# SOME CHARACTERIZATIONS OF $C R$-SUBMANIFOLDS WITH $(n-1) C R$-DIMENSION IN A COMPLEX PROJECTIVE SPACE 

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#### Abstract

The purpose of this paper is to give some characterizations of $n$-dimensional $C R$-submanifolds with $(n-1) C R$-dimension immersed in a complex projective space $C P^{\frac{n+p}{2}}$, in terms of the Riemannian curvature tensor $R$.


## 1. Introduction

Let $M$ be a connected real $n$-dimensional submanifold of real codimension $p$ of a complex manifold $\bar{M}$ with complex structure $J$. If the maximal $J$-invariant subspace $J T_{x} M \cap T_{x} M$ of $T_{x} M$ has constant dimension for any $x$ in $M$, then $M$ is called a $C R$-submanifold and the constant is called the $C R$-dimension of $M([8,9])$. Now let $M$ be an $n$ dimensional $C R$-submanifold of $(n-1) C R$-dimension of $\bar{M}$. Then $M$ admits an induced almost contact structure ( $[11,15,16]$ ). A typical example of an $n$-dimensional $C R$-submanifold of $(n-1) C R$-dimension is a real hypersurface. When the ambient manifold $\bar{M}$ is a complex projective space, real hypersurfaces are investigated by many authors ( $[2,4,5,6,7,10,12,13,14])$ in connection with the shape operator and the induced almost contact structure.

Recently, from these results, the several authors ( $[8,11]$ ) studied about an $n$-dimensional $C R$-submanifold of $(n-1) C R$-dimension in a complex projective space $C P^{\frac{n+p}{2}}$. Especially, by using the Erbacher's

[^0]reduction theorem ([3]), Okumura and Vanhecke [11] proved the following theorem, which is focused on the induced almost contact metric structure $F$ on $M$ and $A_{1}$ a special kind of shape operators.

Theorem A. Let $M$ be an $n$-dimensional $C R$-submanifold of $(n-$ 1) $C R$-dimension immersed in a complex projective space $C P^{\frac{n+p}{2}}$. If the normal vector field $\xi_{1}:=\xi$ appeared in (2.1) is parallel with respect to the normal connection and if $F$ and $A_{1}$ commute, then $\pi^{-1}(M)$ is locally a product of $M_{1} \times M_{2}$, where $M_{1}$ and $M_{2}$ belong to some odddimensional spheres ( $\pi$ is the Hopf-fibration $S^{n+p+1}(1) \rightarrow C P^{\frac{n+p}{2}}$ ).

The purpose of this paper is to give some characterizations of $C R$ -sub- manifolds of $(n-1) C R$-dimension in $C P^{\frac{n+p}{2}}$, in terms of the Riemannian curvature tensor $R$. We first have a classification of $C R$ submanifold of $(n-1) C R$-dimension in $C P^{\frac{n+p}{2}}$ satisfying $\mathcal{L}_{U_{1}} R=0$, where $\mathcal{L}_{U_{1}}$ denotes the Lie derivative in the direction of the structure vector field $U_{1}$.

Theorem 1. Let $M$ be an $n$-dimensional $C R$-submanifold of $(n-1)$ $C R$-dimension immersed in $C P^{\frac{n+p}{2}}$ and let there exist an orthonormal basis $\left\{\xi_{\alpha}\right\}_{\alpha=1, \ldots, p}\left(\xi_{1}:=\xi\right)$ of normal vectors to $M$ each of which is parallel with respect to the normal connection. If $\mathcal{L}_{U_{1}} R=0$, then $\pi^{-1}(M)$ is locally a product of $M_{1} \times M_{2}$, where $M_{1}$ and $M_{2}$ belong to some odd-dimensional spheres.

Next, we also have a classification of $C R$-submanifold of $(n-1)$ $C R$-dimension in $C P^{\frac{n+p}{2}}$ satisfying $\nabla_{U_{1}} R=0$, where $\nabla_{U_{1}} R$ denotes the covariant derivative in the direction of the structure vector field $U_{1}$. Namely, we prove the following theorem

Theorem 2. Let $M$ be as in Theorem 1 with $n \geq 3$. If $\nabla_{U_{1}} R=0$ and $g\left(A_{1} U_{1}, U_{1}\right) \neq 0$, then $\pi^{-1}(M)$ is locally a product of $M_{1} \times M_{2}$, where $M_{1}$ and $M_{2}$ belong to some odd-dimensional spheres.

## 2. Preliminaries

Let $M$ be an $n$-dimensional Riemannian manifold isometrically immersed in a complex space form $\bar{M}=M^{\frac{n+p}{2}}(c)$ and denote by $(J, \bar{g})$ the Kähler structure on $\bar{M}$. For $x$ of $M$ we denote by $T_{x} M$ and $T_{x} M^{\perp}$
the tangent space and normal space of $M$ at $x$, respectively. From now on we assume that $M$ is an $n$-dimensional $C R$-submanifold of $(n-1)$ $C R$-dimension, that is, $\operatorname{dim}\left(J T_{x} M \cap T_{x} M\right)=n-1$. This implies that $\operatorname{dim} M$ is odd ([11]).

Note that the definition of $C R$-submanifold of $(n-1) C R$-dimension meets the definition of $C R$-submanifold in the sense of Bejancu [1].

Furthermore, our hypothesis implies that there exists a unit vector field $\xi_{1}$ normal to $M$ such that $J T M \subset T M \oplus \operatorname{Span}\{\xi\}$. Hence, for any tangent vector field $X$ and for a local orthonormal basis $\left\{\xi_{\alpha}\right\}_{\alpha=1, \ldots, p}$ ( $\xi_{1}:=\xi$ ) of normal vectors to $M$, we have the following decomposition in tangential and normal components :

$$
\begin{gather*}
J X=F X+u^{1}(X) \xi_{1}  \tag{2.1}\\
J \xi_{\alpha}=-U_{\alpha}+P \xi_{\alpha}, \quad \alpha=1, \ldots, p \tag{2.2}
\end{gather*}
$$

It is easily seen that $F$ and $P$ are skew-symmetric linear endomorphisms acting on $T_{x} M$ and $T_{x} M^{\perp}$, respectively. Moreover, the Hermitian property of $J$ implies

$$
\begin{array}{r}
g\left(F U_{\alpha}, X\right)=-u^{1}(X) \bar{g}\left(\xi_{1}, P \xi_{\alpha}\right), \\
g\left(U_{\alpha}, U_{\beta}\right)=\delta_{\alpha \beta}-\bar{g}\left(P \xi_{\alpha}, P \xi_{\beta}\right) . \tag{2.4}
\end{array}
$$

From $\bar{g}\left(J X, \xi_{\alpha}\right)=-\bar{g}\left(X, J \xi_{\alpha}\right)$, we get $g\left(U_{\alpha}, X\right)=u^{1}(X) \delta_{1 \alpha}$ and hence

$$
\begin{equation*}
g\left(U_{1}, X\right)=u^{1}(X), \quad U_{\alpha}=0, \quad \alpha=2, \ldots, p . \tag{2.5}
\end{equation*}
$$

Next, applying $J$ to (2.1), using (2.2) and (2.5) we have

$$
\begin{equation*}
F^{2} X=-X+u^{1}(X) U_{1}, \quad u^{1}(X) P \xi_{1}=-u^{1}(F X) \xi_{1} . \tag{2.6}
\end{equation*}
$$

Since $P$ is skew-symmetric, (2.3) and the second equation of (2.6) give

$$
\begin{equation*}
u^{1}(F X)=0, \quad P \xi_{1}=0, \quad F U_{1}=0 . \tag{2.7}
\end{equation*}
$$

So, (2.2) may be written in the form

$$
\begin{equation*}
J \xi_{1}=-U_{1}, \quad J \xi_{\alpha}=P \xi_{\alpha}, \quad \alpha=2, \ldots, p \tag{2.8}
\end{equation*}
$$

and further, we may put

$$
\begin{equation*}
P \xi_{\alpha}=\sum_{\beta=2}^{p} P_{\alpha \beta} \xi_{\beta}, \quad \alpha=2, \ldots, p \tag{2.9}
\end{equation*}
$$

where $\left(P_{\alpha \beta}\right)$ is a skew-symmetric matrix which satisfies

$$
\begin{equation*}
\sum_{\beta=2}^{p} P_{\alpha \beta} P_{\beta \gamma}=-\delta_{\alpha \gamma}, \quad \alpha, \gamma=2, \ldots, p \tag{2.10}
\end{equation*}
$$

These results imply that $\left(F, U_{1}, u^{1}, g\right)$ defines an almost contact metric structure on $(M, g)$ ([16]).

Now, let $\bar{\nabla}$ and $\nabla$ denote the Levi-Civita connection on $\bar{M}$ and $M$, respectively and denote by $D$ the normal connection induced from $\bar{\nabla}$ in the normal bundle $T M^{\perp}$ of $M$. Then the Gauss and Weingarten equations are given by

$$
\begin{gather*}
\bar{\nabla}_{X} Y=\nabla_{X} Y+h(X, Y)  \tag{2.11}\\
\bar{\nabla}_{X} \xi_{\alpha}=-A_{\alpha} X+D_{X} \xi_{\alpha}, \quad \alpha=1, \ldots, p \tag{2.12}
\end{gather*}
$$

for any tangent vector fields $X$ and $Y$ to $M$. Here $h$ denotes the second fundamental form and $A_{\alpha}$ is the shape operator corresponding to $\xi_{\alpha}$. They are related by $h(X, Y)=\sum_{\alpha=1}^{p} g\left(A_{\alpha} X, Y\right) \xi_{\alpha}$.

Furthermore, putting

$$
\begin{equation*}
D_{X} \xi_{\alpha}=\sum_{\beta=1}^{p} s_{\alpha \beta}(X) \xi_{\beta} \tag{2.13}
\end{equation*}
$$

it follows that $\left(s_{\alpha \beta}\right)$ is the skew-symmetric matrix of connection forms of $D$. Next, the Gauss, Codazzi and Ricci equations are ([11]) :
(2.14) $\bar{g}(\bar{R}(X, Y) Z, W)=g(R(X, Y) Z, W)$

$$
+\sum_{\alpha=1}^{p}\left\{g\left(A_{\alpha} X, Z\right) g\left(A_{\alpha} Y, W\right)-g\left(A_{\alpha} Y, Z\right) g\left(A_{\alpha} X, W\right)\right\}
$$

$$
\begin{align*}
& \bar{g}\left(\bar{R}(X, Y) Z, \xi_{\alpha}\right)=g\left(\left(\nabla_{X} A_{\alpha}\right) Y-\left(\nabla_{Y} A_{\alpha}\right) X, Z\right)  \tag{2.15}\\
& +\sum_{\beta=1}^{p}\left\{g\left(A_{\beta} Y, Z\right) s_{\beta \alpha}(X)-g\left(A_{\beta} X, Z\right) s_{\beta \alpha}(Y)\right.
\end{align*}
$$

$$
\begin{equation*}
\bar{g}\left(\bar{R}(X, Y) \xi_{\alpha}, \xi_{\beta}\right)=\bar{g}\left(R^{\perp}(X, Y) \xi_{\alpha}, \xi_{\beta}\right)+g\left(\left[A_{\beta}, A_{\alpha}\right] X, Y\right) \tag{2.16}
\end{equation*}
$$

for any tangent vector fields $X, Y, Z$ and $W$ to $M . \bar{R}$ denotes the Riemannian curvature tensor of $\bar{M}$ and $R$ that of $M . R^{\perp}$ is the curvature tensor of the normal connection $D$.

Moreover, if the ambient space $\bar{M}$ is of constant holomorphic sectional curvature $c$, since

$$
\begin{aligned}
\bar{R}(\bar{X}, \bar{Y}) \bar{Z}= & \frac{c}{4}\{\bar{g}(\bar{Y}, \bar{Z}) \bar{X}-\bar{g}(\bar{X}, \bar{Z}) \bar{Y}+\bar{g}(J \bar{Y}, \bar{Z}) J \bar{X} \\
& -\bar{g}(J \bar{X}, \bar{Z}) J \bar{Y}-2 \bar{g}(J \bar{X}, \bar{Y}) J \bar{Z}\}
\end{aligned}
$$

for any tangent vector fields $\bar{X}, \bar{Y}$ and $\bar{Z}$ to $\bar{M}$, the Riemannian curvature tensor $R$ of $M$ given by

$$
\begin{align*}
& R(X, Y) Z=\frac{c}{4}\{g(Y, Z) X-g(X, Z) Y+g(F Y, Z) F X  \tag{2.17}\\
&-g(F X, Z) F Y-2 g(F X, Y) F Z\} \\
&+ \sum_{\alpha=1}^{p}\left\{g\left(A_{\alpha} Y, Z\right) A_{\alpha} X-g\left(A_{\alpha} X, Z\right) A_{\alpha} Y\right\}
\end{align*}
$$

for any tangent vector fields $X, Y$ and $Z$ to $M$.
In the sequel, we consider the case of a complex space form $\bar{M}=$ $M^{\frac{n+p}{2}}(c)$ and $\bar{\nabla} J=0$. Then by differentiating (2.1) and (2.2) covariantly and by comparing the tangential and normal parts, we have

$$
\begin{gather*}
\left(\nabla_{Y} F\right) X=u^{1}(X) A_{1} Y-g\left(A_{1} X, Y\right) U_{1},  \tag{2.18}\\
\left(\nabla_{Y} u^{1}\right) X=g\left(F A_{1} Y, X\right)  \tag{2.19}\\
\nabla_{X} U_{1}=F A_{1} X,  \tag{2.20}\\
g\left(A_{\alpha} U_{1}, X\right)=-\sum_{\beta=2}^{p} s_{1 \beta}(X) P_{\beta \alpha}, \quad \alpha=2, \ldots, p \tag{2.21}
\end{gather*}
$$

for any tangent vector fields $X$ and $Y$ to $M$.
In the rest of this paper we suppose that there exists an orthonormal basis $\left\{\xi_{\alpha}\right\}_{\alpha=1, \ldots, p}$ of normal vectors to $M$ each of which is parallel with respect to the normal connection $D$. Then from (2.13) we have

$$
\begin{equation*}
s_{\alpha \beta}=0 . \tag{2.22}
\end{equation*}
$$

Hence, from (2.21) and (2.22) we obtain

$$
\begin{equation*}
A_{\alpha} U_{1}=0, \quad \alpha=2, \ldots, p \tag{2.23}
\end{equation*}
$$

Moreover, from (2.22) and (2.23), the Codazzi equation (2.15) becomes

$$
\begin{align*}
& \left(\nabla_{X} A_{1}\right) Y-\left(\nabla_{Y} A_{1}\right) X  \tag{2.24}\\
& =\frac{c}{4}\left\{g\left(X, U_{1}\right) F Y-g\left(Y, U_{1}\right) F X-2 g(F X, Y) U_{1}\right\},
\end{align*}
$$

for any tangent vector fields $X$ and $Y$ to $M$. Also, by differentiating (2.23) covariantly and using (2.25) we get

$$
\begin{equation*}
\left(\nabla_{U_{1}} A_{\alpha}\right) U_{1}=0, \quad \alpha=2, \ldots, p \tag{2.26}
\end{equation*}
$$

Especially, recently Kwon and Pak [8] proved the following lemma.
Lemma 2.1. Let $M$ be an $n$-dimensional $C R$-submanifold of $(n-1)$ $C R$-dimension immersed in a complex space form $M^{\frac{n+p}{2}}(c), c \neq 0$ and let there exist an orthonormal basis $\left\{\xi_{\alpha}\right\}_{\alpha=1, \ldots, p}$ of normal vectors to $M$ each of which is parallel with respect to the normal connection. If $A_{1} U_{1}=\lambda U_{1}$ for some function $\lambda$, then $\lambda$ is locally constant.

Finally, we suppose that $U_{1}$ is principal with corresponding principal curvature $\lambda$. Then, by Lemma 2.1, $\lambda$ is constant on $M$ and it satisfies

$$
\begin{gather*}
\left(\nabla_{U_{1}} A_{1}\right) U_{1}=0  \tag{2.27}\\
A_{1} F A_{1}=\frac{c}{4} F+\frac{1}{2} \lambda\left(A_{1} F+F A_{1}\right) \tag{2.28}
\end{gather*}
$$

by virtue of (2.20) and (2.24). Hence from (2.24) and (2.28), we get

$$
\begin{equation*}
\nabla_{U_{1}} A_{1}=-\frac{1}{2} \lambda\left(A_{1} F-F A_{1}\right) \tag{2.29}
\end{equation*}
$$

## 3. Proof of Theorem 1

In this section, we are concerned with the proof of Theorem 1. Let $M$ be an $n$-dimensional $C R$-submanifold of $(n-1) C R$-dimension immersed in a complex space form $M^{\frac{n+p}{2}}(c)$. Then $M$ admits an almost contact metric structure $\left(F, U_{1}, u^{1}, g\right)$. The Lie derivative $\mathcal{L}_{U_{1}} R$ of $R$ with respect to the structure vector field $U_{1}$ satisfies

$$
\begin{align*}
\left(\mathcal{L}_{U_{1}} R\right)(X, Y, Z)= & \mathcal{L}_{U_{1}}(R(X, Y) Z)-R\left(\mathcal{L}_{U_{1}} X, Y\right) Z  \tag{3.1}\\
& -R\left(X, \mathcal{L}_{U_{1}} Y\right) Z-R(X, Y) \mathcal{L}_{U_{1}} Z
\end{align*}
$$

for any vector fields $X, Y$ and $Z$ on $M$. From now on we shall prove the following lemma.

Lemma 3.1. Let $M$ be as in Lemma 2.1. If $\mathcal{L}_{U_{1}} R=0$, then $A_{1} F=$ $F A_{1}$.

Proof. Let $T_{0}$ be a distribution defined by the subspace $T_{0}(x)=$ $\left\{u \in T_{x} M: g\left(u, U_{1}(x)\right)=0\right\}$ of the tangent space $T_{x} M$ of $M$ at any point $x$, which is called the holomorphic distribution. Suppose that the structure vector field $U_{1}$ is not necessarily principal. Then we can put $A_{1} U_{1}=\lambda U_{1}+\mu V$, where $V$ is a unit vector field in $T_{0}, \lambda$ and $\mu$ are smooth functions on $M$. From (2.17), (2.18), (2.20), (3.1) and our assumption, we have

$$
\begin{align*}
0 & =\frac{c}{4} \mu\left[\left\{u^{1}(Y) g(Z, V)-u^{1}(Z) g(Y, V)\right\} F X\right.  \tag{3.2}\\
& -\left\{u^{1}(X) g(Z, V)-u^{1}(Z) g(X, V)\right\} F Y \\
& -2\left\{u^{1}(X) g(Y, V)-u^{1}(Y) g(X, V)\right\} F Z \\
& +g(F Y, Z)\left\{u^{1}(X) V-g(X, V) U_{1}\right\} \\
& -g(F X, Z)\left\{u^{1}(Y) V-g(Y, V) U_{1}\right\} \\
& \left.-2 g(F X, Y)\left\{u^{1}(Z) V-g(Z, V) U_{1}\right\}\right] \\
& -\frac{c}{4}\left\{g(F Y, Z) F\left(A_{1} F-F A_{1}\right) X-g(F X, Z) F\left(A_{1} F-F A_{1}\right) Y\right. \\
& -2 g(F X, Y) F\left(A_{1} F-F A_{1}\right) Z+g\left(\left(A_{1} F-F A_{1}\right) Y, Z\right) X \\
& -g\left(\left(A_{1} F-F A_{1}\right) X, Z\right) Y+g\left(\left(A_{1} F^{2}-F^{2} A_{1}\right) Y, Z\right) F X
\end{align*}
$$

$$
\begin{aligned}
& \left.-g\left(\left(A_{1} F^{2}-F^{2} A_{1}\right) X, Z\right) F Y-2 g\left(\left(A_{1} F^{2}-F^{2} A_{1}\right) X, Y\right) F Z\right\} \\
& +g\left(\left(\nabla_{U_{1}} A_{1}\right) Y, Z\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) X, Z\right) A_{1} Y \\
& +g\left(A_{1} Y, Z\right)\left\{\left(\nabla_{U_{1}} A_{1}\right) X+\left(A_{1} F-F A_{1}\right) A_{1} X\right\} \\
& -g\left(A_{1} X, Z\right)\left\{\left(\nabla_{U_{1}} A_{1}\right) Y+\left(A_{1} F-F A_{1}\right) A_{1} Y\right\} \\
& -\sum_{\alpha=2}^{p}\left[\left\{g\left(A_{1} F A_{\alpha} Y, Z\right)-g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) Y, Z\right)-g\left(A_{\alpha} F A_{1} Y, Z\right)\right\} A_{\alpha} X\right. \\
& \left.-g\left(A_{\alpha} Y, Z\right)\left\{\left(\nabla_{U_{1}} A_{\alpha}\right) X-F A_{1} A_{\alpha} X+A_{\alpha} F A_{1} X\right\}\right] \\
& +\sum_{\alpha=2}^{p}\left[\left\{g\left(A_{1} F A_{\alpha} X, Z\right)-g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) X, Z\right)-g\left(A_{\alpha} F A_{1} X, Z\right)\right\} A_{\alpha} Y\right. \\
& \left.-g\left(A_{\alpha} X, Z\right)\left\{\left(\nabla_{U_{1}} A_{\alpha}\right) Y-F A_{1} A_{\alpha} Y+A_{\alpha} F A_{1} Y\right\}\right]
\end{aligned}
$$

for any vector fields $X, Y$ and $Z$ on $T_{x} M$. Putting $Z=U_{1}$ and taking $X$ and $Y$ in the holomorphic distribution $T_{0}$ in (3.2) and using (2.23) and (2.26), we have
(3.3) $0=\frac{c}{4} \mu\{g(Y, F V) X-g(X, F V) Y\}+g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right) A_{1} X$
$-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} Y$
$+\mu\left[g(Y, V)\left\{\left(\nabla_{U_{1}} A_{1}\right) X+\left(A_{1} F-F A_{1}\right) A_{1} X\right\}\right.$
$\left.-g(X, V)\left\{\left(\nabla_{U_{1}} A_{1}\right) Y+\left(A_{1} F-F A_{1}\right) A_{1} Y\right\}\right]$
$+\sum_{\alpha=2}^{p} \mu\left\{g\left(A_{\alpha} Y, F V\right) A_{\alpha} X-g\left(A_{\alpha} X, F V\right) A_{\alpha} Y\right\}$.
Again, putting $Y=Z=U_{1}$ and taking $X$ in the holomorphic distribution $T_{0}$ in (3.2) and using (2.23), we have

$$
\begin{align*}
\lambda\left(\nabla_{U_{1}} A_{1}\right) X & =\mu g(X, V)\left(\nabla_{U_{1}} A_{1}\right) U_{1}-d \lambda\left(U_{1}\right) A_{1} X  \tag{3.4}\\
& +g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} U_{1} \\
& +\frac{c}{4} \mu g(X, F V) U_{1}+\mu^{2} g(X, V)\left(A_{1} F-F A_{1}\right) V \\
& -\lambda \mu^{2} g(X, V) F V-\lambda\left(A_{1} F-F A_{1}\right) A_{1} X .
\end{align*}
$$

Eliminating $\left(\nabla_{U_{1}} A_{1}\right) X$ and $\left(\nabla_{U_{1}} A_{1}\right) Y$ in (3.3) and (3.4) and using
(2.26), we obtain

$$
\begin{align*}
0= & \frac{c}{4} \mu[\lambda\{g(Y, F V) X-g(X, F V) Y\}+\mu\{g(X, F V) g(Y, V)  \tag{3.5}\\
& \left.-g(X, V) g(Y, F V)\} U_{1}\right] \\
& +\lambda\left\{g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} Y\right\} \\
& +\mu\left[g(Y, V)\left\{g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} U_{1}-d \lambda\left(U_{1}\right) A_{1} X\right\}\right. \\
& \left.-g(X, V)\left\{g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right) A_{1} U_{1}-d \lambda\left(U_{1}\right) A_{1} Y\right\}\right] \\
& +\sum_{\alpha=2}^{p} \mu\left\{g\left(A_{\alpha} Y, F V\right) A_{\alpha} X-g\left(A_{\alpha} X, F V\right) A_{\alpha} Y\right\}
\end{align*}
$$

for any vector fields $X$ and $Y$ in $T_{0}$. Now, putting $X=V$ and $Y=F V$ in (3.5) and using (2.26), we get

$$
\begin{align*}
0= & \frac{c}{4} \mu\left(\lambda V-\mu U_{1}\right)+\lambda\left\{g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right) A_{1} V\right.  \tag{3.6}\\
& \left.-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, V\right) A_{1} F V\right\} \\
& -\mu\left\{g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right) A_{1} U_{1}-d \lambda\left(U_{1}\right) A_{1} F V\right\} \\
& +\sum_{\alpha=2}^{p} \mu\left\{g\left(A_{\alpha} F V, F V\right) A_{\alpha} V-g\left(A_{\alpha} V, F V\right) A_{\alpha} F V\right\} .
\end{align*}
$$

Taking the inner product of (3.6) with $U_{1}$ and using (2.23), we obtain $\mu=0$, that is, the structure vector field $U_{1}$ is principal. Hence, by Lemma 2.1, $\lambda$ is constant. If $\lambda=0$, then putting $X=U_{1}$ in (3.2) and using (2.23), (2.26) and $c \neq 0$, we get $A_{1} F-F A_{1}=0$. Next, suppose that $\lambda \neq 0$. Then from (3.4) and (2.27) we have

$$
\begin{equation*}
\left(\nabla_{U_{1}} A_{1}\right) X+A_{1} F A_{1} X-F A_{1}^{2} X=0 \tag{3.7}
\end{equation*}
$$

for any vector field $X$ in $T_{0}$.
Furthermore, putting $Y=Z=U_{1}$ in (3.2) and using (2.23) and (2.27), we see that (3.7) holds for any vector field $X$. This implies that

$$
\begin{equation*}
F\left(A_{1}^{2}-\lambda A_{1}-\frac{c}{4} I\right) X=0 \tag{3.8}
\end{equation*}
$$

for any vector field $X$, where $I$ denotes the identity transformation and we have used (2.28) and (2.29). (3.8) is equivalent to

$$
A_{1}^{2}-\lambda A_{1}-\frac{c}{4}\left(I-u^{1} \otimes U_{1}\right)=0
$$

from which it follows that $A_{1}$ satisfies $\left(A_{1} F-F A_{1}\right)^{2}=0$, where we have used that (2.28) and $A_{1} F^{2}=F^{2} A_{1}=-A_{1}+\lambda u^{1} \otimes U_{1}$. Hence, we have $A_{1} F-F A_{1}=0$.

Proof of Theorem 1. Combining Lemma 3.1 and Theorem A, we have Theorem 1.

## 4. Proof of Theorem 2

In this section, we are concerned with the proof of Theorem 2. Let $M$ be an $n$-dimensional $C R$-submanifold of $(n-1) C R$-dimension immersed in a complex space form $M^{\frac{n+p}{2}}(c)$. Then $M$ admits an almost contact metric structure $\left(F, U_{1}, u^{1}, g\right)$. The covariant derivative $\nabla_{U_{1}} R$ of $R$ with respect to the structure vector field $U_{1}$ satisfies

$$
\begin{align*}
\left(\nabla_{U_{1}} R\right)(X, Y, Z)= & \nabla_{U_{1}}(R(X, Y) Z)-R\left(\nabla_{U_{1}} X, Y\right) Z  \tag{4.1}\\
& -R\left(X, \nabla_{U_{1}} Y\right) Z-R(X, Y) \nabla_{U_{1}} Z
\end{align*}
$$

for any vector fields $X, Y$ and $Z$ on $M$. From now on we shall prove the following lemma.

Lemma 4.1. Let $M$ be as in Lemma 2.1 with $n \geq 3$. If $\nabla_{U_{1}} R=0$, then $\nabla_{U_{1}} A_{1}=0$.

Proof. From (2.17), (2.18), (4.1) and our assumption, we have

$$
\begin{align*}
0= & \frac{c}{4}\left[\left\{u^{1}(Y) g\left(A_{1} U_{1}, Z\right)-u^{1}(Z) g\left(A_{1} U_{1}, Y\right)\right\} F X\right.  \tag{4.2}\\
& -\left\{u^{1}(X) g\left(A_{1} U_{1}, Z\right)-u^{1}(Z) g\left(A_{1} U_{1}, X\right)\right\} F Y \\
& -2\left\{u^{1}(X) g\left(A_{1} U_{1}, Y\right)-u^{1}(Y) g\left(A_{1} U_{1}, X\right)\right\} F Z \\
& +g(F Y, Z)\left\{u^{1}(X) A_{1} U_{1}-g\left(A_{1} U_{1}, X\right) U_{1}\right\} \\
& -g(F X, Z)\left\{u^{1}(Y) A_{1} U_{1}-g\left(A_{1} U_{1}, Y\right) U_{1}\right\}
\end{align*}
$$

$$
\begin{aligned}
& \left.-2 g(F X, Y)\left\{u^{1}(Z) A_{1} U_{1}-g\left(A_{1} U_{1}, Z\right) U_{1}\right\}\right] \\
& +g\left(\left(\nabla_{U_{1}} A_{1}\right) Y, Z\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) X, Z\right) A_{1} Y \\
& +g\left(A_{1} Y, Z\right)\left(\nabla_{U_{1}} A_{1}\right) X-g\left(A_{1} X, Z\right)\left(\nabla_{U_{1}} A_{1}\right) Y \\
& +\sum_{\alpha=2}^{p}\left\{g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) Y, Z\right) A_{\alpha} X-g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) X, Z\right) A_{\alpha} Y\right. \\
& \left.+g\left(A_{\alpha} Y, Z\right)\left(\nabla_{U_{1}} A_{\alpha}\right) X-g\left(A_{\alpha} X, Z\right)\left(\nabla_{U_{1}} A_{\alpha}\right) Y\right\}
\end{aligned}
$$

for any vector fields $X, Y$ and $Z$ on $T_{x} M$. Suppose that the structure vector field $U_{1}$ is not necessarily principal. Then we can put $A_{1} U_{1}=$ $\lambda U_{1}+\mu V$, where $V$ is a unit vector field in $T_{0}$, and $\lambda$ and $\mu$ are smooth functions on $M$. Let $M_{0}$ be the non-empty open subset of $M$ consisting of points $x$ at which $\mu(x) \neq 0$. Hereafter unless otherwise stated, we shall discuss on the subset $M_{0}$ of $M$. By the form $A_{1} U_{1}=\lambda U_{1}+\mu V$, (4.2) is reformed as

$$
\begin{align*}
0= & \frac{c}{4} \mu\left[\left\{u^{1}(Y) g(Z, V)-u^{1}(Z) g(Y, V)\right\} F X\right.  \tag{4.3}\\
& -\left\{u^{1}(X) g(Z, V)-u^{1}(Z) g(X, V)\right\} F Y \\
& -2\left\{u^{1}(X) g(Y, V)-u^{1}(Y) g(X, V)\right\} F Z \\
& +g(F Y, Z)\left\{u^{1}(X) V-g(X, V) U_{1}\right\} \\
& -g(F X, Z)\left\{u^{1}(Y) V-g(Y, V) U_{1}\right\} \\
& \left.-2 g(F X, Y)\left\{u^{1}(Z) V-g(Z, V) U_{1}\right\}\right] \\
& +g\left(\left(\nabla_{U_{1}} A_{1}\right) Y, Z\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) X, Z\right) A_{1} Y \\
& +g\left(A_{1} Y, Z\right)\left(\nabla_{U_{1}} A_{1}\right) X-g\left(A_{1} X, Z\right)\left(\nabla_{U_{1}} A_{1}\right) Y \\
& +\sum_{\alpha=2}^{p}\left\{g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) Y, Z\right) A_{\alpha} X-g\left(\left(\nabla_{U_{1}} A_{\alpha}\right) X, Z\right) A_{\alpha} Y\right. \\
& \left.+g\left(A_{\alpha} Y, Z\right)\left(\nabla_{U_{1}} A_{\alpha}\right) X-g\left(A_{\alpha} X, Z\right)\left(\nabla_{U_{1}} A_{\alpha}\right) Y\right\}
\end{align*}
$$

for any vector fields $X, Y$ and $Z$ on $T_{x} M$. Putting $Z=U_{1}$ and taking $X$ and $Y$ in the holomorphic distribution $T_{0}$ in (4.3) and using (2.23) and (2.26), we have

$$
\begin{align*}
0= & \frac{c}{4} \mu\{-g(Y, V) F X+g(X, V) F Y-2 g(F X, Y) V\}  \tag{4.4}\\
& +g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} Y \\
& +\mu\left\{g(Y, V)\left(\nabla_{U_{1}} A_{1}\right) X-g(X, V)\left(\nabla_{U_{1}} A_{1}\right) Y\right\} .
\end{align*}
$$

Next, putting $Y=Z=U_{1}$ and taking $X$ in the holomorphic distribution $T_{0}$ in (4.3) and using (2.20), (2.23) and (2.26) we have

$$
\begin{align*}
\lambda\left(\nabla_{U_{1}} A_{1}\right) X= & \left.g\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} U_{1}  \tag{4.5}\\
& +\mu g(X, V)\left(\nabla_{U_{1}} A_{1}\right) U_{1}-d \lambda\left(U_{1}\right) A_{1} X .
\end{align*}
$$

Combining (4.4) and (4.5) and using (2.26), we obtain

$$
\begin{align*}
0= & \frac{c}{4} \lambda \mu\{-g(Y, V) F X+g(X, V) F Y-2 g(F X, Y) V\}  \tag{4.6}\\
& +\mu\left\{g(Y, V) g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right)\right. \\
& \left.-g(X, V) g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right)\right\} A_{1} U_{1} \\
& +\left\{\lambda g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right)-\mu d \lambda\left(U_{1}\right) g(Y, V)\right\} A_{1} X \\
& -\left\{\lambda g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right)-\mu d \lambda\left(U_{1}\right) g(X, V)\right\} A_{1} Y
\end{align*}
$$

for any vector fields $X$ and $Y$ in $T_{0}$. Let $L\left(U_{1}, V, F V\right)$ be a distribution defined by the subspace $L_{x}\left(U_{1}, V, F V\right)$ in the tangent space $T_{x} M$ spanned by the vectors $U_{1}(x), V(x)$ and $F V(x)$ at any point $x$ in $M$, and let $T_{1}$ be the orthogonal complement in the tangent bundle $T M$ of the distribution $L\left(U_{1}, V, F V\right)$. Then $T_{1}$ is not empty because of $n \geq 3$. For any unit vector field $X$ in $T_{1}$, putting $Y=F X$ in (4.6) and using (2.26), we have

$$
\begin{equation*}
\frac{c}{2} \mu V=g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F X\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} F X \tag{4.7}
\end{equation*}
$$

provided $\lambda \neq 0$. Suppose that there is a unit vector field $X_{0}$ in $T_{1}$ at which $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X_{0}\right)=0$. Then from (4.7) we obtain

$$
\begin{equation*}
\frac{c}{2} \mu V=g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F X_{0}\right) A_{1} X_{0} \neq 0 . \tag{4.8}
\end{equation*}
$$

Accordingly we can put $A_{1} X_{0}=\omega\left(X_{0}\right) V$, where $\omega$ is a 1-form on $M_{0}$. Putting $X=X_{0}, Y=V$ in (4.6), we have

$$
\begin{equation*}
\frac{c}{4} \lambda \mu F X_{0}-\omega\left(X_{0}\right)\left\{\lambda g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, V\right)-\mu d \lambda\left(U_{1}\right)\right\} V=0 . \tag{4.9}
\end{equation*}
$$

Thus, since $F X_{0}$ and $V$ are orthonormal vector fields and $\lambda \neq 0$, (4.9) implies $\mu=0$, a contradiction. Accordingly we get

$$
\begin{equation*}
g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) \neq 0 \tag{4.10}
\end{equation*}
$$

for any non-zero vector field $X$ in $T_{1}$. On the other hand, putting $Y=F V$ in (4.6) and using (2.26), we have

$$
\begin{equation*}
g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right) A_{1} X-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) A_{1} F V=0 \tag{4.11}
\end{equation*}
$$

for any $X$ in $T_{1}$ under the assumption $\lambda \neq 0$. If $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right)=0$, then from (4.10) and (4.11) we obtain $A_{1} F V=0$. Now, we suppose that $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right) \neq 0$. From (4.10) and (4.11) we have

$$
\begin{equation*}
A_{1} X=\theta(X) A_{1} F V, \quad \theta(X) \neq 0 \tag{4.12}
\end{equation*}
$$

for any non-zero vector field $X$ in $T_{1}$, where $\theta$ is a 1-form on $M_{0}$. Hence, for any non-zero vector fields $X$ and $Y$ in $T_{1}$, we obtain

$$
\begin{equation*}
A_{1}\{\theta(Y) X-\theta(X) Y\}=0, \quad \theta(X) \neq 0, \quad \theta(Y) \neq 0 \tag{4.13}
\end{equation*}
$$

If we put $Z_{1}=\theta\left(Y_{1}\right) X_{1}-\theta\left(X_{1}\right) Y_{1}$ for given linearly independent vector fields $X_{1}$ and $Y_{1}$ in $T_{1}$, then from (4.13) $A_{1} Z_{1}=0$ and hence $A_{1} F V=0$ by virtue of (4.12).

Next, putting $X=V$ and $Y=F V$ in (4.6), and using $A_{1} F V=0$, we have

$$
\begin{equation*}
\frac{3 c}{4} \lambda \mu V-g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right)\left(\lambda A_{1} V-\mu A_{1} U_{1}\right)=0 \tag{4.14}
\end{equation*}
$$

Consequently, we get $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, F V\right) \neq 0$ which together with (4.11) we have $A_{1} X=0$ for any vector field $X$ in $T_{1}$. Hence, putting $X=U_{1}$ and taking $Y, Z \in T_{1}$ in (4.3), and using (2.23) and (2.26), we obtain

$$
\begin{equation*}
\lambda g\left(\left(\nabla_{U_{1}} A_{1}\right) Y, Z\right) U_{1}+\mu\left\{\frac{c}{4} g(F Y, Z)+g\left(\left(\nabla_{U_{1}} A_{1}\right) Y, Z\right)\right\} V=0 \tag{4.15}
\end{equation*}
$$

Accordingly it turns out to be $\mu=0$ on $M_{0}$ provided $\lambda \neq 0$, a contradiction. This means that $U_{1}$ is principal on $M^{\prime}$, where $M^{\prime}$ denotes the open subset of $M$ consisting of points $x$ at which $\lambda(x) \neq 0$. Thus, putting $Y=Z=U_{1}$ in (4.3) and using (2.23), (2.26) and (2.27), we have $\nabla_{U_{1}} A_{1}=0$.

Now, let us denote by $\operatorname{Int}\left(M-M^{\prime}\right)$ the interior of the subset ( $M-$ $\left.M^{\prime}\right)$. Then $\lambda=0$ on $\operatorname{Int}\left(M-M^{\prime}\right)$. Suppose that $U_{1}$ is not principal
on $\operatorname{Int}\left(M-M^{\prime}\right)$. Then the subset $M_{1}$ of $\operatorname{Int}\left(M-M^{\prime}\right)$ consisting of points $x$ at which $\mu(x) \neq 0$ is non-empty open set. Hence, from (4.5) we have

$$
\begin{equation*}
g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) V+g(X, V)\left(\nabla_{U_{1}} A_{1}\right) U_{1}=0 \tag{4.16}
\end{equation*}
$$

on $M_{1}$ for any vector field $X$ in $T_{0}$. Accordingly $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, Y\right)=0$ for any vector field $Y$ in $T_{0}$ orthogonal to $V$. Taking the inner product of (4.16) with $X$ in $T_{0}$, we have $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, X\right) g(X, V)=0$. Putting $X=V$ in this equation, we get $g\left(\left(\nabla_{U_{1}} A_{1}\right) U_{1}, V\right)=0$. Hence, putting $X=V$ in (4.16), we obtain $\left(\nabla_{U_{1}} A_{1}\right) U_{1}=0$ on $M_{1}$. Taking $X$ and $Y$ in $T_{0}$ orthogonal to $V$ in (4.4) and using $\left(\nabla_{U_{1}} A_{1}\right) U_{1}=0$, we obtain $g(F X, Y)=0$ on $M_{1}$, a contradiction. This means that $U_{1}$ is principal with corresponding principal curvature $\lambda=0$. Accordingly we have $\nabla_{U_{1}} A_{1}=0$ on $\operatorname{Int}\left(M-M^{\prime}\right)$ by virtue of (2.29). This completes the proof by the continuity of $\nabla_{U_{1}} A_{1}=0$.

Proof of Theorem 2. Combining (2.29), Lemma 4.1 and Theorem A, we have Theorem 2.

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