

Chemical Shift Artifact Correction in MREIT

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(Received October 21, 2009. Accepted December 10, 2009)

Abstract

Magnetic resonance electrical impedance tomography (MREIT) enables us to perform high-resolution conductivity imaging of an electrically conducting object. Injecting low-frequency current through a pair of surface electrodes, we measure an induced magnetic flux density using an MRI scanner and this requires a sophisticated MR phase imaging method. Applying a conductivity image reconstruction algorithm to measured magnetic flux density data subject to multiple injection currents, we can produce multi-slice cross-sectional conductivity images. When there exists a local region of fat, the well-known chemical shift phenomenon produces misalignments of pixels in MR images. This may result in artifacts in magnetic flux density image and consequently in conductivity image. In this paper, we investigate chemical shift artifact correction in MREIT based on the well-known three-point Dixon technique. The major difference is in the fact that we must focus on the phase image in MREIT. Using three Dixon data sets, we explain how to calculate a magnetic flux density image without chemical shift artifact. We test the correction method through imaging experiments of a cheese phantom and postmortem canine head. Experimental results clearly show that the method effectively eliminates artifacts related with the chemical shift phenomenon in a reconstructed conductivity image.

Key words : magnetic resonance electrical impedance tomography, magnetic flux density, chemical shift artifact, Dixon technique, conductivity image

1. INTRODUCTION

Magnetic resonance electrical impedance tomography (MREIT) is a new bio-imaging method providing a high-resolution conductivity image of an electrically conducting object [1-5]. We probe the imaging object by injecting a low-frequency electrical current through a pair of electrodes. It induces internal distributions of current density J and magnetic flux density $B = (B_x, B_y, B_z)$, which are determined by the unknown conductivity distribution of the object. We can measure B_z inside the imaging object by using an MRI scanner with its main magnetic field $B_0 = B_0 a_z$ where a_z is the unit vector along the z -direction [4]. Measured B_z data subject to multiple injection currents are obtained from MR phase images and utilized in an image reconstruction algorithm to produce a cross-sectional conductivity image.

The procedure to extract B_z images from measured k -space data implicitly assumes that spin isochromats precess at the

Larmor frequency of water. It does not hold in a fatty region, where the precession frequency differs by 3.5 ppm (440 Hz at 3T MRI scanner) [6]. Around a fatty region, a certain number of pixels are shifted depending on the bandwidth per pixel and B_0 . This results in MR signal void in one region and improper signal overlap in the other region. Signal void and overlap produce spurious noise and artifact, respectively, in MR phase images and these are transferred to the reconstructed conductivity image through B_z images.

When MR magnitude images are of primary concern, three different techniques are commonly used to deal with the chemical shift problem. The first is to confine the shift within one pixel by increasing the bandwidth per pixel. It is not desirable in MREIT due to a reduced signal-to-noise ratio (SNR). The second is to suppress the fat signal. We should avoid using it in MREIT due to a reduced overall SNR and loss of phase information in the fatty region. The third is to separate fat signals from water signals. Since the water-fat separation offers a better option in terms of SNR, we chose it to deal with the chemical shift problem in MREIT.

The fat separation can be performed by using the Dixon method [7,8]. In a typical Dixon technique, multiple data are acquired with an extra delay in echo time (TE). It introduces a phase shift between water and fat signals, which enables us to

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This work was supported by the Korea Science and Engineering Foundation (KOSEF) grant funded by the Korea government (MEST) (R11-2002-103).

separate water and fat images. The original method proposed by Dixon used two such data acquisitions with water-fat phase shifts of 0 and π [7,9]. In the presence of a field inhomogeneity, the three-point Dixon method should be used to compensate for the phase error due to the field inhomogeneity [10,11]. Three data sets are acquired in a form of either $(0, \pi, -\pi)$ and $(0, \pi, 2\pi)$. We can implement it in the conventional spin echo or gradient echo pulse sequence. Variations of the Dixon method have been proposed for fast imaging sequences [12-15]. A novel postprocessing technique based on the iterative least-square method was also proposed to enhance SNR [16].

For the present MREIT technique where spin-echo type pulse sequences are predominant [5,17], the three-point Dixon method with phase shifts of $(0, \pi, -\pi)$ appears to be sufficient. For a given total number of signal averages, we can split them into three scans with three different phase shifts. In MREIT, for a given pair of electrodes, we inject currents twice with the same amplitude but opposite polarities to cancel out any systematic phase error in a B_z image. This requires additional steps in the chemical shift artifact correction. In this paper, we briefly describe a mathematical derivation of the B_z data extraction from the three Dixon data sets, in the context of spin-echo pulse sequence used in MREIT. For the validation of the proposed method, we will discuss imaging experiments of a cheese phantom and postmortem canine head.

II. METHODS

A. Magnetic flux density imaging in the presence of fat

We assume an imaging object containing a fatty region. Placing the object inside the MRI scanner with its main magnetic field $B_0 = B_0 a_z$, we inject current I as shown in

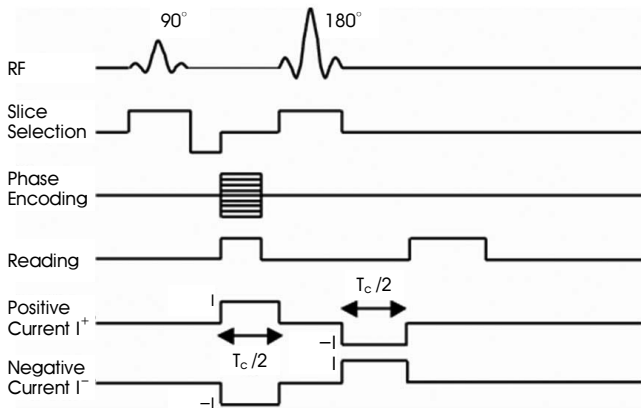


Fig. 1. Typical spin echo pulse sequence for MREIT.

figure 1. We try to measure the z-component of the induced magnetic flux density, B_z , inside a chosen imaging slice. The injection current generates extra inhomogeneity of the main magnetic field and this alters the MR phase image in such a way that the phase change is proportional to B_z .

Given a read gradient G_x in the x-direction, water and fat frequencies, f_w and f_f , respectively, are expressed as

$$f_w = \frac{\gamma}{2\pi} G_x x \tag{1}$$

$$f_f = \frac{\gamma}{2\pi} (G_x x + \Delta B_0) = f_w + \frac{\gamma}{2\pi} \Delta B_0 \tag{2}$$

where γ is the gyromagnetic ratio of the hydrogen and ΔB_0 is 3.5 ppm of B_0 . The phase accumulated by water protons at time t is given by

$$\phi_x^w = \frac{\gamma}{2\pi} G_x x t = k_x x \tag{3}$$

where $k_x = \frac{\gamma}{2\pi} G_x t$ is a spatial frequency. The phase accumulated by fat protons at time t is given by

$$\phi_x^f = \frac{\gamma}{2\pi} G_x x t + \frac{\gamma}{2\pi} \Delta B_0 t = k_x x + \epsilon = k_x (x + x') \tag{4}$$

where $x' = \frac{\Delta B_0}{G_x}$ is a given constant indicating the pixel shift.

Let $W(x, y)$ and $F(x, y)$ be the proton densities of the water and fat, respectively. The k -space signal is assumed to be a linear combination of water and fat signals. Using the positive and negative injection currents I^\pm shown in figure 1, we can obtain the following k -space signals S^\pm , respectively:

$$S^\pm(k_x, k_y) = \iint W(x, y) e^{j\delta(x, y)} e^{\pm j\gamma B_z(x, y) T_c} e^{-j(k_x x + k_y y)} dx dy + \iint F(x, y) e^{j\delta(x, y)} e^{\pm j\gamma B_z(x, y) T_c} e^{-j(k_x (x+x') + k_y y)} dx dy \tag{5}$$

where $\delta(x, y)$ is any systematic phase error and T_c is the current injection pulse width. Through the change of variable $x + x'$ in the second term, we get,

$$S^\pm(k_x, k_y) = \iint W(x, y) e^{j\delta(x, y)} e^{\pm j\gamma B_z(x, y) T_c} e^{-j(k_x x + k_y y)} dx dy + \iint F(x - x', y) e^{j\delta(x - x', y)} e^{\pm j\gamma B_z(x - x', y) T_c} e^{-j(k_x x + k_y y)} dx dy \tag{6}$$

Taking inverse Fourier transform, we obtain two complex MR images of,

$$M^\pm(x, y) = W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} + F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c} \quad (7)$$

The magnetic flux density B_z is embedded in phase parts of $M^\pm(x, y)$. If there is no chemical shift, that is, $x' = 0$, we may extract B_z from

$$\varphi = \arg\left[\frac{M^+(x, y)}{M^-(x, y)}\right] = 2\gamma T_c B_z(x, y) - \quad (8)$$

When $x' \neq 0$, (8) fails to provide the phase information accurately due to shifting of pixels. In such a case, separation of water and fat signals is necessary to estimate the phase accurately.

B. Separation of water and fat signals

We collect k -space data three times with three different delays of the 180° RF pulse by $\tau = -0.57, 0, 0.57$ ms, producing phase shifts of $-\pi, 0, \pi$ respectively. Assuming that x' is moderate (i.e. the readout gradient is not too slow) and the B_0 field is smoothly varying, there may occur additional phase shifts common to both water and fat signals. We denote them as $-\varnothing^\tau, 0, \varnothing^\tau$ for $\tau = -0.57, 0, 0.57$ ms, respectively [7]. We may express k -space signals $S_{-\pi}^\pm$ and S_π^\pm for $\tau = -0.57$ and 0.57 , respectively, as

$$S_{-\pi}^\pm(k_x, k_y) = \iint [W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - \iint F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c}]e^{-j\varnothing^\tau}e^{-j(k_x x + k_y y)} dx dy \quad (9)$$

and

$$S_\pi^\pm(k_x, k_y) = \iint [W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - \iint F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c}]e^{j\varnothing^\tau}e^{-j(k_x x + k_y y)} dx dy \quad (10)$$

Taking inverse Fourier transforms of (9) and (10), we get

$$M_{-\pi}^\pm(x, y) = [W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c}]e^{-j\varnothing^\tau} \quad (11)$$

and

$$M_\pi^\pm(x, y) = [W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c}]e^{j\varnothing^\tau} \quad (12)$$

Using (11) and (12), we get

$$\frac{1}{2}\left(\frac{M_\pi^+(x, y)}{M_{-\pi}^+(x, y)} + \frac{M_\pi^-(x, y)}{M_{-\pi}^-(x, y)}\right) = e^{j2\varnothing^\tau} \quad (13)$$

We now estimate $e^{j\varnothing^\tau}$ from $e^{j2\varnothing^\tau}$ by carefully choosing a proper sign of $\sqrt{e^{j2\varnothing^\tau}}$. Improper sign selection will interchange water and fat signals in separated images. One solution is to unwrap the wrapped phase in (13), divide the unwrapped phase $2\varnothing^\tau$ by 2, and then wrap it again by calculating $e^{j\varnothing^\tau}$ [9]. Using the estimated $e^{j\varnothing^\tau}$, we eliminate it from (11) and (12) to get

$$N_{-\pi}^\pm(x, y) = W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c} \quad (14)$$

and

$$N_\pi^\pm(x, y) = W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} - F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c} \quad (15)$$

From (7), (14) and (15), we can separate water and fat signals as,

$$\frac{W(x, y)e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} + 2M_{-\pi}^\pm(x, y) + N_{-\pi}^\pm(x, y)}{4} \quad (16)$$

and

$$\frac{F(x - x', y)e^{j\delta(x - x', y)}e^{\pm j\gamma B_z(x - x', y)T_c} + 2M_\pi^\pm(x, y) - N_{-\pi}^\pm(x, y) - N_\pi^\pm(x, y)}{4} \quad (17)$$

C. Correction of pixel shift

Since $x' = \frac{\Delta B_0}{G_x}$ is a known value, and can also be found experimentally, we correct the pixel shift in (17) to finally get

Table 1. Imaging parameters for the gelatin-TX151-cheese phantom and postmortem canine head experiments.

Parameters	Gelatin-TX151-cheese phantom	Postmortem canine head
Sampling time (μ s)	24	36
Current amplitude (mA)	30	26
Current injection time (ms)	23	21.5
TR/TE (ms)	1000 / 30	1200 / 30
FOV (mm)	200×200	180×180
Pixel size (mm)	1.56	1.41

$$K^\pm(x, y) = [W(x, y) + F(x, y)]e^{j\delta(x, y)}e^{\pm j\gamma B_z(x, y)T_c} \quad (18)$$

This allows us to compute the B_z image using (8) with K in place of M . We can also easily obtain magnitude images of $M = W + F$, W and F with all pixels correctly placed.

D. Imaging experiment and conductivity image reconstruction

We conducted MREIT experiments of a gelatin-TX151-cheese phantom and postmortem canine head. Four surface electrodes were attached around the imaging object. For the postmortem animal experiment, we followed the experimental protocol approved by the Institutional Animal Care and Use Committee (IACUC) [18]. Using our 3T MRI scanner (Medinus, Korea), we collected k -space data three times with three different delays of the refocussing RF pulse. Table 1 summarizes several imaging parameters. Water and fat images were obtained using the method described in section B. B_z images for the horizontal and vertical current injections were

computed after correcting the pixel shift as described in section C. Conductivity images were reconstructed using the single-step harmonic B_z algorithm [19-21], which is implemented in the recently developed conductivity image reconstruction software for MREIT [22]. Reconstructed conductivity images presented in this paper provide contrast information only.

III. RESULTS

Figure 2(a) is the MR magnitude image of the phantom before correction, where we can observe shifting of pixels in the vertical direction around the fatty region. Separated water and fat images are shown in (b) and (c), respectively. Figure 2(d), (e) and (f) are the images from the postmortem canine head.

In figure 3(a), we marked MR signal void and overlap due to the chemical shift using arrows. Uncorrected B_z images subject to the horizontal and vertical current injections are shown in (b) and (c), respectively. We can observe that both

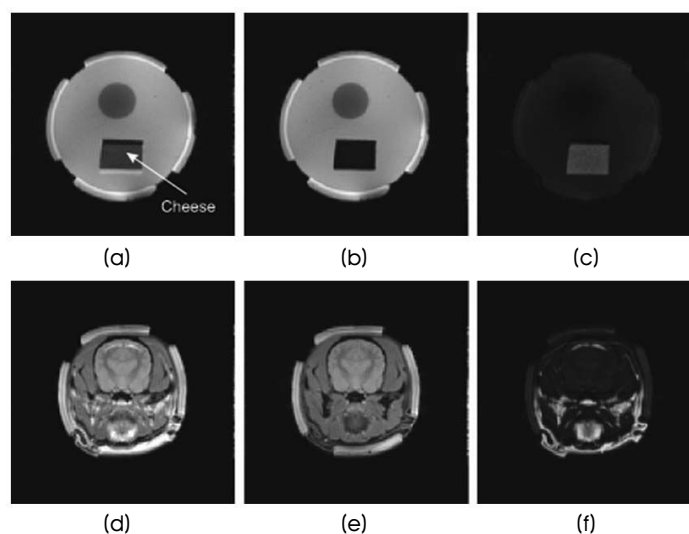


Fig. 2. (a), (b) and (c) are the uncorrected MR magnitude, separated water and fat images, respectively, from the gelatin-TX151-cheese phantom. (d), (e) and (f) are images from the postmortem canine head.

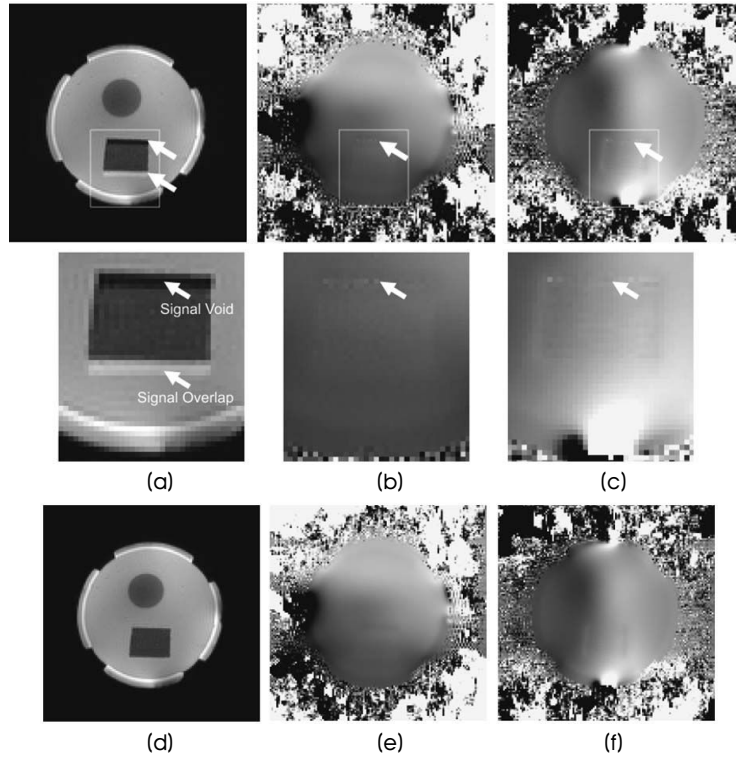


Fig. 3. (a) is the uncorrected MR magnitude image of the phantom. (b) and (c) are uncorrected images subject to the horizontal and vertical current injections, respectively. In (a), (b) and (c), images inside the rectangles are magnified by three times and shown in the second row. (d), (e) and (f) are images after the correction.

B_z images contain spurious noise in the region of signal void. Though the effect is not visible, we should presume that both B_z images contain artifact in the region of signal overlap. Applying the correction method and shifting fat images by 2

pixels, we could obtain the images in (d), (e) and (f) where the problem is clearly resolved. Figure 4 shows the similar results from the postmortem canine head. For the canine head case, we shifted fat images by 3 pixels.

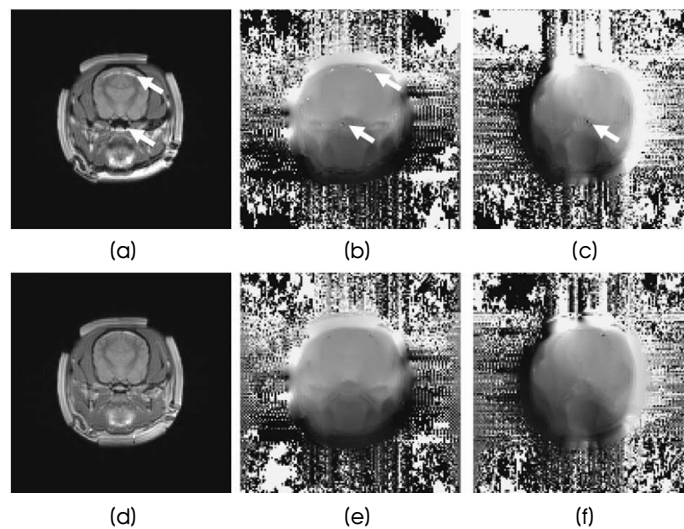


Fig. 4. (a) is the uncorrected MR magnitude image of the postmortem canine head. (b) and (c) are uncorrected B_z images subject to the horizontal and vertical current injections, respectively. (d), (e) and (f) are images after the correction.

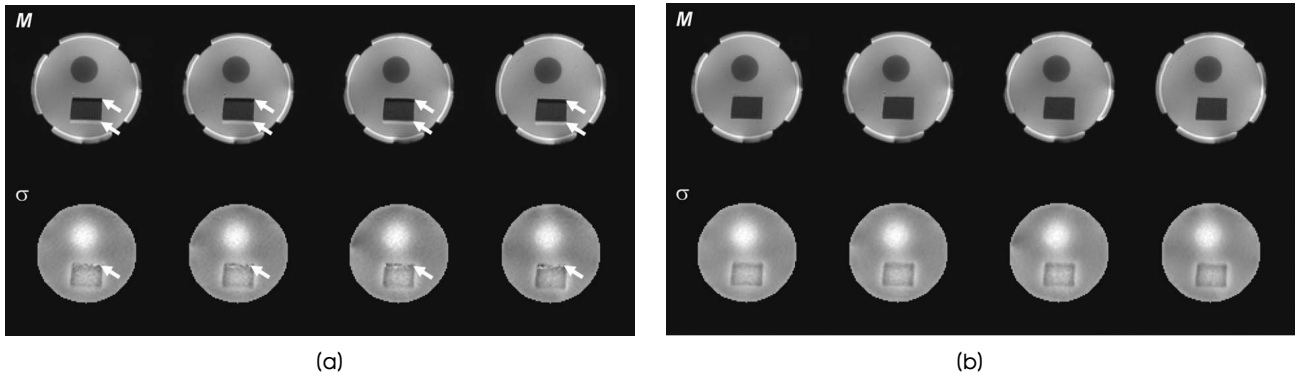


Fig. 5. (a) Multi-slice MR magnitude and conductivity images of the phantom in the top and bottom rows, respectively, before applying the chemical shift artifact correction. (b) are images after the correction. Reconstructed conductivity values are not constant across anomalies due to the diffusion of ions between anomalies and the background medium over time.

Figure 5(a) and (b) show the multi-slice MR magnitude (M) and conductivity images (σ) from the gelatin-TX151-cheese phantom before and after applying the correction method, respectively. They illustrate that the chemical shift phenomenon results in spurious noise in conductivity images inside the region of signal void since random phase noise comes out in the absence of the signal. The correction method significantly improves the image quality in the region of signal void. In the region of signal overlap, we must have phase errors since overlapped water and fat signals make wrong phase changes depending on relative signal strengths. Nevertheless, the phase errors in the overlapping region are less prominent. We could get similar results from the canine head case shown in figure 6.

IV. DISCUSSION AND CONCLUSION

When there exists a fatty region in a chosen imaging slice, its conductivity image suffers from MR signal void and overlap due to the chemical shift phenomenon. We could

successfully implement a chemical shift artifact correction together with the magnetic flux density imaging method in MREIT. Experimental results show that it improves the quality of a reconstructed conductivity image.

Though we implicitly assumed that the chemical shift occurs only in the frequency-encoding direction, it may also occur in the slice selection direction (z -direction in our case). During conductivity image reconstructions, we need to compute the three-dimensional Laplacian of the measured B_z data [22]. However, we expect that the chemical shift in the z -direction has a negligible effect since the slice thickness is at least 3 mm in most MREIT studies. For the cases where the slice thickness is comparable to the pixel size, we should investigate ways to correct any pixel shift along the z -direction.

The amount of phase change due to the main magnetic field inhomogeneity affects how well water and fat images are separated. Without a proper shimming, some water signals may remain in a fat image inseparable and vice-versa. Switching of water and fat images may also happen in a few slices. We recommend a careful shimming prior to any scan.

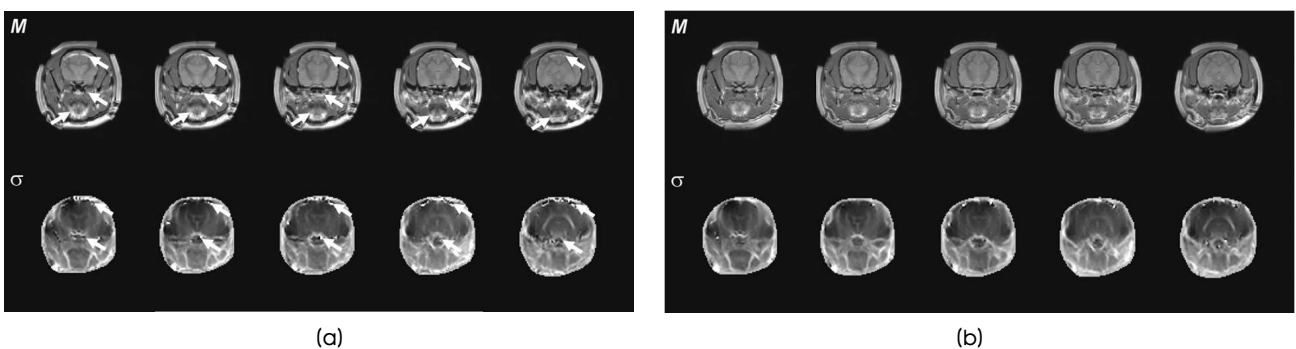


Fig. 6. (a) Multi-slice MR magnitude and conductivity images of the canine head in the top and bottom rows, respectively, before applying the chemical shift artifact correction. (b) are images after the correction.

Glover and Schneider (1991) suggested a method to automatically determine the sign in (16) and (17) to prevent fat and water images from being switched. Instead of using phase shifts of $(0, \pi, -\pi)$, one may also use $(0, \alpha, -\alpha)$ with $\alpha < \pi$ to prevent pixel-switching by avoiding the phase unwrapping step [12-15].

In our correction method, we kept the total scan time same as that of a conventional MREIT scan. We equally divided the total number of scans used for signal averaging among three Dixon scans. We found that the SNR of the corrected MR magnitude image was reduced to 80 to 95% of the uncorrected image as analyzed by Glover and Schneider (1991). Since the noise level in a B_z image is inversely proportional to the SNR of the MR magnitude image [23,24], we plan to investigate a newer Dixon data acquisition method using phase shifts of $(0, \alpha, -\alpha)$ with $\alpha < \pi$ [12-15], which requires a different data processing scheme such as an iterative least square method [16]. In our future work, we plan to undertake a detailed quantitative analysis of the proposed chemical shift artifact correction method in terms of the noise level in B_z image. A comparison of various modifications of the Dixon technique in the context of MREIT is necessary to choose a proper data sampling technique and data processing algorithm.

Lately, Hamamura *et al.* [25] and Minhas *et al.* [26] proposed similar methods to deal with chemical shift artifacts in MREIT. Hamamura *et al.* [25] used three Dixon data sets with positive current injections only. As the fourth data set, they acquired data in the conventional way without any shifting of 180° RF pulse. The B_z extraction procedure from these four data sets is thus different from the one explained in this paper. Our approach in this paper demonstrated that just three Dixon data acquisitions are sufficient to extract the corrected B_z data. Details of the correction method presented in this paper will fill any gap in the short papers by Hamamura *et al.* [25] and Minhas *et al.* [26] that may hinder complete understanding of the method.

The proposed correction method will be beneficial to animal and human imaging experiments. We plan to incorporate the developed chemical shift artifact correction method in the recently developed MREIT software package [22]. We plan to conduct *in vivo* imaging experiments using animals of different disease models.

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