

Estimation of Optimal Weather Routing of a Ship using the Result of Model Test and Weather data

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요 약 : 최적기상항로 추정 of 주요 평가지수중 하나인 파랑중 부가저항의 모형시험을 이용하여 실험역의 불규칙파중 부가저항을 도출하였으며, 이를 평가지수로 갖는 A*알고리즘을 도입하여 최적기상항로를 추정하였다.

핵심용어 : 최적기상항로(Optimal weather routing), 파랑중 부가저항(Added Resistance in waves), A*알고리즘(A* algorithm)

Index

- ❖ Introduction
- ❖ Experiment on added resistance in waves
- ❖ Application of A* Algorithm to optimal routing
- ❖ Simulation and Results
- ❖ Conclusion & future works

2 Optimal path of a ship in wave condition

Introduction

$$\Delta R = \Delta R_{AA} + \Delta R_{AW} + \Delta R_{\delta\delta} + \Delta R_{\beta\beta} + \Delta R_{AS} + \Delta R_{AIDS}$$

Where;

- ΔR : the ship's added resistance
- ΔR_{AA} : added resistance due to wave
- ΔR_{AW} : added resistance due to wind
- $\Delta R_{\delta\delta}$: resistance correction by the effect of steering gear(rudder)
- $\Delta R_{\beta\beta}$: resistance correction by the effect of drift
- ΔR_{AS} : resistance correction by the effect of water temperature
- ΔR_{AIDS} : resistance correction by the effect of difference in trip or draft of the ship

3 Optimal path of a ship in wave condition

Introduction

- ❖ Optimal weather routing
 - Safety and minimal fuel consumption by considering waves.
- ❖ Optimization algorithms:
 - A modified isochrone method: Hideki Hagikawa (1989)
 - Estimating the standard deviations of passage time.
 - Dijkstra's algorithm: Takashima (2009)
 - The propeller revolution number is kept constant during the voyage and only the course can be controlled.
 - 3D Dynamic programming method: In Wei, Zhou (2012)
 - Ship power and heading are control variables.

➡ The optimization of ship routing algorithms along with the precise wave forecasting data and ship characteristics have been developed and evaluated.

4 Optimal path of a ship in wave condition

Introduction

- ❖ "Systematic Experimental and Numerical Analyses on Added Resistance in waves" (Park, et. al. 2014)
- ❖ "Some methods to obtain the added resistance of a ship advancing in waves" (F.Pérez Arribas, 2007)
- ❖ "On the Prediction Method of Added Resistance of Ships Regular Heave Waves" (J.M.Lew et. al. 1986)

Model test

In linear towing tank

- A number of periods
- Large scaled model
- Linear towing only

In square tank

- Short periods
- Linear towing
- Diagonal towing

<Linear towing tank in KRISO>

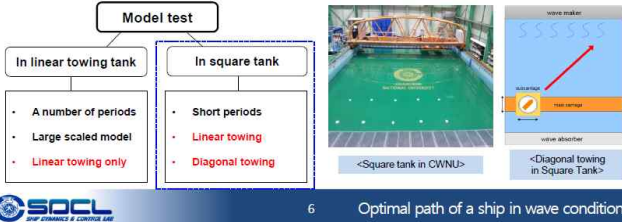
<Diagram for linear towing>

5 Optimal path of a ship in wave condition

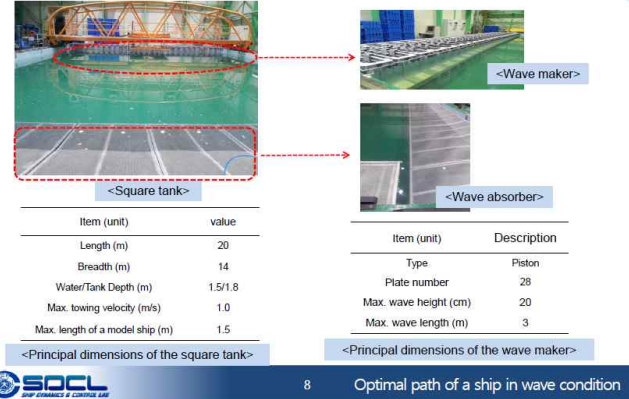
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Introduction

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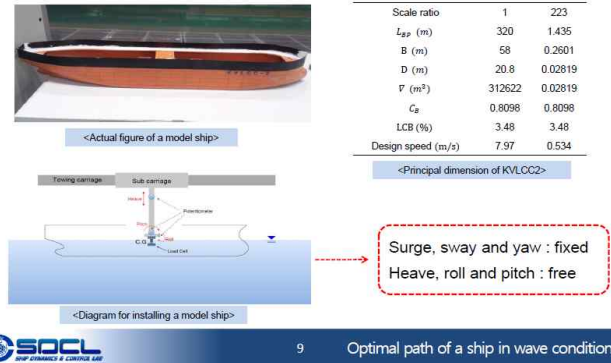


Test facility



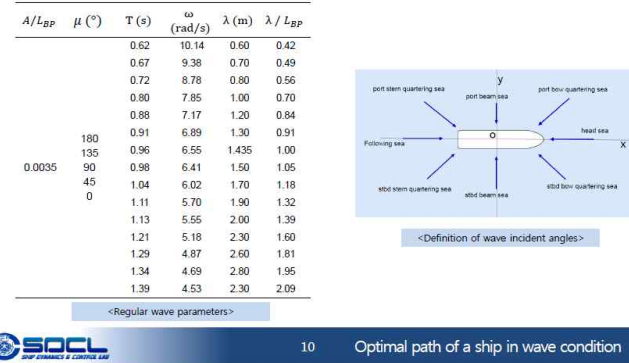
Target model ship

KVLCC2



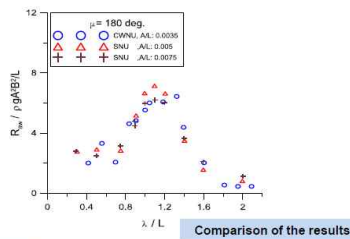
Regular wave properties

Wave parameters & wave incident angles



Comparison of the results

- ❖ Head sea condition
- ❖ Comparison between the results in CWNU and SNU
- ❖ To verify the availability of the test results → **guaranteed**



Added resistance in waves

