

GLOBAL CONSTANCY PRINCIPLE FOR MIZOHATA OPERATORS

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Introduction

In [1] L. Nirenberg constructed a famous example of a smooth vector field which have only the constant functions as solutions in an open subset of the plane. Explanations of this phenomenon have been proposed in Treves [3] and Sjöstrand [2]. The explanation in [3] is related to the following so-called "local constancy principle".

(L) If a C^1 solution u of $Lu=0$ with $du \neq 0$ exists, then, locally, any other C^1 solution h of this equation is constant on each set on which u is constant.

In this short paper we shall obtain a sufficient condition for the validity of a global version of the local constancy principle (L) for Mizohata operators M_k .

Throughout this paper let M_k (k , odd) be the vector field in an open subset Ω of R^2

$$(1) \quad M_k = \frac{\partial}{\partial y} + iy^k \frac{\partial}{\partial x}.$$

We now give a sufficient condition on Ω for a Mizohata operator M_k of the form (1) to satisfy the following global version of the local constancy principle (L):

(G) Let u be a C^1 solution of

$$(2) \quad M_k u = 0$$

in Ω with $du \neq 0$. Then any other C^1 solution h of (2) in Ω is constant on $u^{-1}(z)$ for every fixed $z \in u(\Omega)$.

Note that there exists a C^∞ function u of (2) in Ω with $du \neq 0$ for all $\omega \in \Omega$. For example one may take

$$u = x - i \frac{y^{k+1}}{k+1}.$$

We denote by u^+ and u^- the restrictions of u to Ω^+ and Ω^- , respectively.

PROPOSITION 1. *Let u be a solution of (2) in Ω with $du(\omega) \neq 0$. Then the Jacobians of u^+ and u^- are nonvanishing in Ω^+ and Ω^- , respectively.*

Proof: Since $\operatorname{Re} u_y = y^k \operatorname{Im} u_x$ and $\operatorname{Im} u_y = -y^k \operatorname{Re} u_x$

$$\begin{aligned} \frac{\partial(\operatorname{Re} u, \operatorname{Im} u)}{\partial(x, y)} &= -y^k((\operatorname{Re} u_x)^2 + (\operatorname{Im} u_x)^2) \\ &= -\frac{1}{y^k}((\operatorname{Re} u_y)^2 + (\operatorname{Im} u_y)^2). \end{aligned}$$

REMARK. $u^+(u^-, \text{ resp.})$ in Proposition 1 is a local diffeomorphism from $\Omega^+(\Omega, \text{ resp.})$ into C .

Before stating the main theorem, let us examine the following crucial example.

EXAMPLE. Let Ω be the S-shaped domain in R^2 , shown in Fig. 1 and consider

$$M = \frac{\partial}{\partial y} - iy \frac{\partial}{\partial x} \text{ in } \Omega.$$

Take the solution $u = x + iy^2/2$ of $Mu = 0$.

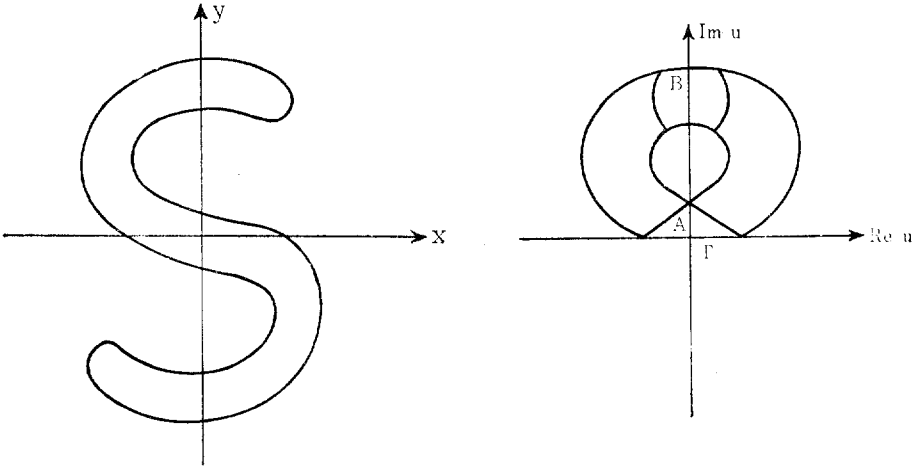


Fig. 1

Clearly du does not vanish in Ω . Then u maps onto the annulus shaped domain in C in Fig. 1. Put

$$u(\Omega^+) \cap u(\Omega^-) = A \cup B$$

with A, B indicated in Fig. 1. Note that the closure of A contains the line segment Γ which is the image of $\Omega_0 = \{(x, y) \in \Omega \mid y = 0\}$ under the mapping u .

Let h be any other C^1 solution of $Mu = 0$ and let h^\pm be the restriction of h to Ω^\pm . Then we can form $\tilde{h}^\pm = h^\pm \circ u^{-1}$, since u^\pm is a diffeomorphism of Ω^\pm onto $u(\Omega^\pm)$. Thus \tilde{h}^\pm is defined in $u(\Omega^\pm)$. Since $d(h^\pm du) = -(Mh^\pm) dx \wedge dy = 0$ in Ω^\pm , we have $d(\tilde{h}^\pm dz) = 0$ in $u(\Omega^\pm)$. In other words, h^\pm is holomorphic in $u(\Omega^\pm)$. As z approaches any point in Γ $\tilde{h}(z) = \tilde{h}^+(z) - \tilde{h}^-(z)$ tends to zero. Therefore by analytic continuation we must have $\tilde{h}(z) = 0$, i. e., $\tilde{h}^+(z) = \tilde{h}^-(z)$ in A . However, \tilde{h}^+ and \tilde{h}^- do not have to coincide in B . Examples of this type can be easily constructed.

This example shows us that the connectedness of $u(\Omega^+) \cap u(\Omega^-)$ is crucial for (G) to be true. We now prove that this condition is sufficient for (G).

THEOREM 1. *Let Ω be an open subset of R^2 and u be a solution of (2) with $du \neq 0$ in Ω , u^+ and u^- injective in Ω^+ and Ω^- , respectively. Suppose that $u(\Omega^+) \cap u(\Omega^-)$ is connected. Then (G) holds for M_k .*

Proof. Put $G = u(\Omega^+) \cap u(\Omega^-)$. Then the closure of G contains $\Gamma = u(Q_0)$. Set $V^\pm = (u^\pm)^{-1}(G)$. Call h^\pm the restriction of h to V^\pm . Since u^\pm is a diffeomorphism of V^\pm onto G , we put $\tilde{h}^\pm = h^\pm \circ (u^\pm)^{-1}$ and $\tilde{h} = \tilde{h}^+ - \tilde{h}^-$ in G . Since $d(h^\pm du) = -(M_k h^\pm) dx dy = 0$ in V^\pm we have $d(\tilde{h}^\pm dz) = 0$ in G . Hence \tilde{h}^+, \tilde{h}^- and \tilde{h} are holomorphic in G . However $\tilde{h}(z)$ tends to 0 as z approaches some point on Γ . Since Γ contains a nonempty open arc $\tilde{h} = 0$ in G by analytic continuation. In other words, $h^+ \circ u^{-1} = h^- \circ u^{-1}$ in G .

References

1. L. Nirenberg, *Lectures on linear partial differential equations*, Reg. Conf. Series in Math. No. 17, Amer. Math. Soc. 1973.
2. J. Sjöstrand, *Note on a paper of F. Trèves concerning Mizohata type operators*, Duke Math. J. **47** (1980), 601-608.
3. F. Trèves, *Remarks about certain first order linear PDE in two variables*, Comm. in PDEs, **54** (1980), 381-425.