$

$$h_j = f_d \cdot \sin(\phi_j(k)) \quad (2)$$

$$\begin{bmatrix} F_{tj} \\ F_{rj} \end{bmatrix} = \begin{bmatrix} K_{tc} \cdot h_j + K_{te} \\ K_{rc} \cdot h_j + K_{re} \end{bmatrix} \cdot \mathbf{a} \quad (3)$$

X-Y

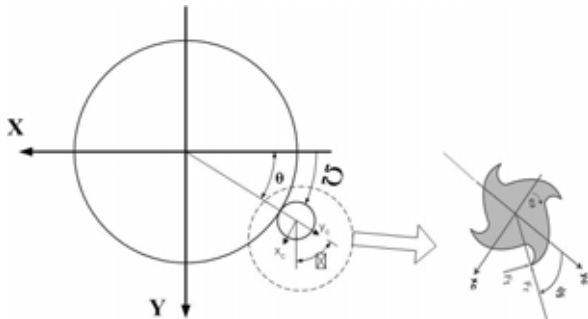


Fig. 1 Geometric of tool and workpiece and cutting forces in tangential and radial

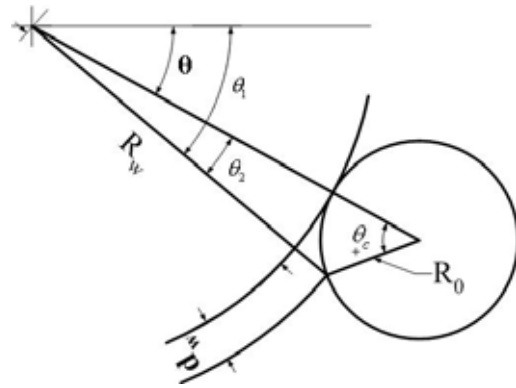


Fig. 2 Instantaneous immersion angle on workpiece

$$\begin{aligned} F_x(\theta, \phi) &= \sum_{j=1}^{N_f} g(\phi_j) [-F_{tj} \cdot \sin(\delta(k)) - F_{rj} \cdot \cos(\delta(k))] \\ F_y(\theta, \phi) &= \sum_{j=1}^{N_f} g(\phi_j) [F_{tj} \cdot \cos(\delta(k)) - F_{rj} \cdot \sin(\delta(k))] \end{aligned} \quad (4)$$

$$\delta(k) = \theta(k) - \phi_j(k)$$

$$g(\phi_j) = \begin{cases} 1 & \text{for } \phi_{st}(\theta) < \phi_j(k) < \phi_{ex}(\theta) \\ 0 & \text{for others} \end{cases}$$

$\phi_{ex}(\theta)$ Fig. 2

$$\theta_c = \frac{R_2^2 + R_0^2 - R_1^2}{2 \cdot R_2 \cdot R_0} \quad (5)$$

$$\phi_{st}(\theta) = \pi - \theta_c \quad (6)$$

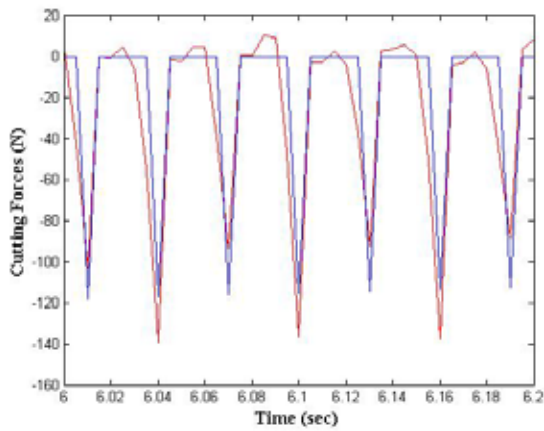
3.

30 °, OSG 11 ° 2 12mm, AD

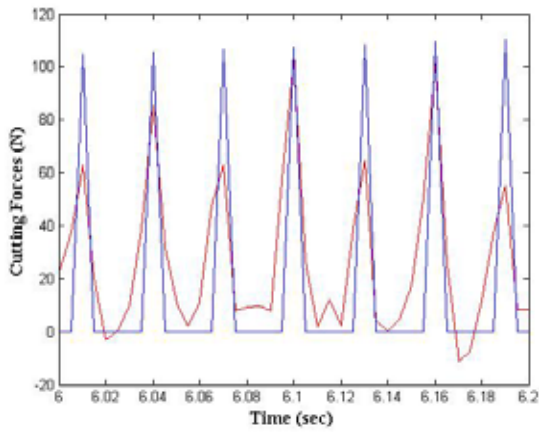
Table 1

Al6061-T6

3.1.1

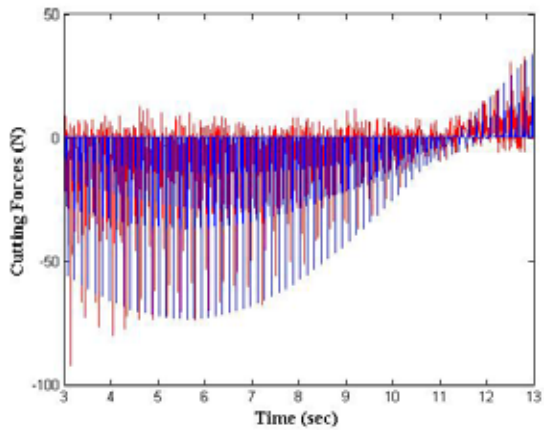


(a) Cutting forces in X direction

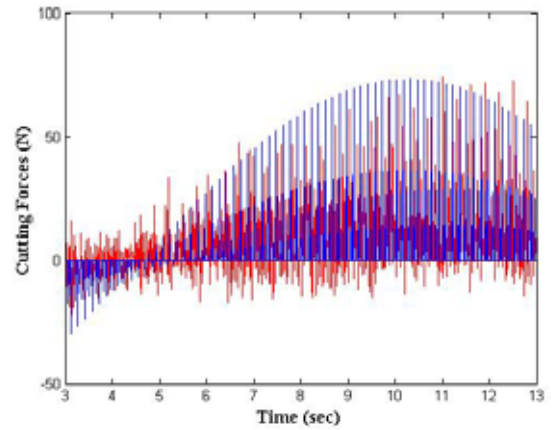


(b) Cutting forces in Y direction

Fig. 3 Comparison of measured and simulated cutting forces at a small time windows for test 3

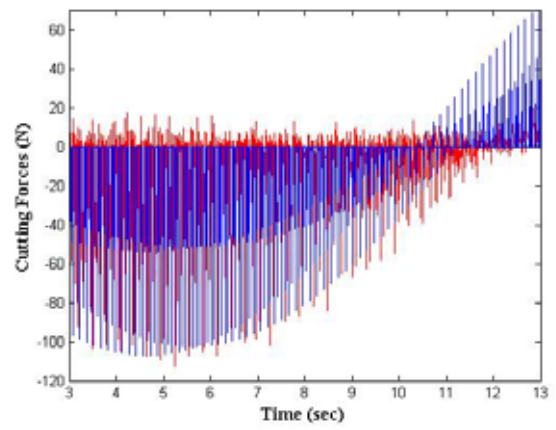


(a) Cutting forces in X direction

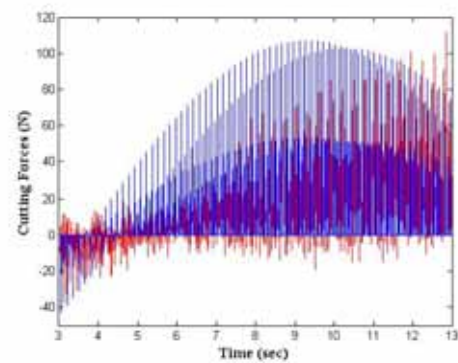


(b) Cutting forces in Y direction

Fig. 4 Cutting forces for test 1 condition

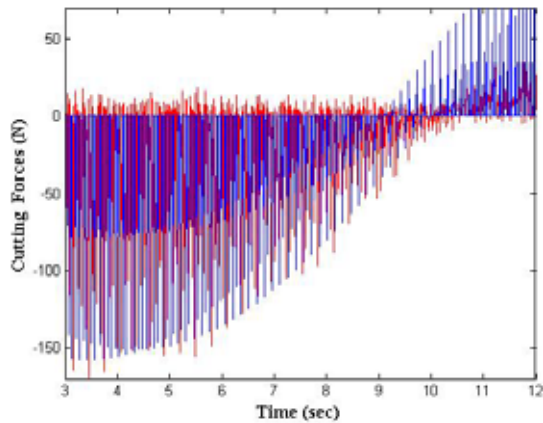


(a) Cutting forces in X direction

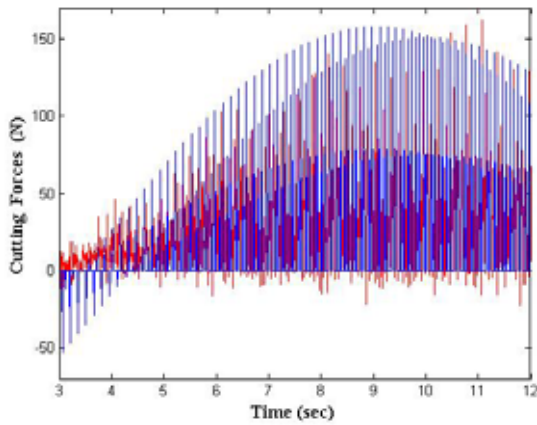


(b) Cutting forces in Y direction

Fig. 5 Cutting forces for test 2 condition



(a) Cutting forces in X direction



(b) Cutting forces in Y direction

Fig. 6 Cutting forces for test 3 condition

Fig. 3 - Fig. 5 Table 2

Geometric uncup chip thickness

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Table 1 Test cut conditions

No	Spindle speed (rpm)	Axial depth (mm)	Radial depth (mm)	Feed (mm/flute)
1	1000	5	0.3	0.2
2	1000	5	0.5	0.2
3	1000	5	0.7	0.2

Table 2 Estimated cutting force coefficients

No	K_{te} (N/mm ²)	K_{rc} (N/mm ²)	K_{te} (N/mm)	K_{rc} (N/mm)
1	180	150	22	15
2	420	116	15	18
3	650	145	20	21

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