

## HYPERSURFACES SATISFYING $\Delta x = Rx + b$ IN $S_1^{n+1}$ AND IN $H^{n+1}$

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ABSTRACT. In this paper, we classify hypersurfaces  $M$  in  $S_1^{n+1}$  or in  $H^{n+1}$  satisfying  $\Delta x = Rx + b$ .

### 1. Introduction

Let  $E_1^{n+2}$  be the  $(n+2)$ -dimensional Minkowski space time with the standard flat metric given by

$$g = \sum_{i=1}^{n+1} dx_i^2 - dx_{n+2}^2,$$

where  $(x_1, x_2, \dots, x_{n+2})$  is a rectangular coordinate system of  $E_1^{n+2}$ . For a positive number  $r$  and a point  $c \in E_1^{n+2}$ , we denote by  $S_1^{n+1}(c, r)$  and  $H^{n+1}(c, -r)$ , the de Sitter space time and the hyperbolic space defined respectively by

$$S_1^{n+1}(c, r) = \{x \in E_1^{n+2} \mid \langle x - c, x - c \rangle = r^2\},$$

$$H^{n+1}(c, -r) = \{x \in E_1^{n+2} \mid \langle x - c, x - c \rangle = -r^2\},$$

where  $\langle \cdot, \cdot \rangle$  denotes the indefinite inner product on  $E_1^{n+2}$ . The point  $c$  is called the center of  $S_1^{n+1}(c, r)$  and  $H^{n+1}(c, -r)$  respectively. We simply denote  $S_1^{n+1}(0, 1)$  and  $H^{n+1}(0, -1)$  by  $S_1^{n+1}$  and  $H^{n+1}$ . In [3], the second

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author considered an isometric immersion  $x : M^n \rightarrow H^{n+1} \subset E_1^{n+2}$  of an  $n$ -dimensional Riemannian Manifold  $M^n$  satisfying

$$(*) \quad \Delta x = Rx + b,$$

where  $x = (x_1, x_2, \dots, x_{n+2})$ ,  $\Delta x = (\Delta x_1, \dots, \Delta x_{n+2})$ ,  $R$  is an  $(n + 2) \times (n + 2)$  constant matrix,  $b$  is a constant vector in  $E_1^{n+2}$  and  $\Delta$  is the Laplacian on  $M^n$ . He classified such immersions in case that  $b = 0$ . The analogous classification problem for hypersurfaces of Euclidean space, for hypersurfaces of the Minkowski space time, or for hypersurfaces of the unit sphere is studied by several authors and is completely solved [1,2,3,4,5]. The purpose of this paper is to study an isometric immersion  $x : M^n \rightarrow S_1^{n+1}(c, 1)$  (or  $H^{n+1}(c, -1) \subset E_1^{n+2}$ ) of an  $n$ -dimensional pseudo Riemannian (or Riemannian) manifold  $M^n$  satisfying  $(*)$  for a constant matrix  $R$  and a constant vector  $b$ . For given such an immersion  $x$ , consider the immersion  $y = x - c$ . Then  $\langle y, y \rangle = \pm 1$  and  $\Delta y = \Delta x = Rx + b'$  ( $b' = Rc + b$ ). So we may assume that  $M^n$  is immersed into  $S_1^{n+1}$  (or  $H^{n+1}$ ) by  $x$  without loss of generality. We will study under this assumption. Our results are:

**THEOREM 1.** *Let  $x : M^n \rightarrow S_1^{n+1} \subset E_1^{n+2}$  be an isometric immersion of an  $n$ -dimensional pseudo Riemannian manifold  $M^n$  satisfying  $(*)$  for a constant matrix  $R$  and a constant vector  $b$ . Then  $M^n$  is minimal in  $S_1^{n+1}$  or is an open part of one of the followings:*

- (1) a flat totally umbilical hypersurface  $N_1(a)$  of  $S_1^{n+1}$  defined by

$$N_1(a) = \{x \in S_1^{n+1} \mid \langle x, a \rangle = \text{nonzero constant}\}$$

for a constant vector  $a$  with  $\langle a, a \rangle = 0$ ;

- (2) a nonflat totally umbilical hypersurface  $S^n(c, r)$  (or  $S_1^n(c, r)$ ) of  $S_1^{n+1}$ ;
- (3) a product manifold  $S^k(0, r_1) \times S_1^{n-k}(0, r_2)$  in  $S_1^{n+1}$ ;
- (4) a product manifold  $S^k(0, r_1) \times H^{n-k}(0, -r_2)$  in  $S_1^{n+1}$ .

**THEOREM 2.** *Let  $x : M^n \rightarrow H^{n+1} \subset E_1^{n+2}$  be an isometric immersion of an  $n$ -dimensional Riemannian manifold  $M^n$  satisfying  $(*)$  for*

a constant matrix  $R$  and a constant vector  $b$ . Then  $M^n$  is minimal in  $H^{n+1}$  or is an open part of one of the followings:

- (1) a flat totally umbilical hypersurface  $N_1(a)$  of  $H^{n+1}$  defined by

$$N_1(a) = \{x \in H^{n+1} | \langle x, a \rangle = \text{nonzero constant}\}$$

for a constant vector  $a$  with  $\langle a, a \rangle = 0$ ;

- (2) a nonflat totally umbilical hypersurface  $S^n(c, r)$  (or  $H^n(c, -r)$ ) of  $H^{n+1}$ ;
- (3) a product manifold  $S^k(0, r_1) \times H^{n-k}(0, r_2)$  in  $H^{n+1}$ .

Since the proof of theorem2 is similar to that of theorem1, we will give only the proof of theorem1.

## 2. Preliminaries

Let  $x : M^n \rightarrow S_1^{n+1} \subset E_1^{n+2}$  be an isometric immersion of an  $n$ -dimensional pseudo Riemannian manifold  $M^n$ . Choose a local pseudo-orthonormal frame  $e_1, e_2, \dots, e_{n+2}$  on  $M^n$  such that  $e_1, e_2, \dots, e_n$  are tangent to  $M^n$ ,  $e_{n+1}, e_{n+2}$  are normal to  $M^n$  and  $e_{n+2} = x$ . From now on, we shall use the following index conventions and notations:

$$1 \leq i, j \leq n, \quad n+1 \leq \alpha \leq n+2, \quad \epsilon_i = \langle e_i, e_i \rangle, \quad \epsilon = \langle e_{n+1}, e_{n+1} \rangle.$$

The pseudo Euclidean connection  $\bar{\nabla}$  on  $E_1^{n+1}$  induces the Levi-Civita connection  $\nabla$  on  $M^n$ ,

$$\bar{\nabla}_{e_i} e_j = \nabla_{e_i} e_j + \mathbf{h}(e_i, e_j) \quad \text{for } i, j = 1, 2, \dots, n,$$

where  $\mathbf{h}$  is the second fundamental form of  $M^n$  in  $E_1^{n+2}$ . Then there exists an  $n \times n$  symmetric matrix  $\{h_{ij}\}$  such that  $\mathbf{h}(e_i, e_j) = h_{ij}e_{n+1} - \epsilon_i \delta_{ij} e_{n+2}$ . The Weingarten equations are given by

$$\begin{aligned} \bar{\nabla}_{e_i} e_{n+1} &= -Ae_i = -\epsilon \sum_{j=1}^n \epsilon_j h_{ij} e_j, \\ \bar{\nabla}_{e_i} e_{n+2} &= e_i \quad \text{for } i = 1, \dots, n, \end{aligned}$$

where  $A$  is the weingarten map associated with  $e_{n+1}$ .

Let  $f \in C^\infty(M^n)$ . Then  $\nabla f$ , the gradient  $f$  and  $\Delta f$ , the Laplacian of  $f$  are given by

$$\begin{aligned} \nabla f &= \sum_i \epsilon_i (e_i f) e_i = \sum_i \epsilon_i f_i e_i, \\ \Delta f &= \sum_i \epsilon_i \{e_i e_i f - (\nabla_{e_i} e_i f)\} \end{aligned}$$

So the following holds

$$\begin{aligned} (2.1) \quad \Delta x &= \sum_i \epsilon_i (\bar{\nabla}_{e_i} \bar{\nabla}_{e_i} x - \bar{\nabla}_{\nabla_{e_i} e_i} x) \\ &= \sum_i \epsilon_i \mathbf{h}(e_i, e_i) \\ &= \sum_i \epsilon_i h_{ii} e_{n+1} - nx \\ &= H e_{n+1} - nx, \end{aligned}$$

where  $H$  is the mean curvature function of  $M^n$  in  $S_1^{n+1}$ . By similar calculation to that appeared in [3], we have the following.

**PROPOSITION 2.1.** *For a hypersurface  $M$  in  $S_1^{n+1}$ ,  $\Delta H e_{n+1}$  is calculated as follows,*

$$\Delta(H e_{n+1}) = -(2A + \epsilon HI)(\nabla H) + (\Delta H - \epsilon H \text{tr} A^2) e_{n+1} + \epsilon H^2 x.$$

Now suppose that the immersion  $x$  satisfies  $(*)$  for a constant matrix  $R$  and a constant vector  $b$ . Let  $R^*$  and  $C$  denote the adjoint matrix of  $R$  with respect to the indefinite metric  $\langle \cdot, \cdot \rangle$  and the skew self adjoint matrix  $\frac{1}{2}(R - R^*)$  respectively. Differentiating the following equation in the direction  $e_j$ ,

$$\langle Rx + b, e_i \rangle = 0, i = 1, 2, \dots, n$$

we can get

$$(2.2) \quad \langle R e_j, e_i \rangle = -\langle Rx + b, \mathbf{h}(e_i, e_j) \rangle, \quad i, j = 1, \dots, n.$$

(2.1) implies that  $\langle \Delta x, x \rangle = \langle Rx + b, x \rangle = -n$ . From this one can deduce that  $R^* x$  is normal to  $M^n$ . Hence we can get

$$(2.3) \quad \langle R^* e_j, e_i \rangle = -\langle R^* x, \mathbf{h}(e_i, e_j) \rangle, \quad i, j = 1, \dots, n.$$

Since  $\langle R e_i, e_i \rangle = \langle R^* e_i, e_i \rangle$ , by (2.2) and (2.3) we obtain

LEMMA 2.2.  $2Cx + b$  is normal to  $M^n$  and  $\langle Rx + b, 2Cx + b \rangle = 0$ .

The symmetry of the second fundamental form  $\mathbf{h}$  implies the following.

LEMMA 2.3.  $CX$  is normal to  $M^n$  for every tangent vector field  $X$  of  $M^n$ .

### 3. Proof of theorem1

At first, we will give the proof under the assumption that  $b = 0$  and  $R$  is self adjoint. Start with the equation  $Rx + nx = He_{n+1}$ . This equation implies

$$(3.1) \quad \langle Re_i, e_{n+1} \rangle = \epsilon H_i, i = 1, \dots, n,$$

$$(3.2) \quad \Delta(He_{n+1}) = R(He_{n+1}).$$

From proposition2.1 and (3.2), we have

$$(3.3) \quad H \langle Re_{n+1}, e_i \rangle = -2\epsilon \sum_j \epsilon_j H_j h_{ji} - \epsilon H H_i.$$

Since  $R$  is self adjoint, from (3.1) and (3.3) we find

$$H H_i = - \sum_j \epsilon_j H_j h_{ji}, i = 1, \dots, n.$$

This implies that

$$A(\nabla H) = -\epsilon H \nabla H.$$

Suppose that  $\nabla H \neq 0$ , i.e,  $H$  is nonconstant. Then  $\nabla H$  is an eigen vector of  $A$  with eigen value  $-\epsilon H$  If  $\langle \nabla H, \nabla H \rangle \neq 0$ , then by choosing  $e_n = \frac{\nabla H}{|\nabla H|}$ , we get

$$A = \begin{pmatrix} A' & 0 \\ 0 & -\epsilon H \end{pmatrix},$$

where  $A'$  is self adjoint. And  $R + nI$  can be written as

$$\begin{pmatrix} -HA' & 0 & & \\ & \epsilon H^2 & * & * \\ 0 & * & * & * \\ & * & * & * \end{pmatrix}.$$

Hence the eigenvalues of  $-HA'$  are constants and so is  $-HtrA' = -HtrA - \epsilon H^2 = -2\epsilon H^2$ , which is a contradiction. If  $\langle \nabla H, \nabla H \rangle = 0$  locally, then one can choose a frame  $e_1, \dots, e_{n-2}, u, v$  of  $M^n$  with all scalar products zero except  $\langle u, v \rangle = 1 = \langle e_i, e_i \rangle$  such that

$$A = \begin{pmatrix} D_{n-k} & 0 \\ 0 & A'_k \end{pmatrix} \text{ and } v \text{ is parallel to } \nabla H,$$

where  $D_{n-k}$  is an  $(n - k)$  diagonal matrix and

$$A'_2 = \begin{pmatrix} -\epsilon H & 0 \\ +1 & -\epsilon H \end{pmatrix}, A'_3 = \begin{pmatrix} -\epsilon H & 1 & 0 \\ 0 & -\epsilon H & 0 \\ 1 & 0 & -\epsilon H \end{pmatrix}.$$

This gives the matrix for  $R + nI$

$$\begin{pmatrix} -HD_{n-k} & 0 & 0 \\ 0 & -HA'_k & * \\ 0 & * & * \end{pmatrix}.$$

This implies that  $HtrD_{n-k} = H(trA - trA'_k) = (k + 1)\epsilon H^2$  is constant, which is a contradiction. Hence we have  $\nabla H = 0$ , i.e.,  $H$  is constant. Suppose  $M^n$  is not a minimal hypersurface of  $S_1^{n+1}$ . This means that  $H \neq 0$ . From proposition 2.1 and  $\Delta(He_{n+1}) = HR e_{n+1}$ , we get

$$(3.4) \quad R e_{n+1} = -\epsilon tr A^2 e_{n+1} + \epsilon H x.$$

And we know that  $tr A^2$  is constant. Differentiating (3.4) and the equation  $Rx = He_{n+1} - nx$  in the direction  $e_i$  ( $i = 1, \dots, n$ ), we get

$$(3.5) \quad R A e_i = -\epsilon tr A^2 A e_i - \epsilon H e_i,$$

$$(3.6) \quad R e_i = -H A e_i - n e_i.$$

Combining (3.5) with (3.6), we obtain

$$\{R^2 + (n + \epsilon tr A^2)R + (\epsilon tr A^2 - \epsilon H^2)I\} e_i = 0.$$

And by a direct computation we know that

$$\{R^2 + (n + \epsilon \text{tr} A^2)R + (\epsilon \text{tr} A^2 - \epsilon H^2)I\}e_\alpha = 0.$$

These imply that

$$(3.7) \quad R^2 + (n + \epsilon \text{tr} A^2)R + (\epsilon \text{tr} A^2 - \epsilon H^2)I = 0.$$

Since  $R$  is self adjoint,  $R$  has at least one real eigenvalue. So the left side of (3.7) can be factorized into linear terms such that

$$(3.8) \quad (R - \lambda_1 I)(R - \lambda_2 I) = 0$$

for some real numbers  $\lambda_1, \lambda_2$ . If  $R = \lambda_1 I$  or  $R = \lambda_2 I$ , then  $\langle Rx, x \rangle = -n$  implies that  $Rx = -nx$ . In this case  $M^n$  is minimal in  $S_1^{n+1}$ , which contradicts to our assumption. We proceed with two cases separately.

CASE1.  $\lambda_1 \neq \lambda_2$

Then  $E_1^{n+2}$  is decomposed into the direct sum of two linear subspaces  $V_1, V_2$ , which are eigen spaces of  $R$  corresponding to  $\lambda_1$  and  $\lambda_2$ , such that  $E_1^{n+2} = V_1 \oplus V_2$ . Since  $R$  is self adjoint,  $V_1$  and  $V_2$  are mutually orthogonal. Let  $E_1, E_2, \dots, E_{n+2}$  be a pseudo orthonormal frame of  $E_1^{n+2}$  such that  $E_1, \dots, E_i$  span  $V_1$  and  $E_{i+1}, \dots, E_{n+2}$  span  $V_2$ . Then  $R$  can be written as

$$\begin{pmatrix} \lambda_1 I & 0 \\ 0 & \lambda_2 I \end{pmatrix}.$$

And the position vector  $x$  can be expressed as  $x = x_1 + x_2$ , where  $x_1 \in \text{span}\{E_1, \dots, E_i\}$  and  $x_2 \in \text{span}\{E_{i+1}, \dots, E_{n+2}\}$ .  $\langle x, x \rangle = 1$  and  $\langle Rx, x \rangle = \lambda_1 \langle x_1, x_1 \rangle + \lambda_2 \langle x_2, x_2 \rangle = -n$  imply that  $\langle x_1, x_1 \rangle = \text{constant}$  and  $\langle x_2, x_2 \rangle = \text{constant}$ . So we can conclude that  $M^n$  is contained in  $S^n(c, r_1)$ , in  $S_1^n(c, r_1)$ , in  $S^k(0, r_1) \times S_1^{n-k}(0, r_2)$  or in  $S^k(0, r_1) \times H^{n-k}(0, -r_2)$  for some positive numbers  $r_1, r_2$  and a point  $c \in E_1^{n+2}$ .

CASE2.  $\lambda_1 = \lambda_2 = \lambda$

In this case, from(3.7) we get

$$(3.9) \quad (n + \epsilon \text{tr} A^2)^2 - 4(\epsilon \text{tr} A^2 - \epsilon H^2) = 0.$$

If  $\epsilon = 1$ , we get from this  $\{(trA^2)^2 - n\}^2 + 4H^2 = 0$ , which is impossible. So  $\epsilon = -1$ . This means that  $M^n$  is Riemannian. Therefore the weingarten map  $A = -\frac{1}{H}(R+nI)$  can be diagonalizable and hence there exists an orthonormal frame  $e_1, e_2, \dots, e_n$  of  $M^n$  such that

$$Ae_i = \mu_i e_i, \quad \mu_i \in C^\infty(M^n).$$

This implies that  $Re_i = (-H\mu_i - n)e_i$ . Since the only eigen value of  $R$  is  $\lambda$ ,  $-H\mu_i - n = \lambda$ . Thus  $\mu_i = -\frac{1}{H}(\lambda + n)$ . And hence

$$H^2 = n(\lambda + n), trA^2 = \lambda + n.$$

Replacing these in (3.9), we get  $\lambda = 0$ . From  $Re_i = 0$  and  $R^2 = 0$ , we can see that  $Rx$  is a null constant vector field. Subsequently  $M^n$  is an open part of a flat totally umbilical hypersurface. Now suppose that  $R$  is not self adjoint or  $b$  is nonzero. If  $2Cx + b = 0$  locally, then  $M^n$  is contained in an  $n$  dimensional affine subspace of  $E_1^{n+2}$ . This is a contradiction. Hence  $U = \{p \in M^n | 2Cx(p) + b \neq 0\}$  is an open dense subset of  $M^n$ . We will work in  $U$ . Let  $M_0, M_1$  be the sets

$$\begin{aligned} &\{p \in U | \langle Rx(p) + b, Rx(p) + b \rangle = 0\}, \\ &\{p \in U | \langle Rx(p) + b, Rx(p) + b \rangle \neq 0\}, \end{aligned}$$

respectively. If  $M_0$  has nonempty interior, then we may assume  $\langle Rx + b, Rx + b \rangle = 0$  locally. Then  $Re_i$  is tangential for a local orthonormal frame  $e_1, e_2, \dots, e_n$ . And if  $Rx + b$  and  $2Cx + b$  are linearly independent, then there exist functions  $\alpha, \beta$  such that

$$x = \alpha(Rx + b) + \beta(2Cx + b).$$

Then  $-n = \langle Rx + b, x \rangle = 0$ , which is a contradiction. Hence we know that  $Rx + b = \gamma(2Cx + b)$  for some function  $\gamma$ . Differentiating this formula in the direction  $e_i$ , we get

$$Re_i = (e_i\gamma)(2Cx + b) + \gamma(2Ce_i).$$

This formula and lemma2.3 imply that  $Re_i$  is normal to  $M^n$ . Therefore  $Re_i = 0$  for  $i = 1, 2, \dots, n$ . So  $Rx + b$  is a constant null vector in the

every component of  $M_0$ . If  $M_1$  is nonempty, then we may assume that  $Rx + b, 2Cx + b$  span the normal space of  $M_1$ . So there exist differentiable functions  $\alpha, \beta$  such that

$$x = \alpha(Rx + b) + \beta(2Cx + b).$$

Differentiating this in the direction  $e_i$ , we get

$$e_i = (e_i\alpha)(Rx + b) + \alpha Re_i + (e_i\beta)(2Cx + b) + \beta(2Ce_i).$$

Hence we get  $e_i\delta_{ij} = \alpha\langle Re_i, e_j \rangle$ . This implies that the weingarten map associated with  $Rx + b$  is  $-\frac{1}{\alpha}I$ , where  $I$  is the identity map. And we know that the weingarten map associated with  $2Cx + b$  is the zero map. So every component of  $M_1$  is an open part of a nonflat totally umbilical hypersurface of  $S_1^{n+1}$ . If  $M_0$  has nonempty interior, then, since  $Re_i = 0$  for a local orthonormal frame  $e_1, e_2, \dots, e_n$ , we can see that  $\text{rank}R$  is 0 or 1. And if  $M_1$  is nonempty, then  $\text{rank}R$  is not less than  $n$ . Therefore, by continuity we can conclude that  $M^n$  is contained a flat totally umbilical hypersurface of  $S_1^{n+1}$  or in a nonflat totally umbilical hypersurface of  $S_1^{n+1}$ .

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