

ON THE EXISTENCE AND BEHAVIOR OF SOLUTIONS FOR PERTURBED NONLINEAR DIFFERENTIAL EQUATIONS

JIN GYO JEONG AND KI-YEON SHIN

ABSTRACT. The existence and behavior of a bounded solution for a perturbed nonlinear differential equation of the type

$$(DE) \quad x'(t) + Ax(t) \ni G(x(t)), \quad t \in [0, \infty)$$

is considered. First, we consider the existence of a bounded solution with more simple assumptions using the concept of “the method of lines”. Then we devote to study its behavior using recent results of almost non-expansive curve which is developed by Djafari Rouhani.

1. Introduction

Let H be a real Hilbert space with inner product (\cdot, \cdot) and norm $\|\cdot\|$. We consider the existence and asymptotic behavior of a strong solution for the abstract perturbed nonlinear differential equation of the type

$$(DE : x_0) \quad \begin{cases} x'(t) + Ax(t) \ni G(x(t)), & t \in [0, \infty), \\ x(0) = x_0 \end{cases}$$

in a Hilbert space where A is a maximal monotone (possibly multi-valued) operator defined on $D(A) \subset H$ and $x_0 \in D(A)$.

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Recently, Djafari Rouhani ([3]) has obtained the asymptotic behavior of quasi-autonomous system

$$(1) \quad x'(t) + Ax(t) \ni f(t), \quad x(0) = x_0$$

in a Hilbert space using the concept of “almost non-expansive curve” which is defined later. In his paper, it is basically assumed that the generalized solution of (1) is assumed bounded (cf. Theorem 4.5 and 4.6 of [3]). On the other hand, Jung, Park and Kang ([5]) also considered the asymptotic behavior of perturbed nonlinear functional differential equation

$$(2) \quad x'(t) + Ax(t) + G(x)(t) \ni f(t), \quad x(0) = x_0$$

in a Hilbert space using same concept. In [5], the existence of a generalized solution is relied on the result of Aizicovici ([1]). Also, many authors are studied the behavior of solutions for (2) using various conditions. The reader is referred the papers which are mentioned in [5].

The purpose of this paper is to show the existence of a bounded solution of (DE: x_0) directly using the concept of “the method of lines” which is used by Kartsatos ([6]) and to find certain conditions on the perturbation G which are quite different from that of [5] to have same asymptotic behavior of solution for perturbed nonlinear differential equation (DE: x_0). “The method of lines” is used frequently to solve the existence problem of various type of differential equations. We refer to Tanaka ([8]), Kartsatos and Parrott ([7]), Ha, Shin and Jin ([4]).

2. Preliminaries

In this section, we give some definitions and recent results for almost non-expansive curve (ANEC). we refer the reader to related results of Djafari Rouhani([2], [3]). First, we denote by $PC_{loc}([0, \infty) : H)$ the space of all piecewise continuous functions $f : [0, T] \rightarrow H$ for every finite interval $[0, T]$, $T > 0$, and $\overline{B_k(0)}$ the closed ball of H with center at zero and radius k for fixed $k > 0$. We also denote by $A^\circ x$ the element of minimum norm in the closed convex set Ax and \rightarrow (\rightharpoonup) strong(weak) convergence in H .

DEFINITION 2.1. Let $u \in C([0, \infty) : H)$ and $\sigma_T = (1/T) \int_0^T u(t)dt$. The $(u(t))_{t \geq 0}$ is ANEC if $\forall r, s, h \geq 0$

$$\|u(r+h) - u(s+h)\|^2 \leq \|u(r) - u(s)\|^2 + \epsilon(r, s)$$

where $\lim_{r,s \rightarrow \infty} \epsilon(r, s) = 0$.

We note that a bounded curve $(u(t))_{t \geq 0}$ satisfying

$$\|u(r+h) - u(s+h)\| \leq \|u(r) - u(s)\| + \epsilon_1(r, s)$$

$\forall r, s, h \geq 0$ where $\lim_{r,s \rightarrow \infty} \epsilon_1(r, s) = 0$ is ANEC.

DEFINITION 2.2. Given a bounded curve $(u(t))_{t \geq 0}$ in H , the asymptotic centre c of $(u(t))_{t \geq 0}$ is defined as follows ; For every $y \in H$, let $\psi(y) = \limsup_{t \rightarrow \infty} \|u(t) - y\|^2$. Then ψ is a continuous, strictly convex function on H satisfying $\psi(y) \rightarrow \infty$ as $\|y\| \rightarrow \infty$. Thus ψ achieves its minimum on H at a unique point c which is called asymptotic centre of the curve $(u(t))_{t \geq 0}$.

We denote by $F(u(t))$ or for simplicity by F the following subset (possibly empty) of H ;

$$F = \{q \in H \mid \lim_{t \rightarrow \infty} \|u(t) - q\| \text{ exists} \}.$$

LEMMA 2.3. Let $(u(t))_{t \geq 0}$ be an ANEC in H . Then the followings are equivalent ;

- (1) $F \neq \emptyset$.
- (2) $\liminf_{T \rightarrow \infty} \|\sigma_T\| < \infty$.
- (3) σ_T converges weakly to the asymptotic centre of $(u(t))_{t \geq 0}$ as $T \rightarrow \infty$.

LEMMA 2.4. Let $(u(t))_{t \geq 0}$ be an ANEC in H such that $\forall h \geq 0$, $u(t+h) - u(t) \rightarrow 0$ as $t \rightarrow \infty$. Then the followings are equivalent ;

- (1) $F \neq \emptyset$.
- (2) $\liminf_{t \rightarrow \infty} \|u(t)\| < \infty$.
- (3) $u(t)$ converges weakly to $p \in H$ as $t \rightarrow \infty$.

LEMMA 2.5. Let $(u(t))_{t \geq 0}$ be any curve in H such that $\lim_{t \rightarrow \infty} (u(t+h), u(t)) = \beta(h)$ exists uniformly in $h \geq 0$. Then σ_T converges strongly to the asymptotic centre of $(u(t))_{t \geq 0}$ as $T \rightarrow \infty$.

3. The existence of a bounded solution

In the following, we assume the following hypotheses hold ;

(A.1) The operator $G : PC_{loc}([0, \infty), \overline{B_k(0)}) \rightarrow H$ satisfies

$$\|G(x(t)) - G(y(t))\| \leq \alpha(t)\|x(t) - y(t)\|$$

for $x, y \in PC_{loc}([0, \infty), \overline{B_k(0)})$ and $\alpha \in L^1([0, \infty), \mathcal{R}) \cap C([0, \infty), \mathcal{R})$.

(A.2) The operator $A : D(A) \subset H \rightarrow 2^H$ is a maximal monotone operator satisfying

$$(z - G(y(t)), x) \geq 0$$

for $y \in PC_{loc}([0, \infty), \overline{B_k(0)})$ and $z \in Ax$ where $x \in D(A)$ with $\|x\| > k$.

Let $T > 0$ be arbitrary but fixed. We shall first establish a theorem concerning the existence of step functions constructed by points satisfying certain equation which is so called approximate discrete scheme.

LEMMA 3.1. *Let $x_0 \in D(A) \cap \overline{B_k(0)}$ and $\{t_j^n\}_{j=0}^n$ be a partition of the interval $[0, T]$, where $t_j^n = jh_n = jT/n, j = 0, 1, \dots, n$. For sufficiently large n , there exists $\{w_j^n\}_{j=0}^n$ such that for $j = 1, 2, \dots, n$*

$$(3) \quad \frac{w_j^n - w_{j-1}^n}{h_n} + Aw_j^n \ni G(\overline{w}_j^n(t_j^n)),$$

where the step function $\overline{w}_j^n(t)$ is defined by

$$\overline{w}_j^n(t) = \begin{cases} x_0, & t = 0, \\ w_i^n, & t \in (t_{i-1}^n, t_i^n], i = 1, 2, \dots, j - 1 \\ w_j^n, & t \in (t_{j-1}^n, T]. \end{cases}$$

The function $x_n(t) = \overline{w}_n^n(t)$ is said to be an approximate solution of (DE: x_0).

Moreover, $\sup_{t \in [0, T]} \|\overline{w}_j^n(t)\| \leq k$ for $j = 1, 2, \dots, n$.

PROOF. Let $T_j : \overline{B_k(0)} \rightarrow H$ be defined by

$$(4) \quad T_j x = [I + h_n A]^{-1}(w_{j-1}^n + h_n G(\overline{x}(t_j^n)))$$

for $j = 1, 2, \dots, n$, where

$$\bar{x}_j^n(t) = \begin{cases} x_0, & t = 0, \\ w_i^n, & t \in (t_{i-1}^n, t_i^n], i = 1, 2, \dots, j - 1 \\ x, & t \in (t_{j-1}^n, T]. \end{cases}$$

Here we may assume $w_{j-1}^n \in \overline{B_k(0)}$. Since $[I + h_n A]^{-1}$ is non-expansive, T_j becomes Lipschitz continuous. In fact, there is $K > 0$ such that $\alpha(t) \leq K$ for all $t \in [0, \infty)$ since $\alpha \in C([0, \infty), \mathcal{R}) \cap L^1([0, \infty), \mathcal{R})$. Hence

$$\|T_j x - T_j y\| \leq h_n \|G(\bar{x}(t_j^n)) - G(\bar{y}(t_j^n))\| \leq h_n K \|x - y\|.$$

For sufficiently large n such as $h_n K < 1$, T_j is Lipschitz continuous with constant $KT/n < 1$. To show that $T_j : \overline{B_k(0)} \rightarrow \overline{B_k(0)}$, we put $u = T_j x$, $x \in \overline{B_k(0)}$ and assume that $\|u\| > k$. Then, since

$$z - G(\bar{x}(t_j^n)) + (u - w_{j-1}^n)/h_n = 0$$

for some $z \in Au$ by (4),

$$\begin{aligned} 0 &= (z - G(\bar{x}(t_j^n)), u) + (u - w_{j-1}^n)/h_n, u \\ &\geq (u - w_{j-1}^n, u)/h_n \geq [\|u\|^2 - (w_{j-1}^n, u)]/h_n \\ &\geq [\|u\| - \|w_{j-1}^n\|] \|u\|/h_n \geq (\|u\| - k) \|u\|/h_n > 0. \end{aligned}$$

From this contradiction, we have that $u \in \overline{B_k(0)}$. Therefore, for each $j = 1, 2, \dots, n$, T_j has a unique fixed point in $\overline{B_k(0)}$. When the unique fixed point of T_j on $\overline{B_k(0)}$ is denoted by w_j^n for $j = 1, 2, \dots, n$, we are able to define the step function $\bar{w}_j^n(t)$ on $[0, T]$ with $\sup_{t \in [0, T]} \|\bar{w}_j^n(t)\| \leq k$. □

LEMMA 3.2. Let $x_0 \in D(A) \cap \overline{B_k(0)}$. Then $\{\|w_j^n - w_{j-1}^n\|/h_n\}$ is uniformly bounded for sufficiently large n .

PROOF. Assume that n is sufficiently large so that $1 - h_n K > 0$, $h_n < 1$. From (3), we have

$$\begin{aligned} \|w_1^n - w_0^n\| &\leq h_n \|G(\bar{w}_1^n(t_1^n))\| + h_n \|(I + h_n A)^{-1} w_0^n - w_0^n\| \\ &\leq h_n \|G(\bar{w}(t_1^n)) - G(\bar{0}(t_1^n))\| + h_n \|G(\bar{0}(t_1^n))\| + h_n |A^0 w_0^n| \\ &\leq h_n [\alpha(t_1^n) \|w_1^n\| + |A^0 x_0|] \leq h_n [Kk + |A^0 x_0|] \equiv h_n C_1 \end{aligned}$$

with $C_1 = Kk + \|G(\bar{0}(0))\| + |A^0 x_0|$ where $\bar{0}$ is the zero function. For $j = 2, 3, \dots, n$, we have similar result such as

$$\begin{aligned} \|w_j^n - w_{j-1}^n\| &\leq \|w_{j-1}^n - w_{j-2}^n\| + h_n \|G(\bar{w}_j^n(t_j^n)) - G(\bar{w}_{j-1}^n(t_{j-1}^n))\| \\ &\leq \|w_{j-1}^n - w_{j-2}^n\| + h_n \|G(\bar{w}_j^n(t_j^n)) - G(\bar{w}_{j-1}^n(t_j^n))\| \\ &\leq \|w_{j-1}^n - w_{j-2}^n\| + h_n \alpha(t_j^n) \|w_j^n - w_{j-1}^n\|. \end{aligned}$$

It follows that

$$\max_{1 \leq i \leq j} \|w_i^n - w_{i-1}^n\|/h_n \leq K \max_{1 \leq i \leq j} \|w_i^n - w_{i-1}^n\| + \max_{1 \leq i \leq j-1} \|w_i^n - w_{i-1}^n\|/h_n.$$

Putting $P_n = 1 - Kh_n \in (0, 1)$ by our assumption, we obtain that

$$\frac{P_n}{h_n} \max_{1 \leq i \leq j} \|w_i^n - w_{i-1}^n\| \leq \frac{1}{h_n} \max_{1 \leq i \leq j-1} \|w_i^n - w_{i-1}^n\|$$

and

$$\begin{aligned} P_n \max_{1 \leq i \leq j} \|w_i^n - w_{i-1}^n\|/h_n &\leq \max_{1 \leq i \leq j-2} \|w_i^n - w_{i-1}^n\|/(P_n h_n) \\ &\vdots \\ &\leq \|w_1^n - w_0^n\|/(P_n^{j-2} h_n) \\ &\leq \|w_1^n - w_0^n\|/(P_n^{j-1} h_n) \end{aligned}$$

which yields, for $j = 2, 3, \dots, n$,

$$\max_{1 \leq i \leq j} \|w_i^n - w_{i-1}^n\|/h_n \leq C_1/P_n^n.$$

Since $1/P_n^n = 1/(1 - KT/n)^n$, there exists $C_2 > 0$ such that for sufficiently large n

$$\max_{1 \leq i \leq n} \|w_i^n - w_{i-1}^n\|/h_n \leq C_1 \exp(KT) \equiv C_2, \quad j = 1, 2, \dots, n.$$

From the above inequality, we have the desired result. □

REMARK 3.3. Let $x_n(t)$ be an h_n -approximate solution of (DE : x_0) for sufficiently large n . We define the function

$$z_n(t) = w_{j-1}^n + (t - t_{j-1}^n)(w_j^n - w_{j-1}^n)/h_n, \quad t \in [t_{j-1}^n, t_j^n] \quad j = 1, \dots, n.$$

It is easy to see that $z_n(t)$, $t \in [0, T]$, is Lipschitzian with constant C_2 . Since for $t \in [0, T]$ there exists j ($1 \leq j \leq n$) such that $t \in [t_{j-1}^n, t_j^n]$ and

$$\|x_n(t) - z_n(t)\| = \|w_j^n - w_{j-1}^n - (t - t_{j-1}^n)(w_j^n - w_{j-1}^n)/h_n\| \leq C_2 h_n,$$

we have for $t, s \in [0, T]$

$$\begin{aligned} \|x_n(t) - x_n(s)\| &\leq \|x_n(t) - z_n(t)\| + \|z_n(t) - z_n(s)\| + \|z_n(s) - x_n(s)\| \\ &\leq C_2|t - s| + 2C_2h_n \leq C_3(|t - s| + h_n). \end{aligned}$$

Consequently, there exists a constant C_3 such that

$$\|x_n(t) - x_n(s)\| \leq C_3(|t - s| + h_n)$$

for $t, s \in [0, T]$.

From the previous lemmas and remark, we have shown the way of construction and boundedness for an approximate solution $x_n(t)$ of (DE: x_0) for sufficiently large n . Moreover, we have also shown that $x_n(t)$ is Lipschitz continuous. Now, we should show the existence of a continuous function on $[0, T]$ which is uniform limit of the approximate solutions as $n \rightarrow \infty$. When we compare our equation (DE: x_0) to the equation (FDE: ϕ) in [5], we note that they are very similar except our equation has no delay term. Moreover, our perturbation G does not depend on t directly. Therefore, since the next processes are very close to those of Tanaka(Theorem 2.6, Theorem 3.3 of [5]), we omit proofs of the next several results.

THEOREM 3.4. Let $x_0 \in D(A) \cap \overline{B_k(0)}$. The limit $x(t) = \lim_{n \rightarrow \infty} x_n(t)$ exists uniformly for $t \in [0, T]$. Moreover, $x(t)$ is a unique strong solution of (DE: x_0).

As the way to show the uniqueness of the previous theorem, the following inequality is crucial. It is also very important to assure that the solution is actually ANEC.

THEOREM 3.5. *Let $x_0, \hat{x}_0 \in D(A) \cap \overline{B_k(0)}$ and $x(t), \hat{x}(t)$ be the corresponding solutions on $[0, T]$ of $(DE:x_0)$ and $(DE:\hat{x}_0)$, respectively. Then, for $0 \leq s \leq t \leq T$,*

$$\begin{aligned} \|x(t) - \hat{x}(t)\| &\leq \|x(s) - \hat{x}(s)\| + \int_s^t \|G(x(\tau)) - G(\hat{x}(\tau))\| d\tau \\ &\leq \|x(s) - \hat{x}(s)\| + \int_s^t \alpha(\tau) \|x(\tau) - \hat{x}(\tau)\| d\tau. \end{aligned}$$

4. Asymptotic behavior of solution

We devote to study the asymptotic behavior of solution of $(DE:x_0)$ which is obtained in Theorem 3.4 in this section.

THEOREM 4.1. *Let (A.1)-(A.2) hold and $x_0 \in D(A) \cap \overline{B_k(0)}$. If x is a strong solution of $(DE:x_0)$ for every interval $[0, T]$, then the curve $(x(t))_{t \geq 0}$ is ANEC in H .*

PROOF. For $\forall r \geq s$, we put $\hat{x}(t) = x(t + (r - s))$. Then $\hat{x}(t)$ is a strong solution of $(DE:x(r - s))$. Now, applying the inequality (5) in the above theorem, we have

$$\begin{aligned} \|x(t) - x(t + (r - s))\| &= \|x(t) - \hat{x}(t)\| \\ &\leq \|x(s) - \hat{x}(s)\| + \int_s^t \|G(x(\tau)) - G(\hat{x}(\tau))\| d\tau \\ &\leq \|x(s) - \hat{x}(s)\| + \int_s^t \alpha(\tau) \|x(\tau) - \hat{x}(\tau)\| d\tau \\ &= \|x(s) - x(s + (r - s))\| + \int_s^t \alpha(\tau) \|x(\tau) - x(\tau + (r - s))\| d\tau. \end{aligned}$$

It follows that

$$\|x(t) - x(t + (r - s))\| \leq \|x(s) - x(r)\| \exp\left(\int_s^t \alpha(\tau) d\tau\right).$$

Putting $t = s + h$ for some $h \geq 0$

$$\begin{aligned} & \|x(s + h) - x(r + h)\| \\ & \leq \|x(s) - x(r)\| \exp\left(\int_s^{s+h} \alpha(\tau) d\tau\right) \\ & = \|x(s) - x(r)\| + \|x(s) - x(r)\|(\exp\left(\int_s^{s+h} \alpha(\tau) d\tau\right) - 1) \\ & \leq \|x(s) - x(r)\| + \epsilon(r, s). \end{aligned}$$

Since $\alpha \in L^1([0, \infty) : \mathcal{R})$ and $\|x(t)\| \leq k$, we have $\epsilon(r, s) \rightarrow 0$ as $r, s \rightarrow \infty$. Hence $(x(t))_{t \geq 0}$ is ANEC in H . □

By the above theorem, we assure that our solution of $(DE:x_0)$ is an ANEC under the conditions. Hence, using the basic properties of ANEC, we have the following results which are same as those of [3].

THEOREM 4.2. *Let (A.1)-(A.2) hold and $x_0 \in D(A) \cap \overline{B_k(0)}$. If x is a strong solution of $(DE:x_0)$ for every interval $[0, T]$, then $\sigma_T = (1/T) \int_0^T x(t) dt$ converges weakly as $T \rightarrow \infty$ to the asymptotic centre of the curve $(x(t))_{t \geq 0}$.*

PROOF. It follows from Lemma 2.3 and Theorem 4.1. □

THEOREM 4.3. *Let (A.1)-(A.2) hold and $x_0 \in D(A) \cap \overline{B_k(0)}$. We assume that x is a strong solution of $(DE:x_0)$ for every interval $[0, T]$ and $\forall h \geq 0, x(t + h) - x(t) \rightarrow 0$ as $t \rightarrow \infty$. Then $x(t)$ converges weakly as $t \rightarrow \infty$ to the asymptotic centre of the curve $(x(t))_{t \geq 0}$.*

PROOF. It follows from Lemma 2.4 and Theorem 4.1. □

THEOREM 4.4. *Let (A.1)-(A.2) hold and $x_0 \in D(A) \cap \overline{B_k(0)}$. We assume that x is a strong solution of $(DE:x_0)$ for every interval $[0, T]$ and $\lim_{t \rightarrow \infty} (x(t), x(t + h)) = \beta(h)$ exists uniformly in $h \geq 0$. Then $\sigma_T = (1/T) \int_0^T x(t) dt$ converges strongly $T \rightarrow \infty$ to the asymptotic centre of the curve $(x(t))_{t \geq 0}$.*

PROOF. From Lemma 2.5, it is obvious. □

REMARK 4.5. The existence of a bounded strong solution of the non-linear functional differential equation

$$(FDE) \quad x'(t) + A(t)x(t) \ni G(t, x_t), \quad t \in [0, \infty)$$

is already considered even reflexive Banach space (cf. Theorem 6 of [6]). Also, we have results for an unbounded(not necessary bounded) solution of (1) in general Banach space by Djafari Rouhani ([2]). In the sequel study, we have some results on behavior of solution of the type

$$(FDE) \quad x'(t) + Ax(t) \ni G(x_t), \quad t \in [0, \infty)$$

in general Banach space using the above results.

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Department of Mathematics
 Pusan National University
 Pusan 609–735, Korea
E-mail: kyshin@hyowon.cc.pusan.ac.kr