ON G-INVARIANT MINIMAL HYPERSURFACES WITH CONSTANT SCALAR CURVATURE IN S^5

JAE-UP SO

ABSTRACT. Let $G = O(2) \times O(2) \times O(2)$ and let M^4 be a closed G-invariant minimal hypersurface with constant scalar curvature in S^5 . If M^4 has 2 distinct principal curvatures at some point, then S=4. Moreover, if S>4, then M^4 does not have simple principal curvatures everywhere.

Introduction

Let M^n be a closed minimally immersed hypersurface in the unit sphere S^{n+1} , and h its second fundamental form. Denote by R and S its scalar curvature and the square norm of h, respectively. It is well known that S = n(n-1) - R from the structure equations of both M^n and S^{n+1} . In particular, S is constant if and only if M has constant scalar curvature. In 1968, J. Simons [8] observed that if $S \leq n$ everywhere and S is constant, then $S \in \{0, n\}$. Clearly, M^n is an equatorial sphere if S = 0. And when S = n, M^n is indeed a product of spheres, due to the works of Chern, do Carmo, and Kobayashi [3] and Lawson [5].

We are interested in the following conjecture posed by Chern [9].

CHERN CONJECTURE. For any $n \geq 3$, the set R_n of the real numbers each of which can be realized as the constant scalar curvature of a closed minimally immersed hypersurface in S^{n+1} is discrete.

C. K. Peng and C. L. Terng [7] proved

THEOREM ([Peng and Terng, 1983]). Let M^n be a closed minimally immersed hypersurface with constant scalar curvature in S^{n+1} . If S > n, then S > n + 1/(12n).

Received July 11, 2001.

²⁰⁰⁰ Mathematics Subject Classification: 53C42.

Key words and phrases: scalar curvature, G-invariant minimal hypersurface, square norm.

S. Chang [2] proved the following theorem by showing that S=3 if S>3 and M^3 has multiple principal curvatures at some point.

THEOREM ([Chang, 1993]). A closed minimally immersed hypersurface with constant scalar curvature in S^4 is either an equatorial 3-sphere, a product of spheres, or a Cartan's minimal hypersurface. In particular, $R_n = \{0, 3, 6\}$.

H. Yang and Q. M. Cheng [10] proved

THEOREM ([Yang and Cheng, 1998]). Let M^n be a closed minimally immersed hypersurface with constant scalar curvature in S^{n+1} . If S > n, then $S \ge n + n/3$.

Let $G \simeq O(k) \times O(p) \times O(q) \subset O(k+p+q)$ and set k+p+q=n+2. Then W. Y. Hsiang [4] investigated G-invariant, minimal hypersurfaces, M^n in S^{n+1} , by studying their generating curves, M^n/G , in the orbit space S^{n+1}/G and proved

THEOREM ([Hsiang, 1987]). For each dimension $n \geq 3$, there exist infinitely many, mutually noncongruent closed G-invariant minimal hypersurfaces in S^{n+1} , where $G \simeq O(k) \times O(k) \times O(q)$ and k = 2 or 3.

We studied G-invariant minimal hypersurfaces, in stead of minimal ones, with constant scalar curvatures in S^5 . In this paper, we shall prove the following theorem:

THEOREM. Let M^4 be a closed G-invariant minimal hypersurface with constant scalar curvature in S^5 , where $G = O(2) \times O(2) \times O(2)$.

- (1) If M^4 has 2 distinct principal curvatures at some point, then S=4
- (2) If S > 4, then M^4 does not have simple principal curvatures everywhere.

1. Preliminaries

Let M^n be a manifold of dimension n immersed in a Riemannian manifold N^{n+1} of dimension n+1. Let $\overline{\nabla}$ and $\langle \,,\, \rangle$ be the connection and metric tensor respectively of N^{n+1} and let $\overline{\mathcal{R}}$ be the curvature tensor with respect to the connection $\overline{\nabla}$ on N^{n+1} . Choose a local orthonormal frame field e_1, \ldots, e_{n+1} in N^{n+1} such that after restriction to M^n , the e_1, \ldots, e_n are tangent to M^n . Denote the dual coframe by $\{\omega_A\}$. Here we will always use i, j, k, \ldots , for indices running over $\{1, 2, \ldots, n\}$ and

 A, B, C, \ldots , over $\{1, 2, \ldots, n+1\}$. As usual, the second fundamental form h and the mean curvature H of M^n in N^{n+1} are respectively defined by

$$h(v, w) = \langle \overline{\nabla}_v w, e_{n+1} \rangle$$
 and $H = \sum_i h(e_i, e_i)$.

And the scalar curvature \bar{R} of N^{n+1} is defined by

$$ar{R} = \sum_{A,B} \langle \bar{\mathcal{R}}(e_A, e_B) e_B, e_A \rangle.$$

Then the structure equations of N^{n+1} are given by

$$\begin{split} d\,\omega_A &= \sum_B \omega_{AB} \wedge \omega_B, \quad \omega_{AB} + \omega_{BA} = 0, \\ d\,\omega_{AB} &= \sum_C \omega_{AC} \wedge \omega_{CB} - \frac{1}{2} \sum_{C,D} K_{ABCD} \,\omega_C \wedge \omega_D, \end{split}$$

where $K_{ABCD} = \langle \bar{\mathcal{R}}(e_A, e_B)e_D, e_C \rangle$. When N^{n+1} is the unit sphere S^{n+1} , we have

$$K_{ABCD} = \delta_{AC} \, \delta_{BD} - \delta_{AD} \, \delta_{BC}.$$

Next, we restrict all tensors to M^n . First of all, $\omega_{n+1} = 0$ on M^n . Then

$$\sum_{i} \omega_{(n+1)i} \wedge \omega_i = d \, \omega_{n+1} = 0.$$

By Cartan's lemma, we can write

$$\omega_{(n+1)i} = -\sum_{j} h_{ij} \, \omega_{j}.$$

Here,

$$h_{ij} = -\omega_{(n+1)i}(e_j) = -\langle \overline{\nabla}_{e_j} e_{n+1}, e_i \rangle$$

= $\langle \overline{\nabla}_{e_i} e_i, e_{n+1} \rangle = h(e_j, e_i) = h(e_i, e_j).$

Second, from

$$\begin{split} d\,\omega_i &= \sum_j \omega_{ij} \wedge \omega_j, \quad \omega_{ij} + \omega_{ji} = 0, \\ d\,\omega_{ij} &= \sum_l \omega_{il} \wedge \omega_{lj} - \frac{1}{2} \sum_{l,m} R_{ijlm} \,\omega_l \wedge \omega_m, \end{split}$$

we find the curvature tensor of M^n is

(1.1)
$$R_{ijlm} = K_{ijlm} + h_{il} h_{jm} - h_{im} h_{jl}.$$

If M^n is a piece of minimally immersed hypersurface in the unit sphere S^{n+1} and R is the scalar curvature of M^n , then we have

$$(1.2) R = n(n-1) - S,$$

where $S = \sum_{i,j} h_{ij}^2$ is the square norm of h.

Given a symmetric 2-tensor $T = \sum_{i,j} T_{ij} \omega_i \omega_j$ on M^n , we also define its covariant derivatives, denoted by ∇T , $\nabla^2 T$ and $\nabla^3 T$, etc. with components $T_{ij,k}$, $T_{ij,kl}$ and $T_{ij,klp}$, respectively, as follows:

(1.3)
$$\sum_{k} T_{ij,k} \omega_{k} = d T_{ij} + \sum_{s} T_{sj} \omega_{si} + \sum_{s} T_{is} \omega_{sj},$$

$$\sum_{l} T_{ij,kl} \omega_{l} = d T_{ij,k} + \sum_{s} T_{sj,k} \omega_{si}$$

$$+ \sum_{s} T_{is,k} \omega_{sj} + \sum_{s} T_{ij,s} \omega_{sk},$$

$$\sum_{p} T_{ij,klp} \omega_{p} = d T_{ij,kl} + \sum_{s} T_{sj,kl} \omega_{si} + \sum_{s} T_{is,kl} \omega_{sj}$$

$$+ \sum_{s} T_{ij,sl} \omega_{sk} + \sum_{s} T_{ij,ks} \omega_{sl}.$$

In general, the resulting tensors are no longer symmetric, and the rule to switch sub-index obeys the Ricci formula as follows:

$$T_{ij,kl} - T_{ij,lk} = \sum_{s} T_{sj} R_{sikl} + \sum_{s} T_{is} R_{sjkl},$$

$$T_{ij,klp} - T_{ij,kpl} = \sum_{s} T_{sj,k} R_{silp} + \sum_{s} T_{is,k} R_{sjlp}$$

$$+ \sum_{s} T_{ij,s} R_{sklp},$$

$$T_{ij,klpm} - T_{ij,klmp} = \sum_{s} T_{sj,kl} R_{sipm} + \sum_{s} T_{is,kl} R_{sjpm}$$

$$+ \sum_{s} T_{ij,sl} R_{skpm} + \sum_{s} T_{ij,ks} R_{slpm}.$$

For the sake of simplicity, we always omit the comma (,) between indices in the special case $T=\sum_{i,j}h_{ij}\,\omega_i\,\omega_j$ with $N^{n+1}=S^{n+1}$.

Since $\sum_{C,D} K_{(n+1)iCD} \omega_C \wedge \omega_D = 0$ on M^n when $N^{n+1} = S^{n+1}$, we find

$$d(\sum_j h_{ij}\,\omega_j) = \sum_{j,l} h_{jl}\,\omega_l \wedge \omega_{ji}.$$

Therefore,

$$\sum_{j,l} h_{ijl} \, \omega_l \wedge \omega_j = \sum_j (dh_{ij} + \sum_l h_{lj} \, \omega_{li} + \sum_l h_{il} \, \omega_{lj}) \wedge \omega_j = 0;$$

i.e., h_{ijl} is symmetric in all indices.

Moreover, in the case that M^n is minimal, we have

$$\sum_{l} h_{ijll} = \sum_{l} h_{lijl}$$

$$= \sum_{l} \{h_{lilj} + \sum_{m} (h_{mi} R_{mljl} + h_{lm} R_{mijl})\}$$

$$= (n-1)h_{ij} + \sum_{l,m} \left\{ -h_{mi} h_{ml} h_{lj} + h_{lm} (\delta_{mj} \delta_{il} - \delta_{ml} \delta_{ij} + h_{mj} h_{il} - h_{ml} h_{ij}) \right\}$$

$$= nh_{ij} - \sum_{l,m} h_{lm} h_{ml} h_{ij} = (n-S)h_{ij}.$$

It follows that

(1.6)
$$\frac{1}{2}\Delta S = (n-S)S + \sum_{i,j,l} h_{ijl}^2.$$

2. G-invariant Hypersurface in S^{n+1}

For $G \simeq O(k) \times O(p) \times O(q)$, \mathbb{R}^{n+2} splits into the orthogonal direct sum of irreducible invariant subspaces, namely

$$\mathbb{R}^{n+2} \simeq \mathbb{R}^k \oplus \mathbb{R}^p \oplus \mathbb{R}^q = \{(X, Y, Z)\}$$

where X is a generic k-vector, Y is a generic p-vector and Z is a generic q-vector. Here if we set x = |X|, y = |Y| and z = |Z|, then the orbit

space \mathbb{R}^{n+2}/G can be parametrized by (x, y, z); $x, y, z \in \mathbb{R}_+$ and the orbital distance metric is given by $ds^2 = dx^2 + dy^2 + dz^2$. By restricting the above G-action to the unit sphere $S^{n+1} \subset \mathbb{R}^{n+2}$, it is easy to see that

$$S^{n+1}/G \simeq \{(x,y,z): x^2 + y^2 + z^2 = 1; x, y, z \ge 0\}$$

which is isometric to a spherical triangle of $S^2(1)$ with $\pi/2$ as its three angles. The orbit labeled by (x, y, z) is exactly $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$.

Analytically, it is more convenient to use the following polar coordinate system of S^{n+1}/G , namely, by performing the coordinate transformation:

$$z = \cos r$$
, $x = \sin r \cos \theta$, $y = \sin r \sin \theta$, $0 \le r$, $\theta \le \frac{\pi}{2}$.

To investigate those G-invariant minimal hypersurfaces, M^n , in S^{n+1} we study their generating curves, $\gamma(s) = M^n/G$, in the orbit space S^{n+1}/G [4, 6].

LEMMA 2.1. Let M^n be a G-invariant hypersurface in S^{n+1} . Then there is a local orthonormal frame field e_1, \ldots, e_{n+1} in S^{n+1} such that after restriction to M^n , the e_1, \ldots, e_n are tangent to M^n and $h_{ij} = 0$ if $i \neq j$.

PROOF. Let $(X_0, Y_0, Z_0) \in M^n \subset S^{n+1}$ with $x = |X_0|, y = |Y_0|$ and $z = |Z_0|$ and choose a local orthonormal frame field on a neighborhood of (X_0, Y_0, Z_0) as follows.

First, we choose vector fields $\widetilde{u}_1, \ldots, \widetilde{u}_{k-1}, \widetilde{v}_1, \ldots, \widetilde{v}_{p-1}, \widetilde{w}_1, \ldots, \widetilde{w}_{q-1}$ on a neighborhood U of (X_0, Y_0, Z_0) in the orbit $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$ such that:

- (1) $\widetilde{u}_1, \ldots, \widetilde{u}_{k-1}$ are lifts of orthonormal tangent vector fields u_1, \ldots, u_{k-1} on a neighborhood of X_0 in $S^{k-1}(x)$ to $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$ respectively,
- (2) $\widetilde{v}_1, \ldots, \widetilde{v}_{p-1}$ are lifts of orthonormal tangent vector fields v_1, \ldots, v_{p-1} on a neighborhood of Y_0 in $S^{p-1}(y)$ to $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$ respectively,
- (3) $\widetilde{w}_1, \ldots, \widetilde{w}_{q-1}$ are lifts of orthonormal tangent vector fields w_1, \ldots, w_{q-1} on a neighborhood of Z_0 in $S^{q-1}(z)$ to $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$ respectively.

Second, let $c(t) = (c_1(t), c_2(t), c_3(t))$ be the unit speed geodesic in S^{n+1}/G orthogonal to the curve $\gamma(s) = (x(s), y(s), z(s))$. For each

 $P = (X, Y, Z) \in U$, let $\widetilde{\gamma}(P, s)$ and $\widetilde{c}(P, t)$ be the horizontal lifts in S^{n+1} of $\gamma(s)$ and c(t) through P respectively. Then we see

$$\widetilde{\gamma}'(P,s) = \Big(x'(s)\frac{X}{x},\,y'(s)\frac{Y}{y},\,z'(s)\frac{Z}{z}\Big),$$

and

$$\widetilde{c}'(P,t) = \Big(c_1'(t)\frac{X}{x},\,c_2'(t)\frac{Y}{y},\,c_3'(t)\frac{Z}{z}\Big).$$

Third, we extend these vector fields over a neighborhood of (X_0, Y_0, Z_0) in S^{n+1} as follows:

- (1) we translate $\widetilde{u}_1, \ldots, \widetilde{u}_{k-1}, \widetilde{v}_1, \ldots, \widetilde{v}_{p-1}, \widetilde{w}_1, \ldots, \widetilde{w}_{q-1}$ parallel along $\widetilde{\gamma}$ and \widetilde{c} .
- (2) we extend $\tilde{\gamma}'$ and \tilde{c}' in the usual fashion.

Then these extended vector fields $\widetilde{u}_1,\ldots,\widetilde{u}_{k-1},\widetilde{v}_1,\ldots,\widetilde{v}_{p-1},\widetilde{w}_1,\ldots,\widetilde{w}_{q-1},\widetilde{\gamma}',\widetilde{c}'$ is a local orthonormal frame field in S^{n+1} . After restriction these vector fields to $M^n,\widetilde{u}_1,\ldots,\widetilde{u}_{k-1},\widetilde{v}_1,\ldots,\widetilde{v}_{p-1},\widetilde{w}_1,\ldots,\widetilde{w}_{q-1},\widetilde{\gamma}'$ are tangent to M^n . For convenience, we write them as e_1,\ldots,e_{n+1} , in order.

Let $\bar{\alpha}_i(u) = (\alpha_i(u), Y, Z)$ be a curve in $S^{k-1}(x) \times S^{p-1}(y) \times S^{q-1}(z)$ through P with $\bar{\alpha}_i'(0) = (\alpha_i'(0), 0, 0) = \tilde{u}_i(P)$. Then,

$$\widetilde{\gamma}(\bar{\alpha}_i(u), s) = \left(x(s)\frac{\alpha_i(u)}{x}, y(s)\frac{Y}{y}, z(s)\frac{Z}{z}\right),$$

and

$$\widetilde{c}(\bar{lpha}_i(u),t) = \Big(c_1(t) \frac{lpha_i(u)}{x}, c_2(t) \frac{Y}{y}, c_3(t) \frac{Z}{z}\Big).$$

It implies that

$$\widetilde{\gamma}'(\bar{\alpha}_i(u), s) = \left(x'(s)\frac{\alpha_i(u)}{x}, y'(s)\frac{Y}{y}, z'(s)\frac{Z}{z}\right),$$

and

$$\widetilde{c}'(\bar{\alpha}_i(u),t) = \Big(c_1'(t)\frac{\alpha_i(u)}{x},\,c_2'(t)\frac{Y}{y},\,c_3'(t)\frac{Z}{z}\Big).$$

Hence, we have

(2.1)
$$\overline{\nabla}_{\widetilde{u}_{i}(P)}\widetilde{\gamma}' = \left\{\frac{x'(0)}{x} \left(\alpha'_{i}(0), 0, 0\right)\right\}^{\top} \\ = \left\{\frac{x'(0)}{x} \widetilde{u}_{i}(P)\right\}^{\top} = \frac{x'(0)}{x} \widetilde{u}_{i}(P),$$

$$\overline{\nabla}_{\widetilde{u}_i(P)}\widetilde{c}' = \left\{ \frac{c_1'(0)}{x} \left(\alpha_i'(0), \, 0, \, 0 \right) \right\}^{\top} = \left\{ \frac{c_1'(0)}{x} \, \widetilde{u}_i(P) \right\}^{\top} = \frac{c_1'(0)}{x} \, \widetilde{u}_i(P)$$

and

$$h_{ij} = \langle \overline{\nabla}_{\widetilde{u}_i(P)} \widetilde{u}_j, \, \widetilde{c}'(0) \rangle = -\langle \widetilde{u}_j(P), \, \overline{\nabla}_{\widetilde{u}_i(P)} \widetilde{c}' \rangle$$
$$= -\langle \widetilde{u}_j(P), \, \frac{c_1'(0)}{x} \widetilde{u}_i(P) \rangle = \frac{-c_1'(0)}{x} \delta_{ij}.$$

In the same way, we have

$$\begin{cases} h_{(k-1+i)(k-1+j)} = \langle \overline{\nabla}_{\widetilde{v}_i(P)} \widetilde{v}_j, \widetilde{c}' \rangle = \frac{-c_2'(0)}{y} \delta_{ij}, \\ h_{(k+p-2+i)(k+p-2+j)} = \langle \overline{\nabla}_{\widetilde{w}_i(P)} \widetilde{w}_j, \widetilde{c}' \rangle = \frac{-c_3'(0)}{z} \delta_{ij}, \\ h(\widetilde{u}_i, \widetilde{v}_j) = h(\widetilde{u}_i, \widetilde{w}_j) = h(\widetilde{v}_i, \widetilde{w}_j) = 0, \\ h(\widetilde{u}_i, \widetilde{\gamma}') = h(\widetilde{v}_i, \widetilde{\gamma}') = h(\widetilde{w}_i, \widetilde{\gamma}') = 0. \end{cases}$$

And, since $\nabla_{\gamma'(P)}\gamma' = (x''(0), y''(0), z''(0))^{\top}$.

$$\begin{split} h_{nn} &= \langle \overline{\nabla}_{\widetilde{\gamma}'} \widetilde{\gamma}', \widetilde{c}' \rangle \\ &= \left\langle (x''(0) \frac{X}{x}, y''(0) \frac{Y}{y}, z''(0) \frac{Z}{z})^{\top}, (c_1'(0) \frac{X}{x}, c_2'(0) \frac{Y}{y}, c_3'(0) \frac{Z}{z}) \right\rangle \\ &= x''(0) c_1'(0) + y''(0) c_2'(0) + z''(0) c_3'(0) \\ &= \langle (x''(0), y''(0), z''(0)), \mathfrak{n} \rangle \\ &= \langle \nabla_{\gamma'} \gamma', \mathfrak{n} \rangle = \kappa_{\varrho}(\gamma), \end{split}$$

where $\mathfrak{n} = (c_1'(0), c_2'(0), c_3'(0))$. Recall that

$$\gamma(s) = (\sin r(s)\cos\theta(s), \sin r(s)\sin\theta(s), \cos r(s)).$$

Then, we have

$$\gamma'(s) = \frac{dr}{ds}\frac{\partial}{\partial r} + \frac{d\theta}{ds}\frac{\partial}{\partial \theta},$$

where $\partial/\partial r = (\cos r \cos \theta, \cos r \sin \theta, -\sin r)$ and $\partial/\partial \theta = \sin r(-\sin \theta \cos \theta, 0)$. Thus, we see

$$\left|\frac{\partial}{\partial r}\right| = 1$$
, $\left|\frac{\partial}{\partial \theta}\right|^2 = \sin^2 r$, and $\left\langle\frac{\partial}{\partial r}, \frac{\partial}{\partial \theta}\right\rangle = 0$.

And we see

$$1 = |\gamma'(s)|^2 = \left(\frac{dr}{ds}\right)^2 + \left(\frac{d\theta}{ds}\right)^2 \left|\frac{\partial}{\partial \theta}\right|^2 = \left(\frac{dr}{ds}\right)^2 + \left(\frac{d\theta}{ds}\right)^2 \sin^2 r.$$

Hence, we obtain

$$\cos\alpha = \left\langle \gamma', \, \frac{\partial}{\partial r} \right\rangle \, / \, \left| \gamma' \right| \left| \frac{\partial}{\partial r} \right| = \frac{dr}{ds} \ \, \text{and} \ \, \sin\alpha = \frac{d\theta}{ds} \, \sin r,$$

where α is the angle between the curve γ and the radial direction $\partial/\partial r$. Suppose S^{n+1}/G is orientated by the frame field $\{(\partial/\partial r), 1/\sin r (\partial/\partial\theta)\}$ and $U = (\partial/\partial r) \times 1/\sin r (\partial/\partial\theta)$. Then we have

$$\mathbf{n} = U \times T = U \times \gamma' = U \times \left(\frac{dr}{ds} \frac{\partial}{\partial r} + \frac{d\theta}{ds} \frac{\partial}{\partial \theta}\right)$$

$$= \frac{1}{\sin r} \frac{dr}{ds} \frac{\partial}{\partial \theta} - \sin r \frac{d\theta}{ds} \frac{\partial}{\partial r}$$

$$= \frac{dr}{ds} (-\sin \theta, \cos \theta, 0) - \sin r \frac{d\theta}{ds} (\cos r \cos \theta, \cos r \sin \theta, -\sin r)$$

$$= (c_1'(0), c_2'(0), c_3'(0)).$$

Thus, we get

$$\begin{split} \kappa_g(\gamma) &= \langle \nabla_{\gamma'} \gamma', \, \mathfrak{n} \rangle \\ &= \left\langle \nabla_{\gamma'} \left(\frac{dr}{ds} \frac{\partial}{\partial r} + \frac{d\theta}{ds} \frac{\partial}{\partial \theta} \right), \, \left(\frac{1}{\sin r} \frac{dr}{ds} \frac{\partial}{\partial \theta} - \sin r \frac{d\theta}{ds} \frac{\partial}{\partial r} \right) \, \right\rangle \\ &= \frac{d\alpha}{ds} + \cos r \frac{d\theta}{ds}. \end{split}$$

Therefore, we compute

(2.2)
$$\begin{cases} h_{ii} = -\frac{c_1'(0)}{x} = \cos r \frac{d\theta}{ds} + \frac{\tan \theta}{\sin r} \frac{dr}{ds}, \\ h_{(k-1+i)(k-1+i)} = -\frac{c_2'(0)}{y} = \cos r \frac{d\theta}{ds} - \frac{\cot \theta}{\sin r} \frac{dr}{ds}, \\ h_{(k+p-2+i)(k+p-2+i)} = -\frac{c_3'(0)}{z} = -\frac{\sin^2 r}{\cos r} \frac{d\theta}{ds}, \\ h_{nn} = \kappa_g(\gamma) = \frac{d\alpha}{ds} + \cos r \frac{d\theta}{ds}, \\ h_{ij} = 0, \quad \text{if} \quad i \neq j. \end{cases}$$

The proof of Lemma 2.1 is complete.

LEMMA 2.2. Let M^n be a G-invariant hypersurface in S^{n+1} and let $\{e_A\}$ be a local orthonormal frame field in S^{n+1} as in Lemma 2.1. Then,

- (a) all $h_{ijl} = 0$ except when $\{i, j, l\}$ is a permutation of either $\{i,i,n\},$
- (b) if $j \neq l$, then $h_{iijl} = h_{jlii} = h_{jjjl} = h_{ljjj} = 0$,
- (c) if i, j, l, m are distinct, then $h_{ijlm} = 0$.

PROOF. (a) Since h_{ijl} is symmetric in all indices, it suffices to show that $h_{ijl} = 0$ if $i \le j \le l$ and $\{i, j, l\} \ne \{i, i, n\}$.

(a.1) In the case $j \neq i$, Lemma 3.1 implies that $h_{ij} = 0$ and

(2.3)
$$h_{ijl} = e_l(h_{ij}) + \sum_s h_{sj} \, \omega_{si}(e_l) + \sum_s h_{is} \, \omega_{sj}(e_l) = (h_{jj} - h_{ii}) \, \omega_{ji}(e_l).$$

Since $h_{ii}=h_{jj}$ if $i,j\leq k-1$, (2.3) implies $h_{ijl}=0$ for all l. If $k\leq i,j\leq k+p-2$ or $k+p-1\leq i,j\leq n-1$, then also $h_{ijl}=0$ for all l.

And, if $i \le k-1$ and $k \le j < n$, then for all l we have

$$(2.4) h_{ijl} = h_{lij} = (h_{ii} - h_{ll}) \, \omega_{il}(e_j) = (h_{ii} - h_{ll}) \langle \nabla_{e_j} e_i, e_l \rangle = 0,$$

since $\nabla_{e_j} e_i = 0$ by the Koszul formula. In the similar cases, we also have $h_{ijl} = 0$.

Moreover, if j = l = n, then $h_{inn} = h_{nni} = e_i(h_{nn}) = 0$ since h_{nn} is constant on each orbit from (2.2).

(a.2) In the case j = i and $l \neq n$, since h_{ii} is constant on each orbit from (2.2),

(2.5)
$$h_{ijl} = h_{iil} = e_l(h_{ii}) + \sum_s h_{si} \omega_{si}(e_l) + \sum_s h_{is} \omega_{si}(e_l) = e_l(h_{ii}) = 0.$$

Therefore, we see all $h_{ijl} = 0$ except when $\{i, j, l\}$ is a permutation of either $\{i, i, n\}$.

(b) If $j \neq l$, then $e_l(h_{iij}) = e_l\{e_j(h_{ii})\} = e_j\{e_l(h_{ii})\} = 0$ since neither j nor l is n and h_{ii} is constant on each orbit. Hence, we have

$$(2.6) h_{iijl} = e_l(h_{iij}) + \sum_s h_{sij} \,\omega_{si}(e_l) + \sum_s h_{isj} \,\omega_{si}(e_l)$$

$$+ \sum_s h_{iis} \,\omega_{sj}(e_l)$$

$$= 2h_{jij} \,\omega_{ji}(e_l) - h_{iin} \,\omega_{nj}(e_l) = 0,$$

since $h_{jji} = 0$ if $i \neq n$ and $\omega_{nj}(e_l) = \langle \nabla_{e_l} e_n, e_j \rangle = 0$ from (2.1). And since $j \neq l$, from (1.4), Lemma 2.1 and (2.6) we also have

(2.7)
$$h_{jlii} = h_{ijli} = h_{ijil} + \sum_{s} h_{sj} R_{sili} + \sum_{s} h_{is} R_{sjli}$$
$$= h_{iijl} + h_{jj} R_{jili} + h_{ii} R_{ijli} = 0.$$

Moreover,

$$(2.8) h_{jjjl} = e_l(h_{jjj}) + \sum_s h_{sjj} \,\omega_{sj}(e_l) + \sum_s h_{jsj} \,\omega_{sj}(e_l)$$

$$+ \sum_s h_{jjs} \,\omega_{sj}(e_l)$$

$$= 3h_{jjn} \,\omega_{nj}(e_l) = 0,$$

since $e_l(h_{jjj})=e_l\{e_j(h_{jj})\}=e_j\{e_l(h_{jj})\}=0$ and $\omega_{nj}(e_l)=0$. And so,

(2.9)
$$h_{ljjj} = h_{jjlj}$$
$$= h_{jjjl} + \sum_{s} h_{sj} R_{sjlj} + \sum_{s} h_{js} R_{sjlj}$$
$$= 2h_{jj} R_{jjlj} = 0.$$

(c) Without loss of generality, it suffices to show that $h_{ijln} = h_{ijnl} = 0$ and $h_{ijlm} = 0$ for all i, j, l, m such that i, j, l, m < n. By using (a), we easily see that

(2.10)
$$h_{ijln} = e_n(h_{ijl}) + \sum_s h_{sjl} \,\omega_{si}(e_n) + \sum_s h_{isl} \,\omega_{sj}(e_n) + \sum_s h_{ijs} \,\omega_{sl}(e_n) = 0,$$

since i, j, l < n and i, j, l are distinct. And, from (1.4) and Lemma 2.1 we also have

(2.11)
$$h_{ijnl} = h_{ijln} + \sum_{s} h_{sj} R_{sinl} + \sum_{s} h_{is} R_{sjnl} = h_{jj} R_{jinl} + h_{ii} R_{ijnl} = 0.$$

If i, j, l, m < n, from (a) we can easily see

(2.12)
$$h_{ijlm} = e_m(h_{ijl}) + \sum_s \{h_{sjl} \,\omega_{sj}(e_m) + h_{isl} \,\omega_{sj}(e_m) + h_{ijs} \,\omega_{sl}(e_m)\}$$
$$= 0.$$

It completes the proof of Lemma 2.2.

Under such frame field as Lemma 2.1, we have

(2.13)
$$e_k(h_{ii}) = h_{iik} - \sum_s h_{si}\omega_{si}(e_k) - \sum_s h_{is}\omega_{si}(e_k) = h_{iik}.$$

Hence, in the case M^n is minimal, by differentiating $\sum_m h_{mm} = 0$ we have

$$0 = (e_j e_i - \nabla_{e_j} e_i) \left(\sum_m h_{mm} \right)$$

$$= \sum_m \{e_j(h_{mmi}) - \sum_s \omega_{is}(e_j) h_{mms} \}$$

$$= \sum_m h_{mmij} - \sum_{m,s} h_{smi} \omega_{sm}(e_j) - \sum_{m,s} h_{msi} \omega_{sm}(e_j)$$

$$- \sum_{m,s} h_{mms} \omega_{si}(e_j) - \sum_{m,s} h_{mms} \omega_{is}(e_j)$$

$$= \sum_m h_{mmij}.$$

Moreover, we have

$$(2.15)$$

$$e_k\left(\sum_{i,j}h_{ij}^2\right) = 2\sum_{i,j}h_{ij}e_k(h_{ij})$$

$$= 2\sum_{i,j}h_{ij}\{h_{ijk} - \sum_s h_{sj}\omega_{si}(e_k)\}$$

$$-\sum_s h_{is}\omega_{sj}(e_k)\}$$

$$= 2\sum_{i,j}h_{ij}h_{ijk}.$$

Hence, in the case S is constant, by differentiating $\sum_{i,j} h_{ij}^2 = S$ twice, we have

$$\begin{aligned} &(2.16) \\ &0 = (e_{l} \, e_{k} - \nabla_{e_{l}} e_{k}) \left(\frac{1}{2} \sum_{i,j} h_{ij}^{2}\right) \\ &= \sum_{i,j} e_{l}(h_{ij}h_{ijk}) - \sum_{i,j,s} \omega_{ks}(e_{l})h_{ij}h_{ijs} \\ &= \sum_{i,j} \left\{e_{l}(h_{ij})h_{ijk} + h_{ij} \, e_{l}(h_{ijk})\right\} - \sum_{i,j,s} h_{ij}h_{ijs} \, \omega_{ks}(e_{l}) \\ &= \sum_{i,j} \left\{h_{ijl} - \sum_{s} h_{sj} \, \omega_{si}(e_{l}) - \sum_{s} h_{is} \, \omega_{sj}(e_{l})\right\} h_{ijk} \\ &+ \sum_{i,j} h_{ij} \left\{h_{ijkl} - \sum_{s} \left[h_{sjk} \, \omega_{si}(e_{l}) + h_{ijs} \, \omega_{sk}(e_{l})\right]\right\} - \sum_{i,j,s} h_{ij}h_{ijs} \, \omega_{ks}(e_{l}) \\ &= \sum_{i,j} h_{ij}h_{ijkl} + h_{ijk}h_{ijl} \\ &- \sum_{i,j,s} \left\{h_{sj}h_{ijk} \, \omega_{si}(e_{l}) + h_{is}h_{ijk} \, \omega_{sj}(e_{l}) + h_{ij}h_{ijs} \, \omega_{ks}(e_{l})\right\} \\ &= \sum_{i,j} h_{ij}h_{ijkl} + h_{ijk}h_{ijl} \\ &- \sum_{i,j,s} \left\{h_{sj}h_{ijk} \, \omega_{si}(e_{l}) + h_{is}h_{ijk} \, \omega_{sj}(e_{l}) + h_{sj}h_{ijk} \, \omega_{is}(e_{l}) + h_{is}h_{ijk} \, \omega_{sj}(e_{l}) + h_{ij}h_{ijs} \, \omega_{ks}(e_{l})\right\} \\ &= \sum_{i,j} \left\{h_{sj}h_{ijk} \, \omega_{si}(e_{l}) + h_{ij}h_{ijs} \, \omega_{sk}(e_{l}) + h_{ij}h_{ijs} \, \omega_{ks}(e_{l})\right\} \\ &= \sum_{i} h_{ii}h_{iikl} + \sum_{i,j} h_{ijk} \, h_{ijl}. \end{aligned}$$

3. G-invariant minimal hypersurface in S^5

Throughout this section, we assume that $G \simeq O(2) \times O(2) \times O(2)$ and M^4 is a closed G-invariant minimal hypersurface with constant scalar curvature in S^5 . Let $\{e_A\}$ be a local orthonormal frame field in S^5 as in Lemma 2.1. Then by differentiating $\sum_i h_{ii} = 0$ and $\sum_i h_{ii}^2 = S$ with

respect to e_4 respectively, we have

$$(3.1) h_{114} + h_{224} + h_{334} + h_{444} = 0,$$

$$(3.2) h_{11}h_{114} + h_{22}h_{224} + h_{33}h_{334} + h_{44}h_{444} = 0.$$

From (1.5), we also have

(3.3)
$$h_{ii11} + h_{ii22} + h_{ii33} + h_{ii44} = (4 - S)h_{ii}.$$

Here, if $i \neq 4$, from (1.3) we know

(3.4)
$$h_{ii4} = h_{i4i} = e_i(h_{i4}) + \sum_s h_{s4}\omega_{si}(e_i) + h_{is}\omega_{s4}(e_i)$$
$$= (h_{44} - h_{ii})\omega_{4i}(e_i)$$

and

(3.5)
$$h_{iiii} = e_i(h_{iii}) + \sum_s \{h_{sii}\omega_{si}(e_i) + h_{isi}\omega_{si}(e_i) + h_{iis}\omega_{si}(e_i)\}$$
$$= 3h_{ii4} \omega_{4i}(e_i).$$

Moreover, if $i, j \neq 4$ and if $i \neq j$,

(3.6)
$$h_{iijj} = e_j(h_{iij}) + \sum_s \{h_{sij}\omega_{si}(e_j) + h_{isj}\omega_{si}(e_j) + h_{iis}\omega_{sj}(e_j)\}$$
$$= h_{ii4}\omega_{4j}(e_j).$$

Now, to prove our Theorem we need the following two lemmas.

LEMMA 3.1. Suppose $h_{ii}=h_{44}=\lambda$ at some point p for i=1,2 or 3. Then,

(3.7)
$$S = \frac{12\lambda^4 + 4\lambda^2}{5\lambda^2 - 1}.$$

PROOF. Without loss of generality, we can assume $h_{33}=h_{44}=\lambda$ at some point p. By using (3.4), we have $h_{334}(p)=0$. Using (3.5) and (3.6), we have at p

$$(3.8) h_{3311} = h_{3322} = h_{3333} = 0.$$

Hence, (3.3) and (3.8) imply

$$(3.9) h_{3344} = (4 - S)h_{33}$$

and (1.4) implies

(3.10)
$$h_{4433} = h_{3344} + (h_{44} - h_{33})(1 + h_{44}h_{33}) = h_{3344}.$$
 Since $\sum_{i,j} h_{ij3}^2 = 0$ at p , from (2.16) we have

(3.11) $h_{11}h_{1133} + h_{22}h_{2233} + h_{33}h_{3333} + h_{44}h_{4433} = 0.$ Let $h_{ii} = \lambda_i$. Then, by using (1.4) and (3.8) we know

(3.12)
$$h_{1133} = h_{3311} + (h_{11} - \lambda)(1 + h_{11} \lambda) = (\lambda_1 - \lambda)(1 + \lambda_1 \lambda)$$
 and

$$h_{2233} = h_{3322} + (h_{22} - \lambda)(1 + h_{22} \lambda) = (\lambda_2 - \lambda)(1 + \lambda_2 \lambda).$$

Hence, (3.11) and (3.12) imply

(3.13)
$$\lambda_1 (\lambda_1 - \lambda)(1 + \lambda_1 \lambda) + \lambda_2 (\lambda_2 - \lambda)(1 + \lambda_2 \lambda) + \lambda (4 - S)\lambda = 0$$
, that is,

$$\lambda_1^2 + \lambda_2^2 - (\lambda_1 + \lambda_2)\lambda + (\lambda_1^3 + \lambda_2^3)\lambda - (\lambda_1^2 + \lambda_2^2)\lambda^2 + (4 - S)\lambda^2 = 0.$$

Here, since

$$\lambda_1 + \lambda_2 + 2\lambda = 0, \quad \lambda_1^2 + \lambda_2^2 + 2\lambda^2 = S, \quad \lambda_1 \lambda_2 = 3\lambda^2 - \frac{S}{2},$$
$$\lambda_1^3 + \lambda_2^3 = (\lambda_1^2 + \lambda_2^2 - \lambda_1 \lambda_2)(\lambda_1 + \lambda_2) = 10\lambda^3 - 3S\lambda,$$

(3.13) becomes

$$S-2\lambda^2-(-2\lambda)\lambda+(10\lambda^3-3S\lambda)\lambda-(S-2\lambda^2)\lambda^2+(4-S)\lambda^2=0$$
 and so,

$$S = \frac{12\lambda^4 + 4\lambda^2}{5\lambda^2 - 1}.$$

It completes the proof of Lemma 3.1.

LEMMA 3.2. If S > 4 and i = 1, 2, 3, then for each i, there exists a point q_i in M^4 so that $h_{ii}(q_i) = 0$.

PROOF. Suppose that the conclusion is not valid. Without loss of generality, we can assume that $h_{33} > 0$ everywhere. Consider a point p_0 , such that

$$h_{33}(p_0) = \min_{M^4} h_{33} > 0.$$

Then, due to the maximal principle, we have

(3.14)
$$e_4(h_{33})(p_0) = h_{334}(p_0) = 0$$
 and
$$Hess. h_{33}(e_4, e_4)(p_0) = (e_4 e_4 - \nabla_{e_4} e_4)(h_{33}) \ge 0.$$

Hence, from (3.14) we have at p_0

(3.15)
$$Hess. h_{33}(e_4, e_4) = h_{3344} - \sum_s \omega_{4s}(e_4) h_{33s} = h_{3344} \ge 0.$$

Since $h_{334}(p_0) = 0$, using (3.5) and (3.6) as in Lemma 4.1, we have at p_0

$$h_{3311} = h_{3322} = h_{3333} = 0$$

and so,

$$(3.16) h_{3344} = (4-S)h_{33}.$$

By using (3.15) and (3.16), we have at p_0

$$h_{3344} = (4 - S)h_{33} \ge 0$$

which is contrary to the hypothesis S > 4. It completes the proof. \square

We are ready to prove our Theorem:

THEOREM. Let M^4 be a closed G-invariant minimal hypersurface with constant scalar curvature in S^5 , where $G = O(2) \times O(2) \times O(2)$.

- (1) If M^4 has 2 distinct principal curvatures at some point, then S=4.
- (2) If S > 4, then M^4 does not have simple principal curvatures everywhere.

PROOF. (1) Suppose M^4 has 2 distinct principal curvatures at some point, say, p. Without loss of generality, we can assume either one of the following three cases for some $\lambda \neq 0$:

Case 1. Suppose $h_{11}=h_{22}=h_{33}=\lambda$ and $h_{44}=-3\lambda$ at the point p. Then from (2.2), we have at p

$$\cos r \frac{d\theta}{ds} + \frac{\tan \theta}{\sin r} \frac{dr}{ds} = \cos r \frac{d\theta}{ds} - \frac{\cot \theta}{\sin r} \frac{dr}{ds} = -\frac{\sin^2 r}{\cos r} \frac{d\theta}{ds}.$$

It implies that

$$\frac{dr}{ds} = 0$$
 and $\frac{d\theta}{ds} = 0$,

which means that $h_{11} = h_{22} = h_{33} = h_{44} = \lambda = 0$ at p. It is contrary to the hypothesis.

Case 2. Suppose $h_{22}=h_{33}=h_{44}=\lambda$ and $h_{11}=-3\lambda$ at the point p. Then

(3.13)
$$S = h_{11}^2 + h_{22}^2 + h_{33}^2 + h_{44}^2 = 12\lambda^2.$$

Hence, (3.7) and (3.13) imply S = 4. i.e. $M^4 = S^1(\sqrt{1/4}) \times S^3(\sqrt{3/4})$.

Case 3. Suppose $h_{11}=h_{22}=-\lambda,\ h_{33}=h_{44}=\lambda$ at the point p. Then

(3.14)
$$S = h_{11}^2 + h_{22}^2 + h_{33}^2 + h_{44}^2 = 4\lambda^2.$$

Hence, (3.7) and (3.14) imply S=4. i.e. $M^4=S^2(\sqrt{1/2})\times S^2(\sqrt{1/2})$. But, it is not G-invariant.

(2) Suppose that M^4 has only simple principal curvatures everywhere. Then since all principal curvatures h_{ii} 's are constant on each orbit, without loss of generality we can assume everywhere either one of the following three cases:

(a)
$$h_{11} < h_{22} < h_{33} < h_{44}$$
 or

(b)
$$h_{11} < h_{22} < h_{44} < h_{33}$$
 or

(c)
$$h_{44} < h_{11} < h_{22} < h_{33}$$
.

But by Lemma 3.2, there exist points q_1 and q_3 in M^4 such that $h_{11}(q_1) = 0$ and $h_{33}(q_3) = 0$ respectively. Hence the above each case is contrary to the fact that

$$h_{11}(q_1) + h_{22}(q_1) + h_{33}(q_1) + h_{44}(q_1) = 0$$
 or $h_{11}(q_3) + h_{22}(q_3) + h_{33}(q_3) + h_{44}(q_3) = 0$.

Therefore, M^4 does not have simple principal curvatures everywhere.

References

- [1] E. Cartan, Sur des familles remarquables d'hypersurfaces isoparametriques dans les espaces spheriques, Math. Z. 45 (1939), 335-367.
- [2] S. Chang, On minimal hypersurfaces with constant scalar curvatures in S⁴, J. Diff. Geom. 37 (1993), 523-534.
- [3] S. S. Chern, M. do Carmo, and S. Kobayashi, Minimal submanifolds of a sphere with second fundamental form of constant length, Duke Math. J. 61 (1990), 195-206.
- [4] W. Y. Hsiang, On the construction of infinitely many congruence classes of imbedded closed minimal hypersurfaces in $S^n(1)$ for all $n \geq 3$, Duke Math. J. **55** (1987), no. 2, 361-367.
- [5] H. B. Lawson, Local rigidity theorems for minimal hypersurfaces, Annals of Math. (2) 89 (1969), 187-191.
- [6] H. B. Park, J. H. Park, and J. U. So, On scalar curvatures of G-invariant minimal hypersurfaces in S^{n+1} , Korean Ann. of Math. 17 (2000), 247–260.
- [7] C. K. Peng and C. L. Terng, Minimal hypersurface of spheres with constant scalar curvature, Annals of Math. Studies, No. 103, Princeton University Press, Princeton, NJ, (1983), 177-198.
- [8] J. Simons, Minimal varieties in a Riemannian manifold, Ann. of Math. (2) 88 (1968), 62-105.
- [9] S. T. Yau, Problem section, Annals of Math. Studies, No. 102, Princeton University Press, Princeton, NJ, (1982), 693.
- [10] H. Yang and Q. M. Cheng, Chern's conjecture on minimal hypersurfaces, Math. Z. 227 (1998), 377–390.

Department of Mathematics Chonbuk National University Chonju, Chonbuk 561-756, Korea *E-mail*: jaeup@moak.chonbuk.ac.kr