

REPRESENTATIONS OF THE CONNECTION IN $*g$ -SEMISYMMETRIC MANIFOLD

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I. INTRODUCTION

Let X_n be an n -dimensional generalized Riemannian space referred to a real coordinate system x^ν , which obeys coordinate transformation $x^\nu \longleftrightarrow x^{\nu'}$ for which

$$(1-1) \quad \det \left(\frac{\partial x^{\nu'}}{\partial x^\nu} \right) \neq 0.$$

The space X_n is endowed with a general real non-symmetric tensor $g_{\lambda\mu}$ which may be split into its symmetric part $h_{\lambda\mu}$ and skew-symmetric part $k_{\lambda\mu}^{(*)}$:

$$(1-2) \quad g_{\lambda\mu} = h_{\lambda\mu} + k_{\lambda\mu},$$

where

$$(1-3) \quad \mathfrak{g} \stackrel{\text{def}}{=} \det(g_{\lambda\mu}) \neq 0, \quad \mathfrak{h} \stackrel{\text{def}}{=} \det(h_{\lambda\mu}) \neq 0.$$

The algebraic structure is imposed on X_n by the basic real tensor $*g^{\lambda\nu}$ defined by

$$(1-4) \quad g_{\lambda\mu} *g^{\lambda\nu} = g_{\mu\lambda} *g^{\nu\lambda} = \delta_\mu^\nu$$

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(*)Throughout the present paper, all Greek indices take the values $1, 2, \dots, n$ and follow the summation convention.

in virtue of (1-3). It may be decomposed into its symmetric part $*h^{\lambda\nu}$ and skew-symmetric part $*k^{\lambda\nu}$:

$$(1-5) \quad *g^{\lambda\nu} = *h^{\lambda\nu} + *k^{\lambda\nu}.$$

Since $\det(*h^{\lambda\nu}) \neq 0$, we may define a unique tensor $*h_{\lambda\mu}$ by

$$(1-6) \quad *h_{\lambda\mu} *h^{\lambda\nu} = \delta_{\mu}^{\nu}.$$

which together with $*h^{\lambda\nu}$ will serve for raising and/or lowering indices of all tensors defined in X_n in the usual manner.

The space X_n is connected by a general real connection $\Gamma_{\lambda}^{\nu\mu}$ with the following transformation rules :

$$(1-7) \quad \Gamma_{\lambda'}^{\nu'\mu'} = \frac{\partial x^{\nu'}}{\partial x^{\alpha}} \left(\frac{\partial x^{\beta}}{\partial x^{\lambda'}} \frac{\partial x^{\gamma}}{\partial x^{\mu'}} \Gamma_{\beta}^{\alpha\gamma} + \frac{\partial^2 x^{\alpha}}{\partial x^{\lambda'} \partial x^{\mu'}} \right)$$

It may also be decomposed into its symmetric part $\Lambda_{\lambda}^{\nu\mu}$ and its skew-symmetric part $S_{\lambda\mu}^{\nu}$, called the torsion tensor of $\Gamma_{\lambda}^{\nu\mu}$:

$$(1-8) \quad \Gamma_{\lambda}^{\nu\mu} = \Lambda_{\lambda}^{\nu\mu} + S_{\lambda\mu}^{\nu}$$

The Einstein condition for defining the connection $\Gamma_{\lambda}^{\nu\mu}$ is given by

$$(1-9a) \quad D_{\omega} *g^{\lambda\mu} = -2S_{\omega\alpha}^{\mu} *g^{\lambda\alpha},$$

or equivalently, [4],

$$(1-9b) \quad D_{\omega} g_{\lambda\mu} = 2S_{\omega\mu}^{\alpha} g_{\lambda\alpha},$$

which gives X_n the differential geometric structure on the geometry of Einstein's unified field theory. Here D_{ω} denotes the symbol of the covariant derivative with respect to $\Gamma_{\lambda}^{\nu\mu}$. A connection $\Gamma_{\lambda}^{\nu\mu}$ is said to be semi-symmetric if its torsion tensor is of the form

$$(1-10) \quad S_{\lambda\mu}^{\nu} = 2\delta_{[\lambda}^{\nu} X_{\mu]}$$

for an arbitrary nonnull vector X_μ . The n -dimensional $*g$ -semi-symmetric manifold is the space X_n , on which the differential structure is imposed by $*g^{\lambda\nu}$ through a semi-symmetric connection $\Gamma_\lambda^\nu{}_\mu$, which satisfies the Einstein's condition. In what follows, we denote the n -dimensional $*g$ -semi-symmetric manifold by X_n .

II. PRELIMINARIES

We shall introduce the following abbreviations:

$$(2-1a) \quad {}^{(0)}*k_\lambda{}^\nu = \delta_\lambda{}^\nu, \quad {}^{(p)}*k_\lambda{}^\nu = {}^{(p-1)}*k_\lambda{}^\alpha *k_\alpha{}^\nu, \quad (p = 1, 2, \dots)$$

$$(2-1b) \quad Y_\lambda^{(p)} = {}^{(p)}*k_\lambda{}^\alpha Y_\alpha, \quad (p = 0, 1, 2, \dots).$$

for arbitrary vector Y_λ . The following quantities will be used :

$$(2-2a) \quad *g = \det(*g_{\lambda\mu}), \quad *h = \det(*h_{\lambda\mu}), \quad *k = \det(*k_{\lambda\mu})$$

$$(2-2b) \quad *g = \frac{*g}{*h}, \quad *k = \frac{*k}{*h}$$

$$(2-2c) \quad \sigma = \begin{cases} 0, & \text{if } n \text{ is even} \\ 1, & \text{if } n \text{ is odd} \end{cases}$$

$$(2-2d) \quad K_p = *k_{[\alpha_1}{}^{\alpha_1} *k_{\alpha_2}{}^{\alpha_2} \dots *k_{\alpha_p}]^{\alpha_p}, \quad (p = 0, 1, 2, \dots)$$

$$(2-2e) \quad {}^{(p)}B^{\lambda\nu} = {}^{(p)}*k_\alpha{}^\lambda B^{\alpha\nu},$$

where $B^{\lambda\nu}$ is an arbitrary symmetric tensor.

It may be easily shown that

$$(2-3a) \quad {}^{(p)}*k_{\lambda\mu} = (-1)^p \cdot {}^{(p)}*k_{\mu\lambda}, \quad (p = 0, 1, 2, \dots)$$

$$(2-3b) \quad \begin{cases} K_0 = 1, & K_n = *k, & \text{if } n \text{ is even} \\ K_p = 0, & & \text{if } p \text{ is odd} \end{cases}$$

$$(2-3c) \quad *g = \sum_{s=0}^{n-\sigma} K_s,$$

$$(2-3d) \quad \sum_{s=0}^{n-\sigma} K_s {}^{(n-s)}*k_\lambda{}^\mu = 0.$$

THEOREM 1. If there exists a semisymmetric connection $\Gamma_{\lambda}^{\nu}{}_{\mu}$ in X_n , it must of the form

$$(2-4a) \quad \Gamma_{\lambda}^{\nu}{}_{\mu} = {}^* \{ \lambda^{\nu}{}_{\mu} \} + 2\delta_{[\lambda}{}^{\nu} X_{\mu]} + U_{\lambda\mu}^{\nu},$$

where

$$(2-4b) \quad U_{\lambda\mu}^{\nu} \stackrel{def}{=} -{}^* h_{\lambda\mu} X^{\nu(1)}.$$

proof. See [3].

In the next Theorem we shall assume that the symmetric real tensor $A_{\lambda\mu}$ defined by

$$(2-5) \quad A_{\lambda\mu} \stackrel{def}{=} (1-n) {}^* h_{\lambda\mu} + (2) {}^* k_{\lambda\mu}$$

is of rank n , so that there exists a unique symmetric inverse tensor $B^{\lambda\nu} = B^{\nu\lambda}$ satisfying

$$(2-6) \quad A_{\lambda\mu} B^{\lambda\nu} = \delta_{\mu}{}^{\nu}.$$

THEOREM 2. There exists a unique semi-symmetric connection $\Gamma_{\lambda}^{\nu}{}_{\mu}$ in X_n if and only if there is a vector X_{λ} such that

$$(2-7) \quad \nabla_{\omega} {}^* k_{\lambda\mu} = 2 {}^* h_{\omega[\lambda} X_{\mu]} + 2 {}^* k_{\omega[\mu} {}^* k_{\lambda]}{}^{\alpha} X_{\alpha}.$$

The vector X_{λ} satisfying (2-7) is unique and may be given by

$$(2-8) \quad X_{\lambda} = B_{\lambda}{}^{\alpha} \nabla_{\beta} {}^* k_{\alpha}{}^{\beta}.$$

proof. See [3].

We shall need several properties of the vector X_{λ} , given by (2-8), and the vectors

$$S_{\lambda} \stackrel{def}{=} S_{\lambda\alpha}{}^{\alpha}, \quad U_{\lambda} \stackrel{def}{=} U^{\alpha}{}_{\lambda\alpha},$$

and some useful recurrence relations.

THEOREM 3. In X_n , the following recurrence relations hold :

$$(2-9a) \quad {}^{(p)}B^{\lambda\nu} = (n-1)^{(p-2)}B^{\lambda\nu} + {}^{(p-2)*}k^{\lambda\nu},$$

$$(2-9b) \quad {}^{(p)}X_\lambda = (n-1) {}^{(p-2)}X_\lambda + {}^{(p-2)}Y_\lambda, \quad (p = 2, 3, 4, \dots)$$

where

$$(2-9c) \quad Y_\lambda \stackrel{def}{=} \nabla_\alpha {}^*k_\lambda^\alpha.$$

proof. Substituting (2-5) into (2-6) and multiplying ${}^{(p-2)*}k^{\lambda\mu}$, we obtain (2-9)a. Similarly we obtain (2-9)b from (2-8).

THEOREM 4. In X_n , the following recurrence relations hold :

$$(2-10a) \quad \sum_{s=0}^{n-\sigma} K_s {}^{(n-s)}B^{\lambda\nu} = 0,$$

$$(2-10b) \quad \sum_{s=0}^{n-\sigma} K_s {}^{(n-s)}X_\lambda = 0.$$

proof. These are the direct consequences of the relations (2-2e), (2-3d) and (2-1b).

THEOREM 5. In X_n , the following relations hold :

$$(2-11a) \quad X_\lambda = \frac{1}{1-n} S_\lambda, \quad U_\lambda = -{}^*k_\lambda^\alpha X_\alpha = -X_\lambda^{(1)}$$

$$(2-11b) \quad {}^{(p)}X_\lambda = -{}^{(p-1)}U_\lambda, \quad {}^{(p)}S_\lambda = (1-n) {}^{(p)}X_\lambda = (n-1) {}^{(p-1)}U_\lambda, \quad (p = 1, 2, \dots)$$

$$(2-11c) \quad U_\omega = -\frac{1}{2} \partial_\omega \ln {}^*g \stackrel{def}{=} -Z_\omega.$$

proof. (2-11a) follows from (1-10) and (2-4b). (2-11b) may be easily from (2-11a) and (2-1b). In order to prove the relation (2-11c) use (1-4) and (1-6) to obtain

$$(*) \quad \ln \mathfrak{g} = -\ln {}^* \mathfrak{g} + 2 \ln {}^* \mathfrak{h}$$

On the other hand, multiply (1-9b) by ${}^* g^{\lambda\nu}$ and put $\nu = \mu$. Then we have

$${}^* g^{\lambda\nu} D_\omega g_{\lambda\nu} = \mathfrak{g}^{-1} D_\omega \mathfrak{g} = 2S_\omega,$$

from which we have

$$\begin{aligned} 0 &= \mathfrak{g}^{-1} D_\omega \mathfrak{g} - 2S_\omega \\ &= \mathfrak{g}^{-1} (\partial_\omega \mathfrak{g} - 2\Gamma_\alpha^\alpha{}_\omega \mathfrak{g}) - 2S_\omega \\ &= \partial_\omega \ln \mathfrak{g} - 2({}^* \{ \alpha^\alpha{}_\omega \} - S_\omega + U_\omega) - 2S_\omega \\ (**) \quad &= \partial_\omega \ln \mathfrak{g} - \partial_\omega \ln {}^* \mathfrak{h} - 2U_\omega. \end{aligned}$$

The relation (2-11c) follows immediately from (*) and (**).

We shall need the following scalar \bar{K}_s :

$$(2-12) \quad \bar{K}_0 \stackrel{\text{def}}{=} 0, \quad \bar{K}_s \stackrel{\text{def}}{=} (n-1)\bar{K}_{s-2} + K_{s-2}, \quad (s = 2, 4, 6, \dots, n+2-\sigma)$$

Direct calculation shows that

$$(2-13) \quad \bar{K}_{n+2-\sigma} = K_0 M^{n-\sigma} + K_2 M^{n-2-\sigma} + \dots + K_{n-\sigma}, \quad M \stackrel{\text{def}}{=} \sqrt{n-1}.$$

III. THE VECTOR X_λ

THEOREM 6. (The first representation for X_λ) The tensor $B^{\lambda\nu}$ and the vector X_λ in X_n may be given by

$$(3-1) \quad \{1 + (n-2)\sigma\} B^{\lambda\nu} = -\frac{1}{\bar{K}_{n+2-\sigma}} \sum_{s=0}^{n-\sigma} \bar{K}_s \{({}^{n-s+\sigma} k^{\lambda\nu} - \sigma {}^* h^{\lambda\nu})\},$$

$$(3-2) \quad \{1 + (n-2)\sigma\} X_\lambda = -\frac{1}{\bar{K}_{n+2-\sigma}} \sum_{s=0}^{n-\sigma} \bar{K}_s \{({}^{n-s+\sigma} Y_\lambda - \sigma Y_\lambda)\},$$

where the vector Y_λ is defined by (2-9c).

proof. Substitute for ${}^{(n)}B^{\lambda\nu}$ into (2-10a) from (2-9a) to obtain

$$(3-3a) \quad \bar{K}_2^{(n-2)*} k^{\lambda\nu} + \bar{K}_4^{(n-2)} B^{\lambda\nu} + K_4^{(n-4)} B^{\lambda\nu} + \dots + K_{n-\sigma}^{(\sigma)} B^{\lambda\nu} = 0.$$

Substituting again for ${}^{(n-2)}B^{\lambda\nu}$ into (2-10a) from (2-9a), we have

$$(3-3b) \quad \bar{K}_2^{(n-2)*} k^{\lambda\nu} + \bar{K}_4^{(n-4)*} k^{\lambda\nu} + \bar{K}_6^{(n-6)} B^{\lambda\nu} + K_6^{(n-6)} B^{\lambda\nu} + \dots + K_{n-\sigma}^{(\sigma)} B^{\lambda\nu} = 0.$$

After $\frac{n-\sigma}{2}$ steps of successive repeated substitutions for ${}^{(n)}B^{\lambda\nu}$, we have

$$(3-3c) \quad \bar{K}_2^{(n-2)*} k^{\lambda\nu} + \dots + \bar{K}_{n-2-\sigma}^{(2+\sigma)*} k^{\lambda\nu} + \bar{K}_{n-\sigma}^{(\sigma)*} k^{\lambda\nu} + \bar{K}_{n+2-\sigma}^{(\sigma)} B^{\lambda\nu} = 0.$$

Now multiply ${}^{(\sigma)}k_{\nu}{}^{\mu}$ to both sides of (3-3c) to obtain

$$(3-3d) \quad \bar{K}_2^{(n-2+\sigma)*} k^{\lambda\mu} + \dots + \bar{K}_{n-2-\sigma}^{(2+2\sigma)*} k^{\lambda\mu} + \bar{K}_{n-\sigma}^{(2\sigma)*} k^{\lambda\mu} + \bar{K}_{n+2-\sigma}^{(2\sigma)} B^{\lambda\mu} = 0.$$

Substituting

$${}^{(2\sigma)}B^{\lambda\mu} = \{1 + (n-2)\sigma\} B^{\lambda\mu} + \sigma^* h^{\lambda\mu}$$

into (3-3d), we have (3-1). The relation (3-2) may be easily obtained from (3-1) and (2-8).

THEOREM 7. (The second representation for X_λ) The vector X_λ in X_n may be given by

$$(3-4) \quad \{1 + (n-2)\sigma\} X_\lambda = -\frac{1}{K_{n-\sigma}} \sum_{s=0}^{n-\sigma} K_s \left\{ \begin{matrix} (n-1-s+\sigma) \\ Z_\lambda \end{matrix} - \sigma Y_\lambda \right\}$$

under the condition $K_{n-\sigma} \neq 0$.

proof. Multiply ${}^{(\sigma)}k_\mu^\lambda$ to both sides of (2-10b). Then we have

$$(3-5) \quad K_0 \overset{(n+\sigma)}{X_\lambda} + K_2 \overset{(n-2+\sigma)}{X_\lambda} + \cdots + K_{n-2-\sigma} \overset{(2+2\sigma)}{X_\lambda} + K_{n-\sigma} \overset{(2\sigma)}{X_\lambda} = 0.$$

Substituting

$$\overset{(2\sigma)}{X_\lambda} = \{1 + (n-2)\sigma\} X_\lambda + \sigma Y_\lambda$$

into (3-5) and using (2-11b,c), we have (3-4).

THEOREM 8. (*The third representation for X_λ*) We have

$$(3-6) \quad X_\lambda = \frac{1}{n-1} \left\{ \frac{1}{2} {}^*k_\lambda^\alpha \partial_\alpha \ln {}^*g - \nabla_\alpha {}^*k_\lambda^\alpha \right\}.$$

proof. The relation (3-6) follows from the relation (2-8), (2-11a,c).

REMARK. Now that we have obtained the vector X_λ in terms of ${}^*g^{\lambda\nu}$ in (3-2), (3-4) and (3-6), it is possible for us to determine the semi-symmetric connection $\Gamma_\lambda^\nu{}_\mu$ in terms of ${}^*g^{\lambda\nu}$ by only substituting for X_λ into (2-4a).

References

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