

CONTINUITY OF DIRECTIONAL ENTROPY FOR A CLASS OF Z^2 -ACTIONS*

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1. Introduction

J. Milnor [Mi2] has introduced the notion of directional entropy in his study of Cellular Automata. Cellular Automaton map can be considered as a continuous map from a space K^{Z^n} to itself which commutes with the translation of the lattice Z^n . Since the space K^{Z^n} is compact, map S is uniformly continuous. Hence S is a block map (a finite code) [He]. (S is said to have a finite memory.) In the case of $n = 1$, we have a shift map, T on K^Z , and a block map S and they together generate a Z^2 action.

Given an arbitrary Z^2 action, it is not hard to define the entropy of a Z -action $T^k S^\ell$, where k and ℓ are both integers. Since the directional entropy is defined in all directions besides the rational directions like $(k, \ell) \in Z^2$, it can be considered as a generalization of the entropy of non cocompact subgroups. It is shown in [Si] and [Pal] that the directional entropy function is upper semi-continuous in the case of a Z^2 action generated by a Cellular Automaton map like Milnor's setting. It is also shown by Thouvenot that the directional entropy is not upper semi-continuous in a more general setting.

Also the notion of directional entropy is an important tool for the computation of the entropy of a skew product with a more general group action. That is, if we have a Z^2 action generated by a Cellular Automaton map on the fiber Y and a skewing function $\varphi : X \rightarrow Z^2$, the entropy of the skew product on $X \times Y$ is computable in terms of the entropy of the base transformation and the integral of the skewing

Received July 6, 1994.

1991 AMS Subject Classification: Primary 28D05.

Key words: directional entropy, cone entropy.

This work was partially supported by Ajou University Faculty Grant and GARC-KOSEF.

function. We require the skewing function to be integrable.(See[Pa2] and [Pa3] for details.)

Given an ergodic system of finite entropy (X, T, \mathcal{F}, μ) , it can be represented (*isomorphic*) as a shift space of finite alphabets. Without confusion, we will denote this symbolic system by (X, T, \mathcal{F}, μ) . Let S be a measure preserving invertible map of X generated by a block map. Hence $\{T, S\}$ generate a Z^2 -action on X . By a block map S , we mean a map determined by a given rule f . That is, the n^{th} coordinate of Sx is determined by $f(x_{n-s}, x_{n-s+1}, \dots, x_0, \dots, x_{n+s})$. We call S a block map of size $2s$.

In this paper we will show that the upper semi-continuity holds for a more general class of Z^2 actions than the class shown in [Pa1]. In particular, if S is a finitary code with finite expected code length, then the directional entropy is upper semi-continuous. It is not yet clear if the directional entropy is in fact continuous even in the case of a Z^2 -action generated by a cellular automation map.

First we embed the lattice Z^2 into the 2-dimensional real vector space R^2 . We call a vector \vec{v} a rational vector if the slope of the vector is rational. Otherwise, we call the vector an irrational vector. Let P be a partition of X according to the alphabets. We denote the partition $T^i S^j(P)$ by $P_{i,j}$. Recall the definition of the directional entropy in the direction of \vec{v} :

$$h(\vec{v}) = \sup_B \overline{\lim}_{t \rightarrow \infty} \frac{1}{t} H \left(\bigvee_{(i,j) \in B+[0,t]\vec{v}} P_{i,j} \right),$$

where $B + [0, t]\vec{v} = \{(i, j) \in Z^2; \text{there exists } (k, \ell) \in B \text{ such that } (i, j) - (k, \ell) = \alpha \vec{v} \text{ for some } \alpha \in [0, t]\}$. Supremum is taken over all bounded subsets of Z^2 .

Given a vector $\vec{v} \in R^2$, which is not a scalar multiple of $(1, 0)$, we define $w = \cot\theta$ where θ is the angle between the vector \vec{v} and x -axis. We note that $(w, 1)$ is a scalar multiple of \vec{v} .

It is not difficult to check that

$$h(\vec{v}) = \lim_{n \rightarrow \infty} \overline{\lim}_{t \rightarrow \infty} \frac{1}{t} H \left(\bigvee_{j=0}^{\lfloor ty \rfloor} \bigvee_{-n+jw+a < i < n+jw+a} P_{i,j} \right)$$

for any $a \in [0, 1]$. Clearly $h(\lambda\vec{v}) = \lambda h(\vec{v})$ and $h(T^p S^q) = h(\vec{v})$ where $\vec{v} = (p, q)$. (see[Mi1])

Also we recall the definition of the cone entropy defined by D.Lind[Li], denoted by $h^c(\vec{v})$ in the direction of $\vec{v} = (x, y)$. Let $\theta_0 = \tan^{-1} \frac{y}{x}$. We consider the vector $\vec{v}_\theta = (x_\theta, y)$ and $\vec{v}_{-\theta} = (x_{-\theta}, y)$ where x_θ and $x_{-\theta}$ satisfy $\frac{y}{x_\theta} = \tan(\theta_0 + \theta)$ and $\frac{y}{x_{-\theta}} = \tan(\theta_0 - \theta)$ respectively. Note that $x_{-\theta} \geq x_\theta$. Cone entropy is defined as follows

$$h^c(\vec{v}) = \lim_{\theta \rightarrow 0} \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{j=0}^{[ny]} \bigvee_{jx_\theta < i < jx_{-\theta}} P_{i,j} \right)$$

We denote the set $\{(i, j) : 0 \leq j < \infty, -m + jw \leq i \leq m + jw\}$ by $R_m(\vec{v})$ and the set $\{(i, j) : 0 \leq j \leq [ny], -m + jw \leq i \leq m + jw\}$ by $R_m^n(\vec{v})$. If $y = 0$, then $R_m(\vec{v})$ denote the set $\{(i, j) : 0 \leq j \leq m, 0 \leq i < \infty\}$ and $R_m^n(\vec{v})$ denote the set $\{(i, j) : 0 \leq j \leq m, 0 \leq i \leq n\}$. Sometimes by $R_m^n(\vec{v})$ we denote also a parallelogram whose base is not necessarily centered around $(0,0)$ as long as the length of the base is m and the height is $[ny]$. We will call $C_\theta(\vec{v}) = \{(i, j) : 0 \leq j < \infty, jx_\theta \leq i \leq jx_{-\theta}\}$ the θ -cone around \vec{v} . Note that $C_\theta(\vec{v})$ is an unbounded cone. We will also call $C_\theta^n(\vec{v}) = \{(i, j) : 0 \leq j \leq n[ny], jx_\theta \leq i \leq jx_{-\theta}\}$ the n - θ -cone. Sometimes we delete \vec{v} in the notation if the vector is obvious in the context.

We can write

$$h(\vec{v}) = \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in R_m^{[ny]}(\vec{v})} P_{i,j} \right)$$

and

$$h^c(\vec{v}) = \lim_{\theta \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in C_\theta^n(\vec{v})} P_{i,j} \right).$$

Note that $h^c(\vec{v}) \geq h(\vec{v})$ for all \vec{v} . It is shown that in the case of a Z^2 -action generated by a block map (Cellular Automaton), cone entropy in the direction of \vec{v} is the same as the directional entropy $h(\vec{v})$ [Pa2]. We have the following Lemma.

LEMMA 1. $h^c(\vec{v})$ is upper semi-continuous.

Proof. We let $\{\vec{v}_i = (x_i, y_i)\} \rightarrow \vec{v} = (x_0, y_0)$. Given $\epsilon > 0$, there exists $\alpha(\epsilon)$ such that if $0 < \theta \leq \alpha$, then

$$\lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in C_\theta^n} P_{i,j} \right) < h^c(\vec{v}) + \epsilon.$$

There exists I such that if $i \geq I$, then

$$\tan^{-1} \frac{y_0}{x_0} - \alpha < \tan^{-1} \frac{y_i}{x_i} < \tan^{-1} \frac{y_0}{x_0} + \alpha.$$

Choose α_i such that each α_i -cone around \vec{v}_i for $i \geq I$ is completely contained in the α -cone around \vec{v} . Hence

$$\begin{aligned} h^c(\vec{v}_i) &\leq \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in C_{\alpha_i}^n(\vec{v}_i)} P_{i,j} \right) \\ &\leq \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in C_\alpha^n(\vec{v}_i)} P_{i,j} \right) \\ &\leq h^c(\vec{v}) + \epsilon. \end{aligned}$$

We have

$$\overline{\lim} h^c(\vec{v}_i) \leq h^c(\vec{v})$$

COROLLARY 2. If $h^c(\vec{v}) = h(\vec{v})$, then $h(\vec{v})$ is upper semi-continuous. In particular, if a Z^2 -action is generated by a block map, then the directional entropy is upper semi-continuous.

Proof. It is known that if a Z^2 -action is generated by a block map, then $h^c(\vec{v}) = h(\vec{v})$ [Pa2].

LEMMA 3. Given $\epsilon > 0$, there exists K such that if $m_1 \geq m_2 \geq K$, then for sufficiently large n ,

$$\frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_1}^n} P_{i,j} \right) \leq \frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_2}^n} P_{i,j} \right) + 2\epsilon.$$

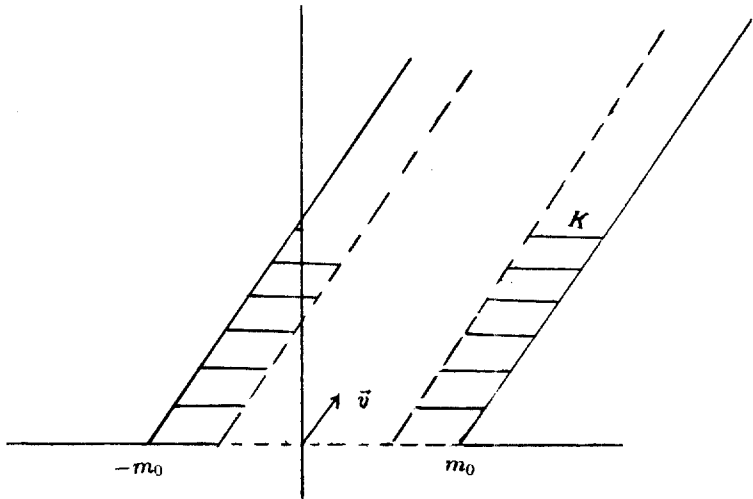
Proof. Clearly we have

$$\frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_1}^n} P_{i,j} \right) \geq \frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_2}^n} P_{i,j} \right).$$

If $y \neq 0$, then by scaling, we may assume that $y = 1$. Hence $[ny] = n$. Choose K_0 such that $\sum_{k > K_0} H(P_{0,1} | \bigvee_{i=-k}^k P_{i,0}) < \varepsilon$. Depending on the given vector \vec{v} , there exists $K \geq K_0$ (independent of m_0) such that for all j ,

$$\begin{aligned} & H \left(\bigvee_{-m_0+jx \leq i \leq m_0+jx} P_{i,j} \mid \bigvee_{-m_0+(j-1)x \leq i \leq m_0+(j-1)x} P_{i,j-1} \right) \\ & \leq H \left(\bigvee_{-m_0+jx \leq i \leq -m_0+jx+K} P_{i,j} \mid \bigvee_{m_0+jx-K \leq i \leq m_0+jx} P_{i,j} \right) \\ & \quad + H \left(\bigvee_{-m_0+(j-1)x \leq i \leq m_0+(j-1)x} P_{i,j} \right) + \varepsilon. \end{aligned}$$

(See Figure 1)



(Figure 1)

We have

$$\begin{aligned} & \frac{1}{n} H \left(\bigvee_{(i,j) \in R_m^n} P_{i,j} \right) \\ &= \frac{1}{n} H \left(\bigvee_{-m \leq i \leq m} P_{i,j} \right) \\ & \quad + \frac{1}{n} \sum_{j=1}^n H \left(\bigvee_{-m+jx \leq i \leq m+jx} P_{i,j} \mid \bigvee_{(i,\ell) \in R_m^{j-1}} P_{i,\ell} \right). \end{aligned}$$

We note that

$$\begin{aligned} & \frac{1}{n} \sum_{j=1}^n H \left(\bigvee_{-m+jx \leq i \leq m+jx} P_{i,j} \mid \bigvee_{(i,\ell) \in R_m^{j-1}} P_{i,\ell} \right) \\ &= \frac{1}{n} \sum_{j=1}^n H \left(\bigvee_{-m+jx \leq i \leq m+jx+K} P_{i,j} \mid \bigvee_{(i,\ell) \in R_m^{j-1}} P_{i,\ell} \right) \\ & \quad + \frac{1}{n} \sum_{j=1}^n H \left(\bigvee_{-m+jx+K < i \leq m+jx-K} P_{i,j} \mid \bigvee_{(i,\ell) \in R_m^{j-1}} \right. \\ & \quad \left. P_{i,\ell} \bigvee_{-m+jx \leq i \leq -m+jx+K} P_{i,j} \right) \\ & \quad + \frac{1}{n} \sum_{j=1}^n H \left(\bigvee_{m+jx-K \leq i \leq m+jx} P_{i,j} \mid \bigvee_{(i,\ell) \in R_m^{j-1}} P_{i,\ell} \bigvee_{-m+jx \leq i \leq m+jx-K} P_{i,j} \right). \end{aligned}$$

We denote the first, second and the third part of the right hand side of the above equation by $\eta(1, m)$, $\eta(2, m)$ and $\eta(3, m)$ respectively. When we compare $\frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_1}^n} P_{i,j} \right)$ and $\frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_2}^n} P_{i,j} \right)$, we have the following.

- (i) $\frac{1}{n} H \left(\bigvee_{-m_1 \leq i \leq m_1} P_{i,0} \right) - \frac{1}{n} H \left(\bigvee_{-m_2 \leq i \leq m_2} P_{i,0} \right) \leq \frac{2(m_1 - m_2)}{n} H(P_{0,0})$.
- (ii) By translating the partitions by $T^{-(m_1 - m_2)}$, it is easy to see that $\eta(1, m_1) \leq \eta(1, m_2)$.
- (iii) Similarly it is easy to see that $\eta(3, m_1) \leq \eta(3, m_2)$.
- (iv) $0 \leq \eta(2, m_1), \eta(2, m_2) \leq \varepsilon \quad \forall m_1, m_2 \geq K$.

Hence if we choose n large enough so that

$$\frac{2(m_1 - m_2)}{n} H(P_{0,0}) < \varepsilon,$$

then we have the claim.

If $y=0$, then clearly we have

$$\begin{aligned} & \frac{1}{n} H \left(\bigvee_{(i,j) \in R_{m_1}^n} P_{i,j} \mid \bigvee_{(i,j) \in R_{m_2}^n} P_{i,j} \right) \\ & \leq \frac{1}{n} H \left(\bigvee_{\substack{m_2 \leq j \leq m_1 \\ -m_1 \leq j \leq -m_2}} \bigvee_{0 \leq i < K} P_{i,j} \right) + \varepsilon \\ & = \frac{2K}{n} (m_1 - m_2) H(P_{0,0}) + \varepsilon < 2\varepsilon. \end{aligned}$$

THEOREM 4. *If S satisfies the condition that*

$$\sum_{k=0}^{\infty} H \left(P_{0,1} \mid \bigvee_{i=-k}^k P_{i,0} \right) < \infty,$$

then we have $h^c(\vec{v}) = h(\vec{v})$.

Proof. Since the proof is almost the same as that of theorem 1 in [P2], we will briefly sketch the main differences. In the case of $y \neq 0$, by scaling we may assume $y=1$. Given $\varepsilon > 0$. K_0 and K are chosen as in Lemma 3. Note that for all $m \geq K$, we have

$$\begin{aligned} H^m(\vec{v}) &= \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{(i,j) \in R_m^n} P_{i,j} \right) \\ &\leq \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{j=0}^{n-1} \bigvee_{i=-K+jx}^{K+jx} P_{i,j} \right) + \varepsilon \\ &= H^K(\vec{v}) + \varepsilon. \end{aligned}$$

Since $h(\vec{v}) = \lim_{m \rightarrow \infty} H^m(\vec{v})$,

$$H^K(\vec{v}) \leq h(\vec{v}) \leq H^K(\vec{v}) + \varepsilon.$$

Since we always have $h^c(\vec{v}) \geq h(\vec{v})$, we need to show that $h^c(\vec{v}) - h(\vec{v})$ is arbitrarily small. Given $\varepsilon > 0$, choose n_0 such that if $n \geq n_0$, then

$$\left| \frac{1}{n} H \left(\bigvee_{(i,j) \in R_K^n} P_{i,j} \right) - h(\vec{v}) \right| < 2\varepsilon.$$

We choose θ sufficiently small and $n(\geq n_0)$ sufficiently large so that

- (i) $h^c(\vec{v}) - 2\varepsilon \leq \frac{1}{n} H \left(\bigvee_{(i,j) \in C_\theta^n} P_{i,j} \right) \leq h^c(\vec{v}) + 2\varepsilon$
- (ii) $(x_{-\theta} - x_\theta)H(P_{0,0}) < \varepsilon$.
- (iii) $\frac{1}{n} H \left(\bigvee_{(i,j) \in C_\theta^n} P_{i,j} \right) \geq \frac{1}{n} H \left(\bigvee_{(i,j) \in R_K^n} P_{i,j} \right)$

We compute

$$\begin{aligned} & h^c(\vec{v}) - h(\vec{v}) \\ & \leq \left(\frac{1}{n} H \left(\bigvee_{(i,j) \in C_\theta^n} P_{i,j} \right) + \varepsilon \right) - \left(\frac{1}{n} H \left(\bigvee_{(i,j) \in R_K^n} P_{i,j} \right) - 2\varepsilon \right) \\ & \leq \frac{1}{n} \left(H \left(\bigvee_{(i,j) \in C_\theta^n} P_{i,j} \right) - H \left(\bigvee_{(i,j) \in R_K^n} P_{i,j} \right) \right) + 4\varepsilon, \\ & \quad \text{where } L = \frac{1}{2}(x_{-\theta} - x_\theta)n \\ & \leq \frac{2}{n}(L - K)H(P_{0,0}) + 4\varepsilon \\ & < \frac{1}{n}(x_{-\theta} - x_\theta)nH(P_{0,0}) + 4\varepsilon \\ & < 5\varepsilon \end{aligned}$$

Hence we have $h^c(\vec{v}) = h(\vec{v})$.

If $y=0$, then by choosing θ small enough so that $\frac{1}{\tan \theta} > K$, it is easy to see that $h^c(\vec{v}) = h(\vec{v})$.

THEOREM 5. *If S is a finitary code with finite expected code length, then $h(\vec{v})$ is upper semi-continuous.*

Proof. It is enough to show that S satisfies the condition

$$\sum_{k=0}^{\infty} H \left(P_{0,1} \mid \bigvee_{i=-k}^k P_{i,0} \right) < \infty.$$

We let $F_k = \{x: x_{[-k,k]}$ uniquely determines the 0^{th} coordinate of $Sx\}$ and let $E_k = F_k - \bigcup_{i=0}^{k-1} F_i$. Note that E'_k 's are disjoint and E_k is a union of the atoms of the partition $Q_k = \bigvee_{i=-k}^k P_{i,0} = \{Q_{k,0}, \dots, Q_{k,\ell_k-1}\}$. Hence F_k is a union of atoms of the partition Q_k . Let L denote the number of atoms of the partition $P_{0,1} = \{R_0, \dots, R_{L-1}\}$. Since S is a finitary code with finite expected code length, we have

$$\sum_{k=0}^{\infty} (2k + 1)\mu E_k < \infty.$$

We compute

$$\begin{aligned} & \sum_{k=0}^{\infty} H \left(P_{0,1} \mid \bigvee_{i=-k}^k P_{i,0} \right) \\ &= \sum_{k=0}^{\infty} H(P_{0,1} \mid Q_k) \\ &= \sum_{k=0}^{\infty} \sum_{j=0}^{\ell_k-1} \mu Q_{k,j} \left(\sum_{i=0}^{L-1} \frac{\mu(R_i \cap Q_{k,j})}{\mu Q_{k,j}} \log \frac{\mu(R_i \cap Q_{k,j})}{\mu Q_{k,j}} \right) \\ &\leq \sum_{k=0}^{\infty} \sum_{\substack{j=0 \\ Q_{k,j} \notin F_k}}^{\ell_k-1} \mu Q_{k,j} (\log L) \\ &= \sum_{k=0}^{\infty} \log L \sum_{\substack{j=0 \\ Q_{k,j} \notin F_k}}^{\ell_k-1} \mu Q_{k,j} \\ &= \sum_{k=0}^{\infty} \log L (1 - \mu F_k) \\ &= \log L \sum_{k=0}^{\infty} (1 - \mu F_k) \\ &= \log L \sum_{k=0}^{\infty} \left(1 - \sum_{\ell=0}^k \mu E_{\ell} \right) \\ &= \log L \left(\lim_{k \rightarrow \infty} ((k + 1) - (k + 1)(\mu E_0 + \mu E_1 + \dots + \mu E_k)) + \sum_{\ell=1}^{k-1} \ell \mu E_{\ell} \right) \\ &= \log L \lim_{k \rightarrow \infty} \left(k(1 - \mu F_{k-1}) + \sum_{\ell=1}^{k-1} \ell \mu E_{\ell} \right) \end{aligned}$$

$$\begin{aligned}
&= \log L \left(\sum_{\ell=1}^{\infty} \ell \mu E_{\ell} + \lim_{k \rightarrow \infty} k \mu F_{k-1}^c \right) \\
&\leq \log L \left(\sum_{\ell=1}^{\infty} \ell \mu E_{\ell} + \lim_{k \rightarrow \infty} k \left(\sum_{\ell=k}^{\infty} \mu E_{\ell} \right) \right) \\
&= \log L \left(\sum_{\ell=1}^{\infty} \ell \mu E_{\ell} + \lim_{k \rightarrow \infty} \sum_{\ell=k}^{\infty} \ell \mu E_{\ell} \right) \\
&= \log L \left(\sum_{\ell=1}^{\infty} \ell \mu E_{\ell} \right) < \infty
\end{aligned}$$

This completes our proof.

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