HARDY’S INEQUALITY RELATED TO A BERNOULLI EQUATION

JUNG-SOON HYUN AND SANG DONG KIM

ABSTRACT. The weighted Hardy’s inequality is known as

\[ \int_a^b |u(x)|^p r(x) dx \leq C \int_a^b |u'(x)|^p s(x) dx \]

where \(-\infty \leq a \leq b \leq \infty\) and \(1 < p < \infty\). The purpose of this article is to provide a useful formula to express the weight \(r(x)\) in terms of \(s(x)\) or vice versa employing a Bernoulli equation having the other weight as coefficients.

1. Introduction

The classical Hardy’s inequality [7] states that for \(1 < p < \infty\) and \(\epsilon \neq p - 1\),

\[ \int_0^\infty |u(x)|^p x^{p-\epsilon} dx \leq \left( \frac{p}{\epsilon - p + 1} \right)^p \int_0^\infty |u'(x)|^p x^{\epsilon} dx \]

provided \(u(0) = 0\) for \(\epsilon < p - 1\) and \(u(\infty) = 0\) for \(\epsilon > p - 1\). For singular value \(\epsilon = p - 1\) for the Hardy’s inequality (1.1), Kadlec and Kufner [6] showed

\[ \int_0^1 |u(x)|^p x^{1-\epsilon} \log x dx \leq C_p \int_0^1 |u'(x)|^p x^{p-1} dx. \]

This inequality asks for which weights \(r(x)\) and \(s(x)\) the following inequality

\[ \int_a^b |u(x)|^p r(x) dx \leq C \int_a^b |u'(x)|^p s(x) dx \]

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holds. For this question, Muckenhoupt [8] showed that the formula (1.3)
holds if and only if

\[
\sup_{0 \leq t \leq \infty} \left( \int_{t}^{\infty} |r(x)|^p dx \right)^{1/p} \left( \int_{0}^{t} |s(x)|^q dx \right)^{1/q} = K < \infty
\]

and \( K \leq C \leq K p^{rac{k}{p}} q^{rac{k}{q}} \) where \( \frac{1}{p} + \frac{1}{q} = 1 \). In a more general setting,
Gurka [5] gave a necessary and sufficient condition for the weights \( r(x) \)
and \( s(x) \), for which

\[
\int_{0}^{\infty} |u(x)|^p r(x) dx \leq C \int_{0}^{\infty} |u'(x)|^q s(x) dx
\]

holds for \( 1 < p \leq q < \infty \). Kufner and Triebel [7] also gave explicit
formulae for \( r(x) \) and \( s(x) \) for the case \( p = q \). In this article, we derive
a simple formula such as

\[
r(x) = s(x)^{-\frac{1}{p-1}} \left( c + \frac{1}{K(p-1)} \int s(x)^{-\frac{1}{p-1}} dx \right)^{-p},
\]

which is the solution of a Bernoulli equation (see (2.4)), to find one
weight function for a given other weight function. An application of
such a formula can be used in a process showing coercivity of variational
formulation arisen in spectral method (see [1], [4]) in an area of numerical
partial differential equations. For this purpose, we use the formula above
with Jacobi weights \( s(x) = (1-x)^a(1-x)^b \), \( (a, b > -1) \) to set Hardy’s
inequality with corresponding weights, \( r(x) \) in this last section. For
\(-1 < a, b < 1 \), the Hardy’s inequality is found in [3, p. 91] for example.

2. Hardy’s inequality and a Bernoulli equation

In this section, we relate two weights \( r(x) \) and \( s(x) \) in the weighted
Hardy’s inequality (1.3) in terms of a Bernoulli equation, that is, one
weight is a solution of a Bernoulli equation with coefficients as other
weight.

**Proposition 2.1.** Let \( 1 < p < \infty \) and \(-\infty \leq a \leq b \leq \infty \). Suppose
\( r(x) > 0 \) and \( s(x) > 0 \). Assume

\[
\int_{a}^{b} |f(x)|^p s(x) dx < \infty.
\]
Then

\[(2.1) \quad \left( \int_a^b \left( \int_a^x |f(t)| dt \right)^p r(x) dx \right)^{1/p} \leq K_p \left( \int_a^b |f(x)|^p s(x) dx \right)^{1/p} \]

holds if

\[(2.2) \quad r(x)^{-\frac{p-1}{p}} s(x)^{-\frac{1}{p}} \int_x^b r(t) dt = K < \infty, \]

where \(K\) is a constant.

\[\text{Proof. For each } \epsilon > 0 \text{ define} \]

\[F_\epsilon(x) = \int_a^x |f_\epsilon(t)| dt \]

where \(f_\epsilon(t) = f(t)\) for \(a + \epsilon \leq x \leq b - \epsilon\) and 0 otherwise. Since

\[F_\epsilon(x)^p = \int_a^x (F_\epsilon(t)^p)' dt = p \int_a^x F_\epsilon(t)^{p-1} |f_\epsilon(t)| dt, \]

by using Fubini’s theorem and Hölder’s inequality and (2.2) we have

\[\int_a^b F_\epsilon(x)^p r(x) dx \]

\[= p \int_a^b \int_a^x F_\epsilon(t)^{p-1} |f_\epsilon(t)| r(x) dt dx \]

\[= p \int_a^b F_\epsilon(x)^{p-1} |f_\epsilon(x)| \int_x^b r(t) dt dx \]

\[= p \int_a^b \left[ (F_\epsilon(x)r(x)^{\frac{1}{p}})^{p-1} \left( |f_\epsilon(x)| s(x)^{\frac{1}{p}} \right) r(x)^{-\frac{p-1}{p}} s(x)^{-\frac{1}{p}} \int_x^b r(t) dt \right] dx \]

\[\leq K_p \left( \int_a^b F_\epsilon(x)^p r(x) \right)^{\frac{1}{q}} \left( \int_a^b |f_\epsilon(x)|^p s(x) dx \right)^{\frac{1}{p}} \]

where \(\frac{1}{p} + \frac{1}{q} = 1\). Hence this implies

\[\left( \int_a^b F_\epsilon(x)^p r(x) dx \right)^{\frac{1}{p}} \leq K_p \left( \int_a^b |f_\epsilon(x)|^p s(x) dx \right)^{\frac{1}{p}}. \]

Finally, applying the Dominated Convergence Theorem yields (2.1). \(\square\)

From the relation (2.2), it is obvious to find \(s(x)\) for given \(r(x)\) and \(K\). Conversely if \(s(x)\) and \(K\) are given, we can find \(r(x)\) in the following way:
Theorem 2.2. For a given weight \( s(x) \) and a constant \( K \), if \( r(x) \) satisfy (2.2), then \( r(x) \) is given by
\[
(2.3) \quad r(x) = s(x)^{\frac{1}{p-1}} \left( c + \frac{1}{K(p-1)} \int s(x)^{-\frac{1}{p-1}} \, dx \right)^{-p}
\]
which is a solution of a Bernoulli equation,
\[
(2.4) \quad r'(x) + \frac{1}{p-1} (\log s(x))^r r(x) = -\frac{p}{p-1} \frac{1}{K} s(x)^{-\frac{1}{p-1}} r(x)^{1+\frac{1}{p}}
\]
where \( c \) is an arbitrary constant.

Proof. By differentiating (2.2), we have a nonlinear equation (2.4) which is of Bernoulli equation and it is well known that the general solution is given by (2.3).

The formula (2.3) provides the way to get other weight for a given weight in the Hardy’s inequality (1.3). As applications of the above theorem, we present two corollaries, which imply the classical case (1.1) and the singular case (1.2) by choosing particular weight \( s(x) \) in the formula (2.3).

Corollary 2.3. Let \( 1 < p < \infty \), and \( \epsilon \neq p - 1 \). Let \( u(x) \) be a function differentiable almost everywhere on \((0, \infty)\) and such that
\[
\int_0^\infty |u'(x)|^p x^\epsilon \, dx < \infty.
\]
Moreover, let \( u(0) = 0 \) for \( \epsilon < p - 1 \) and \( u(\infty) = 0 \) for \( \epsilon > p - 1 \). If \( s(x) = x^\epsilon \), then the classical inequality (1.1) holds.

Proof. Consider the case \( \epsilon < p - 1 \). By choosing \( f(x) = u'(x) \) in (2.1) and \( c = 0 \) in (2.3), \( r(x) \) is given by
\[
\left( \frac{1}{K(p-1-\epsilon)} \right)^{-p} x^{\epsilon-p}.
\]
Putting \( r(x) \) into (2.1) we have
\[
\left( \int_0^\infty |u(x)|^p x^{\epsilon-p} \, dx \right)^{\frac{1}{p}} \leq -\frac{p}{p-1-\epsilon} \left( \int_0^\infty |u'(x)|^p x^\epsilon \, dx \right)^{\frac{1}{p}}.
\]
For the case \( \epsilon > p-1 \), the same argument works with \( F_x(t) = \frac{b}{x} |f_x(t)| \, dt \). Hence, combining these two cases yields (1.1).

Corollary 2.4. Let \( 1 < p < \infty \), and \( u(0) = 0 \). If \( s(x) = x^{p-1} \), then the classical inequality for the singular case (1.2) holds for \( a = 0 \) and \( b = 1 \).
Proof. For \( s(x) = x^{p-1} \), \( r(x) \) in (2.3) is now 
\[
\left( K \frac{1}{p-1} \right)^{-p} \frac{1}{x} |\log x|^{-p},
\]
which is a singular case (1.2). \( \square \)

3. Hardy’s inequalities with Jacobi weights

In this section, we take Jacobi weights \( w(x) = (1-x)^a(1+x)^b \), \((a, b > -1)\) as an application due to the concise formula (2.3) for the corresponding Hardy’s inequalities used in spectral method, which is one of very accurate methods to approximate a solution for partial differential equation numerically, (see [1, 4]). For \(-1 < a, b < 1\), the following result (3.2) coincides with that in [3, p.91] and [2, p.378] for the first kind Chebyshev weight \( a = b = -\frac{1}{2} \), but we present Hardy’s inequality for a general Jacobi weights \((-1 < a, b < \infty)\) in the following theorem using a Bernoulli equation (2.4). Let \( p = 2 \) and \( s(x) = (1-x)^a \) on an interval \((-1, 1)\). By Theorem 2.2 when \( c = 0 \), \( r(x) \) is given by

\[
(3.1) \quad r(x) = \begin{cases} 
(K(1-a))^2(1-x)^{a-2}, & -1 < a < 1, \ a > 1, \\
K^2 \frac{1}{1-x} (\log(1-x))^{-2}, & a = 1, 
\end{cases}
\]

and we may have, for \( s(x) = (1+x)^b \),

\[
(3.1) \quad r(x) = \begin{cases} 
(K(1-a))^2(1+x)^{b-2}, & -1 < b < 1, \ b > 1, \\
K^2 \frac{1}{1+x} (\log(1+x))^{-2}, & b = 1. 
\end{cases}
\]

Note that for such pairs of \( r(x) \) and \( s(x) \), (2.2) is satisfied. Define a weight \( w_1(x) = r_a(x)r_b(x) \) where

\[
r_a(x) = \begin{cases} 
(1-x)^{a-2}, & -1 < a < 1, \ a > 1, \\
\frac{1}{1-x} (\log(1-x))^{-2}, & a = 1, 
\end{cases}
\]

and

\[
r_b(x) = \begin{cases} 
(1+x)^{b-2}, & -1 < b < 1, \ b > 1, \\
\frac{1}{1+x} (\log(1+x))^{-2}, & b = 1. 
\end{cases}
\]

Let \( H_{w,a}^1 = \{ u \in L^2(-1,1) | \int_{-1}^1 u(x)^2 w(x)dx < \infty, \int_{-1}^1 |u'(x)|^2 w(x)dx < \infty, \ u(-1) = u(1) = 0 \} \).
THEOREM 3.1. Let \( w_2(x) = (1 - x)^a(1 + x)^b \) where \( a > -1 \) and \( b > -1 \). Then for all \( u \in H^1_{w_2,0} \) we have the following Hardy’s inequality

\[
\int_{-1}^{1} u(x)^2 w_1(x) dx \leq C \int_{-1}^{1} u'(x)^2 w_2(x) dx
\]

where \( w_1(x) \) is defined above with suitable choice depending on \( a \) and \( b \), and \( C = 4 \max\{m_a^{-1}M_a(1 - b)^{-2}, m_b^{-1}M_b(1 - a)^{-2}\} \) for \( a, b \neq 1 \) and the constant \( C \) will not contain the term \((1 - a)^{-2}\) or \((1 - b)^{-2}\) for the case \( a = 1 \) or \( b = 1 \). The constants \( m_a, M_a, m_b \) and \( M_b \) are defined below.

Proof. For \( a, b \neq 1 \), applying Proposition 2.1 into two weights \( r(x) \) and \( s(x) \) in (3.1)

\[
\int_{0}^{1} u(x)^2 r_a(x) dx = (K(1 - a))^{-2} \int_{0}^{1} \left( \int_{x}^{1} u'(s) ds \right)^2 r(x) dx \leq 4(1 - a)^{-2} \int_{0}^{1} u'(x)^2 (1 - x)^a dx \leq 4m_b^{-1}(1 - a)^{-2} \int_{0}^{1} u'(x)^2 (1 - x)^a(1 + x)^b dx
\]

since \( m_b^{-1}(1 + x)^b \geq 1 \) on \([0, 1]\) where \( m_b = \min(1, 2^b) \). A similar argument shows

\[
\int_{-1}^{0} u(x)^2 r_b(x) dx \leq 4m_a^{-1}(1 - b)^{-2} \int_{0}^{1} u'(x)^2 (1 - x)^a(1 + x)^b dx
\]

so that the result (3.2) now follows from

\[
\int_{-1}^{1} u(x)^2 r(x) dx \leq M_a \int_{-1}^{0} u(x)^2 r_b(x) dx + M_b \int_{0}^{1} u(x)^2 r_a(x) dx
\]

where \( M_a = \max(1, 2^a) \) and \( M_b \), \( m_a \) are defined analogously. The proof for the case \( a = 1 \) or \( b = 1 \) is same. \( \square \)

References

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JUNG-SOON HYUN, FINANCIAL ENGINEERING RESEARCH CENTER, GRADUATE SCHOOL OF MANAGEMENT KAIST, SEOUL 130-012, KOREA
E-mail: jshyun@kgsm.kaist.ac.kr

SANG DONG KIM, DEPARTMENT OF MATHEMATICS EDUCATION, KYUNGPOOK NATIONAL UNIVERSITY, TAEGU 702-701, KOREA
E-mail: skim@sobolev.knu.ac.kr