

EVALUATION FORMULAS OF CONDITIONAL YEH-WIENER INTEGRALS

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ABSTRACT. In this paper, we introduce conditional Yeh-Wiener integrals for generalized conditioning functions including vector-valued functions. And also we establish various evaluation formulas of conditional Yeh-Wiener integrals for generalized conditioning functions.

1. Introduction

J. Yeh [15] introduced the concept of conditional Wiener integrals $E[F|X]$ of F given X as a function on the value space of X and derived a Fourier transform inversion formula for computing conditional Wiener integrals. Using this formula, he obtained some very useful results including a Kac-Feynman integral equation and a Cameron-Martin translation theorem [15,16]. Using Yeh's inversion formula, Chang and Chang [4] evaluated the conditional Wiener integral of F given $X(x) = (x(t_1), \dots, x(t_n))$ where $0 = t_0 < t_1 < t_2 < \dots < t_n \leq T$. And Chang [3] also extended the above results to those for conditional Yeh-Wiener integral of F given $X(x) = (x(s_1, t_1), \dots, x(s_m, t_n))$ where $0 = s_0 < s_1 < \dots < s_m \leq S$ and $0 = t_0 < t_1 < \dots < t_n \leq T$. But Yeh's inversion formulas for conditional Wiener and Yeh-Wiener integrals were very complicated to apply when conditioning functions were vector-valued.

In [7], Park and Skoug introduced a very simple formula for the conditional Wiener integral of F given $X(x) = (x(t_1), \dots, x(t_n))$. In particular, they expressed the conditional Wiener integral directly in terms of an ordinary Wiener integral. Also using this formula, they

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generalized the Kac-Feynman formula and obtained a conditional version of Cameron-Martin translation theorem involving vector-valued conditioning functions. Moreover they extended the conditional Wiener integral theory in [7] to the conditional Yeh-Wiener integral theory with vector-valued conditioning functions [8].

The purpose of this paper is to develop an useful formula to convert conditional Yeh-Wiener integrals of generalized conditioning functions into ordinary Yeh-Wiener integrals and then to obtain various evaluation formulas of conditional Yeh-Wiener integrals for these generalized conditioning functions.

2. Preliminaries

Let $(C_2(Q), \mathcal{Y}, m_y)$ denote Yeh-Wiener space where $C_2(Q)$ is the space of all continuous functions x on $Q = [0, S] \times [0, T]$ such that $x(0, t) = x(s, 0) = 0$ for every $(s, t) \in Q$.

Let $\{\alpha_{ij}\}$ be a complete orthonormal basis for $L_2(Q)$. Now we define the corresponding stochastic integrals

$$\gamma_{ij}(x) = \int_Q \alpha_{ij}(s, t) \tilde{dx}(s, t)$$

for $i = 1, 2, \dots$, and $j = 1, 2, \dots$ where $\int_Q \alpha_{ij}(s, t) \tilde{dx}(s, t)$ denotes the Paley-Wiener-Zygmund integral discussed in [2,4]. Then $\{\gamma_{ij}\}$ forms a set of independent standard Gaussian random variables on $C_2(Q)$ with

$$(2.1) \quad E[x(s, t)\gamma_{ij}(x)] = \int_0^s \int_0^t \alpha_{ij}(u, v) dudv \equiv \beta_{ij}(s, t).$$

For each m and $n \in \mathbb{N}$, let $X_{mn} : C_2(Q) \rightarrow \mathbb{R}^{mn}$ be the conditioning function defined by

$$(2.2) \quad X_{mn}(x) = (\gamma_{11}(x), \dots, \gamma_{1n}(x), \dots, \gamma_{m1}(x), \dots, \gamma_{mn}(x)).$$

Let $\mathcal{F}_{mn}^* = \{X_{mn}^{-1}(B) | B \in \mathcal{B}^{mn}\}$ where \mathcal{B}^{mn} denotes the σ -algebra of Borel sets in \mathbb{R}^{mn} . Then by the definition of conditional expectations

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(see Doob [6], Tucker [10] and Yeh [13]), for each $F \in L_1(C_2(Q), m_y)$,

$$\begin{aligned}
 (2.3) \quad \mu(B) &\equiv \int_{X_{mn}^{-1}(B)} F(x) m_y(dx) \\
 &= \int_{X_{mn}^{-1}(B)} E[F|\mathcal{F}_{mn}^*] m_y(dx) \\
 &= \int_B E[F(x)|X_{mn}(x) = \vec{\xi}] P_{X_{mn}}(d\vec{\xi})
 \end{aligned}$$

where $P_{X_{mn}}(B) \equiv m_y(X_{mn}^{-1}(B))$ and $E[F(X)|X_{mn}(x) = \vec{\xi}]$ is a Lebesgue measurable function of $\vec{\xi}$ which is unique up to null sets in \mathbb{R}^{mn} .

Let X_k^* be the conditioning function defined by

$$(2.4) \quad X_k^*(x) = (\gamma_{11}(x), \dots, \gamma_{1k-1}(x), \gamma_{2k-2}(x), \dots, \gamma_{k-11}(x))$$

for $k = 2, 3, \dots$ and let $X_\infty : C_2(Q) \rightarrow \mathbb{R}^\infty$ be defined by

$$(2.5) \quad X_\infty(x) = (\gamma_{11}(x), \gamma_{12}(x), \gamma_{21}(x), \gamma_{13}(x), \gamma_{22}(x), \gamma_{31}(x), \dots).$$

Then X_k^* is equal to X_{mn} if $mn = \frac{k(k-1)}{2}$. Let \mathcal{F}_k^* be the σ -algebra generated by the sets $\{X_k^{*-1}(B) | B \in \mathcal{B}^{\frac{k(k-1)}{2}}\}$ and let \mathcal{F}^* be the σ -algebra generated by $\bigcup_{k=1}^{\infty} \mathcal{F}_k^*$. Then $\{\mathcal{F}_k^*\}$ is an increasing sequence of σ -algebras of Yeh-Wiener measurable sets, hence for Yeh-Wiener integrable function F , $\{E[F|\mathcal{F}_k^*]\}$ is an martingale sequence. Thus $E|E[F|\mathcal{F}_k^*]| \leq E|F||\mathcal{F}_k^*| \leq E|F|$, for every k , and so by the martingale convergence theorem,

$$(2.6) \quad \lim_{k \rightarrow \infty} E[F|\mathcal{F}_k^*] = E[F|\mathcal{F}^*]$$

almost surely and for every $A \in \bigcup_{k=2}^{\infty} \mathcal{F}_k^*$,

$$(2.7) \quad \lim_{k \rightarrow \infty} \int_A E[F(x)|\mathcal{F}_k^*] m_y(dx) = \int_A E[F(x)|\mathcal{F}^*] m_y(dx).$$

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From this and definition of conditional expectations, it follows that for every Borel set B in \mathbb{R}^n

(2.8)

$$\begin{aligned} & \int_B E[F(x)|\gamma_{ij}(x) = \xi_{ij} \ i = 1, 2, \dots \ j = 1, 2, \dots] P_{X_\infty}(d\vec{\xi}) \\ &= \lim_{k \rightarrow \infty} \int_B E[F(x)|\gamma_{ij}(x) = \xi_{ij} \ i + j \leq k] P_{X_k^*}(d\vec{\xi}), \end{aligned}$$

where

$$(2.9) \quad \begin{aligned} P_{X_k^*}(d\vec{\xi}) &= \prod_{l=2}^k \prod_{i+j=l} \left\{ (2\pi)^{-\frac{1}{2}} \exp\left(-\frac{\xi_{ij}^2}{2}\right) d\xi_{ij} \right\}, \\ P_{X_\infty}(d\vec{\xi}) &= \prod_{l=2}^\infty \prod_{i+j=l} \left\{ (2\pi)^{-\frac{1}{2}} \exp\left(-\frac{\xi_{ij}^2}{2}\right) d\xi_{ij} \right\}. \end{aligned}$$

3. A Simple Fomular for Conditional Yeh-Wiener Integrals

Let $\{\alpha_{ij}\}$ and $\{\gamma_{ij}(x)\}$ be as in Section 2. Now we define the projection map $P_{(mn)}$ from $L_2(Q)$ into $L_2(Q)$ by

$$(3.1) \quad P_{(mn)} h(s, t) = \sum_{i=1}^m \sum_{j=1}^n (h, \alpha_{ij}) \alpha_{ij}(s, t).$$

For $x \in C_2(Q)$ and $\vec{\xi} = (\xi_{11}, \dots, \xi_{1n}, \dots, \xi_{m1}, \dots, \xi_{mn})$, let

$$(3.2) \quad \begin{aligned} x_{(mn)}(s, t) &= \int_Q P_{(mn)} I_{[0,s] \times [0,t]}(u, v) \tilde{dx}(u, v) \\ &= \sum_{i=1}^m \sum_{j=1}^n \gamma_{ij}(x) \int_0^s \int_0^t \alpha_{ij}(u, v) du dv \end{aligned}$$

and

$$\vec{\xi}_{(mn)}(s, t) = \sum_{i=1}^m \sum_{j=1}^n \xi_{ij} \int_{[0,s] \times [0,t]} \alpha_{ij}(u, v) du dv$$

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where $I_{[0,s] \times [0,t]}$ is the indicator function of $[0,s] \times [0,t]$ for $(s,t) \in Q$. Similarly, we define the projection map $P_\infty : L_2(Q) \rightarrow L_2(Q)$ by

$$P_\infty h(s,t) = \sum_{k=2}^{\infty} \sum_{i+j=k} (h, \alpha_{ij}) \alpha_{ij}(s,t).$$

For $x \in C_2(Q)$ and $\vec{\xi} = (\xi_{11}, \xi_{12}, \xi_{21}, \xi_{13}, \xi_{22}, \xi_{31}, \dots)$, let

$$\begin{aligned} (3.3) \quad x_\infty(s,t) &= \int_Q P_\infty I_{[0,s] \times [0,t]}(u,v) dx(u,v) \\ &= \sum_{k=2}^{\infty} \sum_{i+j=k} \gamma_{ij}(x) \int_0^s \int_0^t \alpha_{ij}(u,v) dudv \end{aligned}$$

and

$$\vec{\xi}_\infty(s,t) = \sum_{k=1}^{\infty} \sum_{i+j=k} \xi_{ij} \int_0^s \int_0^t \alpha_{ij}(u,v) dudv.$$

THEOREM 3.1. If $\{x(s,t)|(s,t) \in Q\}$ is the standard Yeh-Wiener process, then the processes $\{x(s,t) - x_\infty(s,t)|(s,t) \in Q\}$ and $\gamma_{ij}(x)$ are independent for $i = 1, \dots, j = 1, \dots$. Also, $\{x(s,t) - x_{(mn)}(s,t)|(s,t) \in Q\}$ and $\gamma_{ij}(x)$ are independent for $i = 1, \dots, m$ and $j = 1, \dots, n$.

Proof. For each i and j , we know that $E[\gamma_{ij}(x)(x(s,t) - x_\infty(s,t))] = 0$. Since both $\gamma_{ij}(x)$ and $x(s,t) - x_\infty(s,t)$ are Gaussian, it follows that they are independent. The second argument follows in the same manner. \square

COROLLARY 3.2. The processes $\{x(s,t) - x_\infty(s,t)|(s,t) \in Q\}$ and $\{x_\infty(s,t)|(s,t) \in Q\}$ are independent, and so are $\{x(s,t) - x_{(mn)}(s,t)|(s,t) \in Q\}$ and $\{x_{(mn)}(s,t)|(s,t) \in Q\}$.

The following theorem plays an important role in the development of a simple formula for conditional Yeh-Wiener integrals of generalized conditioning functions.

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THEOREM 3.3. *Let F be an Yeh-Wiener integrable function. Then*

$$(3.4) \quad \begin{aligned} & E[F(x)|\gamma_{ij}(x) = \xi_{ij}, i = 1, 2, \dots, j = 1, 2, \dots] \\ &= E[F(x - x_\infty + \vec{\xi}_\infty)], \text{ and} \\ & E[F(x)|\gamma_{ij}(x) = \xi_{ij}, i = 1, \dots, m, j = 1, \dots, n] \\ &= E[F(x - x_{(mn)} + \vec{\xi}_{(mn)})]. \end{aligned}$$

Proof. Using the results of Theorem 3.1 and Corollary 3.2, we have

$$\begin{aligned} & E[F(x)|\gamma_{ij}(x) = \xi_{ij}, i = 1, 2, \dots, j = 1, 2, \dots] \\ &= E[F(x - x_\infty + x_\infty)|\gamma_{ij}(x) = \xi_{ij}, i = 1, 2, \dots, j = 1, 2, \dots] \\ &= E_y\{F(y - y_\infty + \vec{\xi}_\infty)\} = E[F(x - x_\infty + \vec{\xi}_\infty)]. \end{aligned}$$

Also the second formula of (3.4) follows by the same reasoning. \square

COROLLARY 3.4. *Let F be an Yeh-Wiener integrable function. Then*

$$E[F(x)|\gamma_{ij}(x) = \xi_{ij}, i = 1, 2, \dots, j = 1, 2, \dots] = F(\vec{\xi}_\infty).$$

The following corollary is an immediate consequence of the second formula in Theorem 3.3.

COROLLARY 3.5. *If F is an Yeh-Wiener integrable function, then for every Borel measurable set B in \mathbb{R}^{mn} ,*

$$(3.5) \quad \int_{X_{mn}^{-1}(B)} F(x)m_y(dx) = \int_B E[F(x - x_{(mn)} + \vec{\xi}_{(mn)})]P_{X_{mn}}(d\vec{\xi}).$$

REMARK 3.6. For each partition $\tau \equiv \tau_{mn} = \{(s_1, t_1), \dots, (s_m, t_n)\}$ with $0 = s_0 < s_1 < \dots < s_m = S$ and $0 = t_0 < t_1 < \dots < t_n = T$, let $X_\tau : C_2(Q) \rightarrow \mathbb{R}^{mn}$ be defined by $X_\tau(x) = (x(s_1, t_1), \dots, x(s_m, t_n))$. In [8] they considered vector-valued conditional Yeh-Wiener integrals of the type $E[F(x)|X_\tau(x) = \vec{\xi}]$ for Yeh-Wiener integrable function F .

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We next find the relationship between the ordinary conditioning function X_τ and the generalized conditioning function X_{mn} . If we define $\alpha_{ij}(s, t) = \frac{I_{[s_{i-1}, s_i] \times [t_{j-1}, t_j]}(s, t)}{\sqrt{(s_i - s_{i-1}) \times (t_j - t_{j-1})}}$, then

$$\begin{aligned} E[F(x)|X_\tau(x) = \xi] &= E\left[F(x)|X_{mn}(x)\right] \\ &= \frac{\xi_{ij} - \xi_{i-1,j} - \xi_{i,j-1} + \xi_{i-1,j-1}}{\sqrt{(s_i - s_{i-1}) \times (t_j - t_{j-1})}}, \quad i = 1, \dots, m, \quad j = 1, \dots, n \end{aligned}$$

where $\xi_{0j} = \xi_{i0} = 0$ for $i = 1, \dots, m$ and $j = 1, \dots, n$.

4. Evaluation Formulas of Conditional Yeh-Wiener Integrals

In this section we establish various evaluation formulas of conditional Yeh-Wiener integrals for generalized conditioning functions.

Using the same notation as in Section 3, for $h \in L_2(Q)$, let

$$(4.1) \quad h_{(mn)}(s, t) = P_{(mn)}h(s, t) = \sum_{i=1}^m \sum_{j=1}^n (h, \alpha_{ij}) \alpha_{ij}(s, t),$$

and

$$h_{(\infty)}(s, t) = P_\infty h(s, t) = \sum_{k=2}^{\infty} \sum_{i+j=k} (h, \alpha_{ij}) \alpha_{ij}(s, t).$$

The following propositions give interesting relationships involving h , $h_{(mn)}$, x and $x_{(mn)}$ that are very useful in computing conditional and ordinary expectations of functions including the stochastic integral $\int_Q h(s, t) \tilde{dx}_{(mn)}(s, t)$.

PROPOSITION 4.1. Let $h \in L_2(Q)$. Then

$$(4.2) \quad \int_Q h(s, t) h_{(mn)}(s, t) dsdt = \int_Q h_{(mn)}^2(s, t) dsdt,$$

and also the above formula holds when $mn = \infty$.

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PROPOSITION 4.2. *Let $h \in L_2(Q)$. Then for each $x \in C_2(Q)$*

$$(4.3) \quad \begin{aligned} \int_Q h(s, t) \tilde{dx}_{(mn)}(s, t) &= \int_Q h_{(mn)}(s, t) \tilde{dx}(s, t) \\ &= \int_Q h_{(mn)}(s, t) \tilde{dx}_{(mn)}(s, t), \end{aligned}$$

and the above formula also holds for $mn = \infty$ if we consider $\int_Q h(s, t) \tilde{dx}_\infty(s, t) = \sum_{k=2}^{\infty} \sum_{i+j=k} \gamma_{ij}(x)(h, \alpha_{ij})$.

Proof. It follows from the fact that the above integrals have the same value $\sum_{i=1}^m \sum_{j=1}^n \gamma_{ij}(x)(h, \alpha_{ij})$. \square

THEOREM 4.3. *Let $h \in L_2(Q)$, and assume that*

$$F(x) = f \left[\int_Q h(s, t) \tilde{dx}(s, t) \right]$$

is in $L_1(C_2(Q), m_y)$.

(i) *If $\{h, \alpha_{11}, \dots, \alpha_{mn}\}$ is a linearly dependent set of functions in $L_2(Q)$, say $h(s, t) = \sum_{i=1}^m \sum_{j=1}^n c_{ij} \alpha_{ij}(s, t)$ on Q , then*

$$(4.4) \quad E \left[f \left[\int_Q h(s, t) \tilde{dx}(s, t) \right] | X_{mn}(x) = \vec{\xi} \right] = f \left(\sum_{i=1}^m \sum_{j=1}^n c_{ij} \xi_{ij} \right).$$

(ii) *If $\{h, \alpha_{11}, \dots, \alpha_{mn}\}$ is a linearly independent set of functions in $L_2(Q)$, then*

$$(4.5) \quad \begin{aligned} E \left[f \left[\int_Q h(s, t) \tilde{dx}(s, t) \right] | X_{mn}(x) = \vec{\xi} \right] &= \left[2\pi \left(\|h\|^2 - \|h_{(mn)}\|^2 \right) \right]^{-\frac{1}{2}} \\ &\times \int_{\mathbb{R}} f(u) \exp \left\{ - \frac{(u - \int_Q h(s, t) d\vec{\xi}_{(mn)}(s, t))^2}{2\|h - h_{(mn)}\|^2} \right\} du. \end{aligned}$$

Proof. (i). Using Theorem 3.3 and Proposition 3.2, we have

$$\begin{aligned}
 & E\left[f\left[\int_Q h(s,t) \tilde{dx}(s,t)\right] | X_{mn}(x) = \vec{\xi}\right] \\
 &= E\left[f\left[\int_Q h(s,t) \{\tilde{d}(x - x_{(mn)} + \xi_{(mn)})\}(s,t)\right]\right] \\
 &= E\left[f\left[\int_Q \left(h(s,t) - h_{(mn)}(s,t)\right) \tilde{dx}(s,t) + \int_Q h(s,t) d\vec{\xi}_{(mn)}(s,t)\right]\right] \\
 &= f\left[\int_Q h(s,t) \left\{d\left(\sum_{i=1}^m \sum_{j=1}^n \xi_{ij} \int_0^s \int_0^t \alpha_{ij}(u,v) du dv\right)\right\}(s,t)\right] \\
 &= f\left(\sum_{i=1}^m \sum_{j=1}^n \xi_{ij} c_{ij}\right).
 \end{aligned}$$

(ii). In this case, we use (3.4), (4.3) and a well known Yeh-Wiener integration formula to obtain

$$\begin{aligned}
 & E\left[f\left[\int_Q h(s,t) \tilde{dx}(s,t)\right] | X_{mn}(x) = \vec{\xi}\right] \\
 &= E\left[f\left[\int_Q (h(s,t) - h_{(mn)}(s,t)) \tilde{dx}(s,t) + \int_Q h(s,t) d\vec{\xi}_{(mn)}(s,t)\right]\right] \\
 &= (2\pi)^{-\frac{1}{2}} \int_{\mathbb{R}} f\left(\|h - h_{(mn)}\|v + \int_Q h(s,t) d\vec{\xi}_{(mn)}(s,t)\right) \exp\left\{-\frac{v^2}{2}\right\} dv \\
 &= [2\pi(\|h - h_{(mn)}\|^2)]^{-\frac{1}{2}} \\
 &\quad \times \int_{\mathbb{R}} f(u) \exp\left\{-\frac{(u - \int_Q h(s,t) d\vec{\xi}_{(mn)}(s,t))^2}{2\|h - h_{(mn)}\|^2}\right\} du. \quad \square
 \end{aligned}$$

The following two corollaries are the special cases of Theorem 4.3 when $h \equiv \alpha_{ij}$ for some i and j or when h is orthogonal to all the α_{ij} 's.

COROLLARY 4.4. Let h, F and f be as in Theorem 4.3. Then

$$(4.6) \quad E\left[f\left[\int_Q \alpha_{ij}(s,t) \tilde{dx}(s,t)\right] | X_{mn}(x) = \vec{\xi}\right] = f(\xi_{ij}),$$

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while if $\{h, \alpha_{11}, \dots, \alpha_{mn}\}$ is an orthogonal set of functions in $L_2(Q)$,

$$\begin{aligned}
(4.7) \quad & E \left[f \left[\int_Q h(s, t) \tilde{dx}(s, t) \right] | X_{mn}(x) = \vec{\xi} \right] \\
&= (2\pi \|h\|^2)^{-\frac{1}{2}} \int_{\mathbb{R}} f(u) \exp \left\{ -\frac{u^2}{2\|h\|^2} \right\} du \\
&= E \left[f \left[\int_Q h(s, t) \tilde{dx}(s, t) \right] \right].
\end{aligned}$$

Proceeding as above, we obtain the following formula which is a generalization of (4.7).

COROLLARY 4.5. If $\{\phi_{11}, \dots, \phi_{kl}, \alpha_{11}, \dots, \alpha_{mn}\}$ is an orthonormal set of functions in $L_2(Q)$ and

$$F(x) = f \left[\int_Q \phi_{11}(s, t) \tilde{dx}(s, t), \dots, \int_Q \phi_{kl}(s, t) \tilde{dx}(s, t) \right]$$

is an Yeh-Wiener integrable function, then

$$\begin{aligned}
& E \left[f \left[\int_Q \phi_{11}(s, t) \tilde{dx}(s, t), \dots, \int_Q \phi_{kl}(s, t) \tilde{dx}(s, t) \right] | X_{mn}(x) = \vec{\xi} \right] \\
&= E \left[f \left[\int_Q \phi(s, t) \tilde{dx}(s, t), \dots, \int_Q \phi_{kl}(s, t) \tilde{dx}(s, t) \right] \right] \\
&= (2\pi)^{-\frac{kl}{2}} \int_{\mathbb{R}^{kl}} f(u_{11}, \dots, u_{kl}) \exp \left\{ -\sum_{i=1}^k \sum_{j=1}^l \frac{u_{ij}^2}{2} \right\} d\vec{u}
\end{aligned}$$

where $\vec{u} = (u_{11}, \dots, u_{kl})$.

Our next corollary follows from the fact that $\int_Q (h(s, t) - h_{(mn)}(s, t)) d\vec{\xi}_{(mn)}(s, t) = 0$ and $(h - h_{(mn)})_{(mn)}(s, t) = 0$.

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COROLLARY 4.6. Let h, F and f be as in Theorem 4.2. Then

$$\begin{aligned} & E \left[f \left[\int_Q h(s, t) \tilde{d}(x(s, t) - x_{(mn)}(s, t)) \right] | X_{mn}(x) = \xi \right] \\ &= E \left[f \left[\int_Q (h(s, t) - h_{(mn)}(s, t)) \tilde{dx}(s, t) \right] \right] \\ &= \left[2\pi \|h - h_{(mn)}\|^2 \right]^{-\frac{1}{2}} \int_{\mathbb{R}} f(u) \exp \left\{ -\frac{u^2}{2\|h - h_{(mn)}\|^2} \right\} du. \end{aligned}$$

Many interesting examples of conditional Yeh-Wiener integrals are obtained as special cases of the following theorem.

THEOREM 4.7. Let $g \in L_2(Q)$. Then

$$\begin{aligned} & E \left[\exp \left\{ \int_Q g(s, t) x(s, t) dsdt \right\} | X_{mn}(x) = \xi \right] \\ &= \exp \left\{ \sum_{i=1}^m \sum_{j=1}^n \xi_{ij}(g, \beta_{ij}) + \frac{1}{2} \int_Q \left[\int_t^T \int_s^S g(u, v) du dv \right]^2 dsdt \right. \\ &\quad \left. - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n (g, \beta_{ij})^2 \right\}. \end{aligned}$$

Proof. Using the integration by parts formula, it follows that

$$\int_Q g(s, t) x(s, t) dsdt = \int_Q \left[\int_t^T \int_s^S g(u, v) du dv \right] \tilde{dx}(s, t)$$

and that

$$\begin{aligned} & \int_Q \left[\int_t^T \int_s^S g(u, v) du dv \right] \alpha_{ij}(s, t) dsdt \\ &= \int_Q g(s, t) \beta_{ij}(s, t) dsdt = (g, \beta_{ij}). \end{aligned}$$

Hence using Theorem 3.3, we obtain

$$\begin{aligned}
 & E\left[\exp\left\{\int_Q g(s, t)x(s, t) ds dt\right\} | X_{mn}(x) = \vec{\xi}\right] \\
 &= E\left[\exp\left[\int_Q \left[\int_t^T \int_s^S g(u, v) du dv\right] \{\tilde{d}(x - x_{(mn)}) - \vec{\xi}_{(mn)}\}(s, t)\right.\right. \\
 &= \exp\left\{\sum_{i=1}^m \sum_{j=1}^n \xi_{ij} \left[\int_Q \left[\int_t^T \int_s^S g(u, v) du dv\right] \alpha_{ij}(s, t) ds dt\right]\right\} \\
 & E\left[\exp \int_Q \left[\int_t^T \int_s^S g(u, v) du dv\right] \tilde{d}x(s, t) \right. \\
 & \quad \left. - \sum_{i=1}^m \sum_{j=1}^n \gamma_{ij}(x) \left[\int_Q \left[\int_t^T \int_s^S g(u, v) du dv\right] \alpha_{ij}(s, t) ds dt\right]\right] \\
 &= \exp\left\{\sum_{i=1}^m \sum_{j=1}^n \xi_{ij}(g, \beta_{ij}) + \frac{1}{2} \int_Q \left[\int_t^T \int_s^S g(u, v) du dv\right]^2 ds dt \right. \\
 & \quad \left. - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n (g, \beta_{ij})^2\right\}.
 \end{aligned}$$

□

The following corollary is a special case of Theorem 4.7.

COROLLARY 4.8. Let $g(s, t) = 1$ and $\alpha_{ij}(u, v) = \frac{I_{[s_{i-1}, s_i] \times [t_{j-1}, t_j]}(u, v)}{\sqrt{(s_i - s_{i-1})(t_j - t_{j-1})}}$.

Then

$$\begin{aligned}
 & E\left[\exp\left\{\int_Q x(s, t) ds dt\right\} | X_{mn}(x) = \vec{\xi}\right] \\
 &= \exp\left\{\sum_{i=1}^m \sum_{j=1}^n \xi_{ij} \sqrt{(s_i - s_{i-1})(t_j - t_{j-1})} \right. \\
 & \quad \left(\left(S - \frac{1}{2}s_i - \frac{1}{2}s_{i-1}\right)\left(T - \frac{1}{2}t_j - t_{j-1}\right) + \frac{1}{18}S^3T^3 \right. \\
 & \quad \left. - \frac{1}{32} \sum_{i=1}^m \sum_{j=1}^n (s_i - s_{i-1})(t_j - t_{j-1})(s_i + s_{i-1})^2(t_j + t_{j-1})^2\right\}.
 \end{aligned}$$

Evaluation formulas of conditional Yeh-Wiener integrals

Using Theorem 4.7 and Corollary 4.8 we obtain various formulas for conditional Yeh-Wiener integrals.

COROLLARY 4.9. If $m = 1, n = 1$ and $\alpha_{11}(s, t) = \frac{1}{\sqrt{ST}}$, then

$$\begin{aligned} & E \left[\exp \left\{ \int_Q g(s, t) x(s, t) ds dt \right\} | x(S, T) = \xi \right] \\ &= \exp \left\{ \frac{\xi}{ST} \int_Q st g(s, t) ds dt + \frac{1}{2} \int_Q \left[\int_t^T \int_s^S g(u, v) du dv \right]^2 ds dt \right. \\ &\quad \left. - \frac{1}{2ST} \left[\int_Q st g(s, t) ds dt \right]^2 \right\}, \end{aligned}$$

$$\begin{aligned} & E \left[\exp \left\{ \int_Q st x(s, t) ds dt \right\} | x(S, T) = \xi \right] \\ &= \exp \left\{ \frac{\xi}{9} S^2 T^2 + \frac{11}{4050} S^5 T^5 \right\}, \end{aligned}$$

and

$$\begin{aligned} & E \left[\exp \left\{ \int_Q x(s, t) ds dt \right\} | x(S, T) = \xi \right] \\ &= \exp \left\{ \frac{\xi}{4} ST + \frac{7}{288} S^3 T^3 \right\}. \end{aligned}$$

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