

## GLOBAL FORM OF A COMPLETE HYPERSURFACE OF $S^n \times S^n$

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### 0. Introduction

In 1973, K. Yano[1] studied the differential geometry of  $S^n \times S^n$  and introduced the structure equations of real hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$ .

In 1982, S.-S.Eum, U-H.Ki and Y.H.Kim [2] researched partially real hypersurfaces of  $S^n \times S^n$  by using the concept of  $k$ -invariance.

In [3], the author found that the necessary and sufficient condition for a hypersurface of  $S^n \times S^n$  being  $k$ -antiholomorphic and investigated its global properties

The purpose of the present paper is devoted to characterization of the global form of a complete hypersurface of  $S^n \times S^n$ .

In section 1, we recall the structure equations of hypersurfaces of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$ .

In section 2, we have global forms of a complete hypersurface of  $S^n \times S^n$  under some algebraic conditions.

### 1. Structure equations of hypersurfaces of $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$

Let  $M$  be a hypersurface immersed isometrically in  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  as a submanifold of codimension 2 of  $(2n+2)$ -dimensional Euclidean space or real hypersurface of  $(2n+1)$ -dimensional unit sphere  $S^{2n+1}(1)$ . And we suppose that  $M$  is covered by the system of coordinate neighborhoods  $\{V; \bar{x}^a\}$ , where here and in the sequel, the indices  $a, b, c, d, \dots$  run over the range  $\{1, 2, \dots, 2n-1\}$ .

Since the immersion  $\iota : M \rightarrow S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  is isometric, from the  $(f, g, u, v, \lambda)$ -structure defined on  $S^n \times S^n$ , we get the so-called  $(f, g, u, v, w, \lambda, \mu, \nu)$ -structure [2] given by

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$$(1.1) \quad f_b^e f_e^a = -\delta_b^a + u_b u^a + v_b v^a + w_b w^a,$$

$$(1.2) \quad \begin{aligned} f_e^a u^e &= -\lambda v^a + \mu w^a, \\ f_e^a v^e &= \lambda u^a + \nu w^a, \\ f_e^a w^e &= -\mu u^a - \nu v^a \end{aligned}$$

or equivalently,

$$(1.3) \quad \begin{aligned} u_e f_a^e &= \lambda v_a - \mu w_a, v_e f_a^e = -\lambda u_a - \nu w_a, w_e f_a^e = \mu u_a + \nu v_a, \\ u_e u^e &= 1 - \lambda^2 - \mu^2, u_e v^e = -\mu\nu, u_e w^e = -\lambda\nu, \\ v_e v^e &= 1 - \lambda^2 - \nu^2, v_e w^e = \lambda\mu, \\ w_e w^e &= 1 - \mu^2 - \nu^2 \end{aligned}$$

where  $u_a$ ,  $v_a$  and  $w_a$  are 1-forms associated with  $u^a$ ,  $v^a$  and  $w^a$  respectively given by  $u_a = u^b g_{ba}$ ,  $v_a = v^b g_{ba}$  and  $w_a = w^b g_{ba}$ , and  $f_{ba} = f_b^c g_{ca}$  is skew-symmetric. Moreover, we obtain

$$(1.4) \quad \nabla_c \lambda = -2v_c, \nabla_c \mu = w_c - \lambda k_c - l_{ce} u^e, \nabla_c \nu = k_{ce} w^e - l_{ce} v^e,$$

Finally, we introduce the followings.

REMARK [4]. If  $\lambda^2 + \mu^2 + \nu^2 = 1$  on the hypersurface  $M$ , we see that  $\mu = 0$ ,  $\nu = \text{constant}(\neq 0)$ ,  $v_c = 0$  and  $\alpha = 0$ . And if the function  $\lambda$  vanishes on some open set, then we have  $v_c = 0$  and  $\mu = 0$ . Moreover the 4-form  $u_b$  never vanishes on an open set in  $M$ , in fact, if 1-form  $u_b$  is zero on an open set in  $M$ , then  $f_{cb} = 0$ , which contradict  $n > 1$ .

LEMMA 1.1 [3]. Let  $M$  be a hypersurface satisfying  $k_{ce} f_b^e = k_{be} f_c^e$  of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$ . Then we have

$$\lambda^2 + \mu^2 + \nu^2 = 1 \text{ or } \mu^2 + \nu^2 + \alpha\mu\nu = 0$$

on  $M$ .

LEMMA 1.2 [3]. Under the same assumptions as those stated in Lemma 1.1,  $M$  is  $k$ -antiholomorphic if and only if  $\lambda^2 + \mu^2 = 1$  holds at every point of  $M$ .

THEOREM A [3]. Let  $M$  be a hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  with  $(f, g, u, v, w, \lambda, \mu, \nu)$ -structure satisfying  $\lambda^2 + \mu^2 + \nu^2 = 1$ . If  $M$  is a minimal hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$ , then  $M$  is Sasakian  $C$ -Einstein manifold.

THEOREM B [3]. Let  $M$  be a  $k$ -antiholomorphic hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying  $k_c^e f_e^a + f_c^e k_e^a = 0$ . If  $M$  is minimal (or the square of length of the second fundamental tensor of  $M$  is not greater than  $2(n-1)$  at every point of  $M$ ), then  $M$  as a submanifold of codimension 3 of a Euclidean  $(2n+2)$ -space, is an intersection of complex cone with generator  $C$  and a  $(2n+1)$ -dimensional sphere  $S^{2n+1}(1)$ .

THEOREM C [5]. If  $M$  is a  $k$ -invariant hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying

$$l_c^e f_e^a + f_c^e l_e^a = 0,$$

then  $M$  is totally geodesic. Moreover,  $M$  is complete and  $M$  is  $S^{n-1} \times S^n$ .

THEOREM D [5]. Let  $M$  be a  $k$ -invariant hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying

$$l_c^e f_e^a - f_c^e l_e^a = 0.$$

Then  $M$  is totally geodesic. Moreover, the hypersurface is complete and  $M$  is  $S^{n-1} \times S^n$ .

## 2. Global form of a complete hypersurface

In this section, we consider a hypersurface  $M$  of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  such that

$$k_c^e f_e^a + f_c^e k_e^a = 0, \quad l_c^e f_e^a + f_c^e l_e^a = 0$$

hold on  $M$ , or equivalently

$$(2.1) \quad k_{ce}f_b^e = k_{be}f_c^e$$

and

$$(2.2) \quad l_{ce}f_b^e = l_{be}f_c^e.$$

Now, transvecting (2.1) with  $f_a^b$  and using (1.1), we find

$$l_{ce}(-\delta_a^e + u_a u^e + v_a v^e + w_a w^e) = l_{be}f_c^e f_a^b,$$

from which, taking the skew-symmetric part,

$$(2.3) \quad (l_{ce}u^e)u_b - (l_{be}u^e)u_c + (l_{ce}v^e)v_b - (l_{be}v^e)v_c + (l_{ce}w^e)w_b - (l_{be}w^e)w_c = 0.$$

If we transvect  $l_{ce}f_b^e$  with  $f^{cb}$ , we get from (2.2)

$$(2.4) \quad l_c^c = l_{cb}u^c u^b + l_{cb}v^c v^b + l_{cb}w^c w^b$$

because of (1.1)

From our assumption (2.1) and section 3 of [3], we get

$$(2.5) \quad (1 - \mu^2 - \nu^2)k_c = \theta w_c, \quad (1 - \alpha^2)w_c = \theta k_c,$$

$$(2.6) \quad k_{ce}w^e = -\alpha w_c,$$

and

$$(2.7) \quad (\mu^2 + \nu^2)k_c + (\mu + \alpha\nu)v_c + (\nu + \alpha\mu)u_c = 0.$$

Thus, according to Lemma 1.1, we may only consider the following two cases in which

$$(2.8) \quad \lambda^2 + \mu^2 + \nu^2 = 1,$$

$$(2.9) \quad \mu^2 + \nu^2 + 2\alpha\mu\nu = 0.$$

In the first place, we consider the case in which  $\lambda^2 + \mu^2 + \nu^2 = 1$ , then by Remark, we have  $\alpha = 0, \mu = 0, \nu = \text{constant}(\neq 0)$  and  $v_c = 0$ .

So (2.7) is turned out to be  $u_c = -\nu k_c$ .

Substituting this into the second expression of (1.2) and remembering the fact that  $v_c = 0$  and  $\nu \neq 0$ , we get

$$(2.10) \quad w_c = \lambda k_c.$$

Therefore (1.4) with  $\mu = 0$  yields  $l_{cc}u^e = 0$  and hence  $l_{ce}k^e = 0$ .

If we transvect  $l_b^e$  to (2.10), then

$$l_{ce}w^e = 0.$$

Using these facts, the equation (2.4) gives  $l_c^e = 0$ , that is, the hypersurface is minimal.

According to Theorem A,  $M$  is, in this case, a minimal Sasakian  $\mathcal{C}$ -Einstein manifold.

Secondly, we consider the case in which  $\mu^2 + \nu^2 + 2\alpha\mu\nu = 0$ . Then as was already shown in section of [3], we have, in this case

$$\nu + \alpha\mu = 0, \quad \mu + \alpha\nu = 0,$$

which show that  $\mu^2 = \nu^2$ . So (2.7) implies

$$(2.11) \quad \mu k_c = 0.$$

If we suppose that the hypersurface is not  $k$ -invariant, then  $\mu = 0$  and hence  $\nu = 0$

Thus the second equation of (1.4) reduces to

$$(2.12) \quad l_{ce}u^e = (1 - \theta\lambda)w_c,$$

where we have used (2.5) with  $\mu = \nu = 0$ .

Since  $\nu$  vanishes in this case, the third equation of (1.4) becomes

$$(2.13) \quad l_{ce}v^e = -\alpha w_c$$

with the aid of (2.6).

Substituting (2.12) and (2.13) into (2.3), we find

$$(1 - \theta\lambda)(w_c u_b - w_b u_c) - \alpha(w_c w_b - w_b v_c) + (l_{ce} w^e) w_b - (l_{be} w^e) w_c = 0.$$

If we transvect this with  $w^c v^b$  and take account of (1.3) with  $\mu = \nu = 0$ , we obtain  $\lambda\alpha = 0$ , where we have used (2.13). Since  $\lambda$  can not be vanish because of Remark, we see that the function  $\alpha$  vanishes identically, therefore by Lemma 1.2  $\lambda^2 = 1$  and hence  $u_c = 0$ , which is contradictory. Thus it follows from (2.11) that the hypersurface is invariant. So, as in the proof of Theorem C,  $M$  is totally geodesic.

**THEOREM 2.1.** *Let  $M$  be a hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying*

$$k_c^e f_e^a + f_c^e k_e^a = 0, \quad l_c^e f_e^a + f_c^e l_e^a = 0.$$

*Then  $M$  is totally geodesic or a minimal Sasakian  $C$ -Einstein manifold.*

Combining Lemma 1.1, Theorem B and Theorem C, we have

**THEOREM 2.2.** *Let  $M$  be a complete hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying*

$$k_c^e f_e^a + f_c^e k_e^a = 0, \quad l_c^e f_e^a + f_c^e l_e^a = 0.$$

*Then  $M$  is  $S^n \times S^{n-1}$  or  $M$  as a submanifold of codimension 3 of Euclidean  $(2n + 2)$ -sphere is an intersection of a complex cone with generator  $C$  and a  $(2n + 1)$ -dimensional sphere  $S^{2n+1}(1)$ .*

According to Lemma 1.1, Theorem B and Theorem D, we have

**THEOREM 2.3.** *Let  $M$  be a complete hypersurface of  $S^n(1/\sqrt{2}) \times S^n(1/\sqrt{2})$  ( $n > 1$ ) satisfying*

$$k_c^e f_e^a + f_c^e k_e^a = 0, \quad l_c^e f_e^a + f_c^e l_e^a = 0.$$

*Then  $M$  is  $S^n \times S^{n-1}$ , or  $M$  as a submanifold of codimension 3 of a Euclidean  $(2n + 2)$ -space is an intersection of a complex cone with generator  $C$  and a  $(2n + 1)$ -dimensional sphere  $S^{2n+1}(1)$ , that is, a Brieskorn manifold  $B^{2n-1}$ .*

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