

## FINITE TYPE CURVE IN 3-DIMENSIONAL SASAKIAN MANIFOLD

CETIN CAMCI AND H. HILMI HACISALIHOGLU

ABSTRACT. We study finite type curve in  $R^3(-3)$  which lies in a cylinder  $N^2(c)$ . Baikousis and Blair proved that a Legendre curve in  $R^3(-3)$  of constant curvature lies in cylinder  $N^2(c)$  and is a 1-type curve, conversely, a 1-type Legendre curve is of constant curvature. In this paper, we will prove that a 1-type curve lying in a cylinder  $N^2(c)$  has a constant curvature. Furthermore we will prove that a curve in  $R^3(-3)$  which lies in a cylinder  $N^2(c)$  is finite type if and only if the curve is 1-type.

### 1. Introduction

If a differentiable  $(2n+1)$ -dimensional manifold  $M$  carries a global differential 1-form  $\eta$  such that

$$\eta \wedge (d\eta)^n \neq 0$$

everywhere on  $M$ , it is called contact manifold and  $\eta$  is called contact structure [3]. It is well known that there exists a unique vector  $\xi$  such that  $\eta(\xi) = 1$  and  $d\eta(X, \xi) = 0$ .  $\xi$  is called characteristic vector field of the contact structure on  $\eta$ .  $D$  is said to be contact distribution defined by

$$D = \{X \in \chi(M) : \eta(X) = 0\}.$$

1-dimensional integral submanifold of  $M$  is called a Legendre curve [2].  $(\phi, \xi, \eta)$  is called an almost contact structure on  $M$  where  $\phi$ ,  $\eta$  and  $\xi$  are type  $(1, 1)$ ,  $(0, 1)$  and  $(1, 0)$ , respectively, satisfying the equations  $\phi^2 X = -X + \eta(X)\xi$  and  $\phi(\xi) = 0$  [3].  $(\phi, \xi, \eta, g)$  is called an almost contact metric structure on  $M$  if  $(\phi, \xi, \eta)$  is almost contact structure and  $g$  is a Riemannian metric satisfying

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y).$$

$(\phi, \xi, \eta, g)$  is called a contact metric structure on  $M$  if it is an almost contact metric on  $M$  and such that  $d\eta(X, Y) = g(X, \phi Y)$  [3]. It is well known that a contact metric structure is a contact structure. A  $(2n+1)$ -dimensional manifold is said to be a Sasakian manifold if it is endowed with a normal contact

---

Received March 11, 2009; Revised November 10, 2009.

2000 *Mathematics Subject Classification*. Primary 53C15; Secondary 53C25.

*Key words and phrases*. Sasakian Manifold, Legendre curve, finite type curve.

metric structure  $(\phi, \xi, \eta, g, \xi)$  [3]. It is well known that an almost contact metric structure  $(\phi, \xi, \eta, g, \xi)$  on  $M$  is a Sasakian structure if and only if

$$(1.1) \quad (\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X,$$

where  $X, Y \in \chi(M)$  [3]. Let  $(x, y, z)$  be standard coordinates on  $R^3$ . Consider the 1-form  $\eta = \frac{1}{2}(dz - ydx)$  on  $R^3$ . In this case if we put  $\xi = 2\frac{\partial}{\partial z}$ , then we obtain  $\eta(\xi) = 1$  and  $d\eta(\xi, \cdot) = 0$ . Thus  $\xi$  is a characteristic vector field. We consider the endomorphism of  $\phi$  defined by matrix

$$\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & y & 0 \end{bmatrix}.$$

Thus we have  $\phi^2 X = -X + \eta(X)\xi$ . Hence  $(\phi, \xi, \eta)$  is an almost contact structure on  $R^3$  [3]. If the Riemannian metric is defined by

$$ds^2 = \frac{1}{4}(dx^2 + dy^2) + \eta \otimes \eta,$$

then it is well known that  $(\phi, \xi, \eta, g)$  is a Sasakian structure. In this space, the sectional curvature of all plane sections orthogonal to  $\xi$  is equal to  $-3$ .  $(R^3, \phi, \xi, \eta, g, )$  is denoted shortly by  $R^3(-3)$  [2]. It is well known that

$$\left\{ e = e_1 = 2\frac{\partial}{\partial y}, \quad \phi e = e_2 = 2\left(\frac{\partial}{\partial x} + y\frac{\partial}{\partial z}\right), \quad \xi = e_3 = 2\frac{\partial}{\partial z} \right\}$$

is orthonormal basis with respect to  $g$ .

In a 3-dimensional contact metric manifold, if the angle between tangent vector of the curve and the Reeb vector field is a constant, then it is said that the curve is a slant curve [7]. Cho et al. have investigated slant curves in a Sasakian 3-manifold and stated the following theorem. A non-geodesic curve in a Sasakian 3-manifold  $M$  is a slant curve if and only if  $\eta(n) = g(n, \xi) = 0$ , where  $n$  is a normal vector of the curve [7].

Let  $R^3(-3)$  be an isometric immersion, where  $M$  is a compact submanifold of  $R^3(-3)$ . Then we have spectral decomposition

$$(1.2) \quad x^A - (x^A)_0 = \sum_{t=p_A}^{q_A} (x^A)_t,$$

where  $p_A = \{\inf t : (x_A)_t \neq 0\}$  and  $q_A = \{\sup t : (x_A)_t \neq 0\}$ . If  $p = \inf\{p_A\}$  and  $q = \sup\{q_A\}$ , then we have the following spectral decomposition

$$(1.3) \quad \phi^2 x = \phi^2 x_0 + \sum_{t=p}^q \phi^2 x_t,$$

where  $\Delta g(x_t, e_A) = \lambda_t g(x_t, e_A)$  ([1], [2]). In spectral decomposition, if there are exactly  $k$  nonzero of  $\phi^2 x_t$ , then we say that the submanifold  $M$  of  $R^3(-3)$  is  $k$ -type ([1], [2]).

Furthermore, in  $R^3(-3)$  Sasakian space, the cylinder is defined by

$$N^2(r) = \{X \in R^3(-3) : g(x - x_0, x - x_0) - \eta(x - x_0) = r^2\}$$

or

$$(1.4) \quad N^2(r) = \{X = (x, y, z) \in R^3(-3) : (x - x_0)^2 + (y - y_0)^2 = (2r)^2\},$$

where  $r$  is a constant [2].

Takahashi [8] showed that a submanifold of Euclidean space is 1-type if and only if it is a minimal submanifold of a hypersphere. As a result of Takahashi's theorem, a curve in 2-sphere in Euclidean 3-space is 1-type if and only if it is circle. Furthermore Chen et al. [6] showed that a finite type curve 2-sphere in Euclidean 3-space is a circle.

Extension of Takahashi's theorem is given by Baikousis and Blair [1]. They showed that a compact  $m$ -dimensional integral submanifold of  $R^{2n+1}(-3)$  is of 1-type if and only if it is minimal in cylinder  $N^{2n}(c)$  [1]. Furthermore, they showed that a Legendre curve in  $R^3(-3)$  of constant curvature lying in a cylinder  $N^2(r)$  is a 1-type curve. Conversely, a 1-type Legendre curve is of constant curvature. They conjectured that a finite type curve lying in a cylinder  $N^2(c)$  is of constant curvature in the metric of  $R^3(-3)$  [2]. In this paper, we prove this conjecture.

## 2. Finite type curve in cylinder $N^2(r)$ of $R^3(-3)$

Let  $\gamma$  be a curve with unit coordinate neighborhood  $(I, \gamma)$  and  $s$  be arc-parameter for the curve. Define the curve by

$$\gamma(s) = (x(s), y(s), z(s))$$

in  $N^2(r)$ , then we have

$$(x - x_0)^2 + (y - y_0)^2 = (2r)^2.$$

Thus we write  $x(s) = 2r \cos \theta(s) + x_0$ ,  $y(s) = 2r \sin \theta(s) + y_0$ ,

$$\gamma(s) - \gamma_0 = (2r \cos \theta(s), 2r \sin \theta(s), z(s) - z_0)$$

and

$$(2.1) \quad \gamma - \gamma_0 = r \sin \theta e + r \cos \theta \phi e + \left( \frac{z(s) - z_0}{2} \right) \xi,$$

where  $\gamma_0 = (x_0, y_0, z_0)$ .

**Lemma 2.1** ([4]). *Let  $\gamma$  be a curve which lies in a cylinder  $N^2(r)$ . The curve is 1-type if and only if  $\theta'$  is a constant.*

*Proof.* If the curve is a 1-type, then we obtain

$$\Delta g(\gamma - \gamma_0, e_i) = \lambda g(\gamma - \gamma_0, e_i), \quad i = 1, 2.$$

It is well known that the Laplacian of the curve is given by

$$(2.2) \quad \Delta f = -X_1 X_1 f = -f'',$$

where  $X_1 = \gamma'$  is the unique tangent vector of the curve [1]. Thus from the equations (2.1) and (2.2), we see that

$$-r\theta''\cos\theta + r(\theta')^2\sin\theta = \lambda r\sin\theta$$

and

$$r\theta''\sin\theta + r(\theta')^2\cos\theta = \lambda r\cos\theta.$$

Thus we easily see that  $\theta'$  is a constant.

Conversely, suppose that  $\theta' = c$  is a constant. Thus we write

$$\theta(s) = cs + c_1.$$

From the equation (2.1), we have

$$g(\gamma - \gamma_0, e) = r\sin\theta, \quad g(\gamma - \gamma_0, \phi e) = r\cos\theta.$$

Thus from the equations (2.1) and (2.2), we obtain

$$\Delta g(\gamma - \gamma_0, e) = c^2 g(\gamma - \gamma_0, e)$$

and

$$\Delta g(\gamma - \gamma_0, \phi e) = c^2 g(\gamma - \gamma_0, \phi e).$$

Then we see that the curve is 1-type.  $\square$

**Theorem 2.1** ([4]). *Let  $M$  be a curve which lies in cylinder  $N^2(r)$  with  $(I, \gamma)$  unit coordinate neighborhood. If the curve is 1-type, then it has a constant curvature.*

*Proof.* From the equation (2.1), if we take the derivative along  $\gamma$ , then we obtain

$$t = \gamma'(s) = (-2r\theta'(s)\sin\theta(s), 2r\theta'(s)\cos\theta(s), z'(s)),$$

where  $x' = -2r\theta'\sin\theta$  and  $y' = 2r\theta'\cos\theta$ . Furthermore because of

$$\frac{\partial}{\partial y} = \frac{1}{2}e, \quad \frac{\partial}{\partial x} = \frac{1}{2}(\phi e - y\xi), \quad \frac{\partial}{\partial z} = \frac{1}{2}\xi,$$

then we have

$$(2.3) \quad t = \frac{1}{2}(y'e + x'\phi e) + \sigma\xi$$

and

$$(2.4) \quad 1 = r^2(\theta')^2 + \sigma^2.$$

Thus we have

$$(2.5) \quad \nabla_t t = \left(\frac{1}{2}y'' + \sigma x'\right)e + \left(\frac{1}{2}x'' - \sigma y'\right)\phi e + \sigma'\xi.$$

From the equation (2.5) we obtain

$$(2.6) \quad \kappa^2 = \frac{1}{4}((x'')^2 + (y'')^2) + \sigma(y''x' - x''y') + \sigma^2((x')^2 + (y')^2) + (\sigma')^2,$$

where

$$(2.7) \quad x' = -2r\theta'\sin\theta, \quad x'' = -2r\theta''\sin\theta - 2r(\theta')^2\cos\theta$$

and

$$(2.8) \quad y' = 2r\theta' \cos \theta, \quad y'' = 2r\theta'' \cos \theta - 2r(\theta')^2 \sin \theta.$$

From the equations (2.6), (2.7) and (2.8), we have

$$\kappa^2 = r^2(\theta')^4 + 4r^2(\theta')^3 \sqrt{(1 - r^2(\theta')^2) + 4r^2(\theta')^2(1 - r^2(\theta')^2)} + \frac{r^2(\theta'')^2}{1 - r^2(\theta')^2}.$$

Assume that the curve is a 1-type then from Lemma 1 and the equation above,  $\theta'$  is a constant. Therefore the curvature of the curve is a constant.  $\square$

*Remark 2.1 ([4]).* The converse of the above theorem is not true. If we define the function  $F$  from open interval  $(-\frac{1}{r}, \frac{1}{r})$  to  $(-\frac{1}{r}, \frac{1}{r})$  by

$$F(y) = \int_{y_0}^y \frac{du}{\sqrt{1 - r^2 u^2} \sqrt{\frac{k^2}{r^2} + (4r^2 - 1)u^4 - 5u^3 - 4u^3 \sqrt{1 - r^2 u^2}}},$$

then we have

$$F'(y) = \frac{1}{\sqrt{1 - r^2 y^2} \sqrt{\frac{k^2}{r^2} + (4r^2 - 1)y^4 - 5y^3 - 4y^3 \sqrt{1 - r^2 y^2}}},$$

where  $k$  is a constant and  $y, y_0 \in (-\frac{1}{r}, \frac{1}{r})$ . Since  $F'(y) > 0$ , there exists an inverse function of  $F$ . Define  $\theta(s)$  by

$$\theta(s) = \int_{s_0}^s F^{-1}(h) dh,$$

then we see that  $\kappa$  is equal to  $k$ . Since  $\theta'$  is not constant, the curve is not of 1-type.

**Corollary 2.1.** *Let  $\gamma$  be a curve which lies in a cylinder  $N^2(r)$  in  $R^3(-3)$ . From the equation (2.4), we easily see that the curve is a slant curve if and only if  $\theta'$  is a constant.*

**Theorem 2.2 ([4]).** *Let  $\gamma$  be a curve which lies in a cylinder  $N^2(r)$  in  $R^3(-3)$ . Then the curve is of finite type if and only if it is of 1-type.*

*Proof.* Let  $\gamma$  be a curve with unit coordinate neighborhood  $(I, \gamma)$  and  $s$  be arc-parameter for the curve. If the curve finite  $k$ -type, then we have

$$\phi^2(\gamma - \gamma_0) = \phi^2\gamma_1 + \phi^2\gamma_2 + \cdots + \phi^2\gamma_k$$

and

$$\Delta g(\gamma_i, e_j) = \lambda_i g(\gamma_i, e_j),$$

where  $i = 1, 2, \dots, k$  and  $j = 1, 2$ . From the above equation and (2.2), we have

$$f'' + \lambda_i f = 0,$$

where  $f = g(\gamma_i, e_j)$ . Integrating the above equation, we have

$$\begin{aligned} \gamma_i(s) &= (A_{i1} \cos(\sqrt{\lambda_i} s) + A_{i2} \sin(\sqrt{\lambda_i} s))e \\ &\quad + (B_{i1} \cos(\sqrt{\lambda_i} s) + B_{i2} \sin(\sqrt{\lambda_i} s))\phi e + \mu\xi. \end{aligned}$$

Thus we obtain

$$(2.9) \quad g(\gamma - \gamma_0, e) = \sum_{i=1}^k (A_{i1} \cos(\sqrt{\lambda_i} s) + A_{i2} \sin(\sqrt{\lambda_i} s))$$

and

$$(2.10) \quad g(\gamma - \gamma_0, \phi e) = \sum_{i=1}^k (B_{i1} \cos(\sqrt{\lambda_i} s) + B_{i2} \sin(\sqrt{\lambda_i} s)).$$

From the equations (2.1), (2.9) and (2.10), we have

$$\begin{aligned} & \left( \sum_{i=1}^k (A_{i1} \cos(\sqrt{\lambda_i} s) + A_{i2} \sin(\sqrt{\lambda_i} s)) \right)^2 \\ & + \left( \sum_{i=1}^k (B_{i1} \cos(\sqrt{\lambda_i} s) + B_{i2} \sin(\sqrt{\lambda_i} s)) \right)^2 = r^2. \end{aligned}$$

If we take the derivative of the equation above, we obtain

$$\begin{aligned} & \sum_{i=1}^k \sqrt{\lambda_i} ((A_{i1} A_{i2} + B_{i1} B_{i2}) \cos 2\sqrt{\lambda_i} s + \frac{1}{2} (A_{i2}^2 + B_{i2}^2 - A_{i1}^2 - B_{i1}^2) \sin 2\sqrt{\lambda_i} s) \\ & + \sum_{i \neq j} (-\sqrt{\lambda_j} (A_{i1} A_{j1} + B_{i1} B_{j1}) + \sqrt{\lambda_i} (A_{i2} A_{j2} + B_{i2} B_{j2})) \sin \sqrt{\lambda_i} s \cos \sqrt{\lambda_j} s \\ & + \sum_{i \neq j} \sqrt{\lambda_j} (A_{i1} A_{j2} + B_{i1} B_{j2}) \cos \sqrt{\lambda_i} s \cos \sqrt{\lambda_j} s \\ & - \sum_{i \neq j} \sqrt{\lambda_j} (A_{i2} A_{j1} + B_{i2} B_{j1}) \sin \sqrt{\lambda_i} s \sin \sqrt{\lambda_j} s = 0. \end{aligned}$$

Since  $\cos(2\sqrt{\lambda_i} s)$ ,  $\cos(2\sqrt{\lambda_j} s)$ ,  $\sin(\sqrt{\lambda_i} s)$ ,  $\cos(\sqrt{\lambda_i} s)$ ,  $\sin(\sqrt{\lambda_i} s) \sin(\sqrt{\lambda_j} s)$ ,  $\cos(\sqrt{\lambda_i} s) \cos(\sqrt{\lambda_j} s)$  are linear independent, we obtain

$$(2.11) \quad A_{i2}^2 + B_{i2}^2 = A_{i1}^2 + B_{i1}^2,$$

$$(2.12) \quad A_{i1} A_{i2} + B_{i1} B_{i2} = 0,$$

$$(2.13) \quad \sqrt{\lambda_j} (A_{i1} A_{j2} + B_{i1} B_{j2}) = \sqrt{\lambda_i} (A_{i2} A_{j2} + B_{i2} B_{j2}),$$

$$(2.14) \quad A_{i1} A_{j2} + B_{i1} B_{j2} = 0,$$

where  $i, j = 1, 2, \dots, k$  and  $i \neq j$ . Assume that  $A_{i1} \neq 0$  and using the equation (2.12), we have

$$(2.15) \quad A_{i2} = -\frac{B_{i1} B_{i2}}{A_{i1}}.$$

From the equations (2.11) and (2.15), we obtain

$$\frac{B_{i2}^2}{A_{i1}^2} (A_{i1}^2 + B_{i1}^2) = A_{i1}^2 + B_{i1}^2$$

and

$$|B_{i2}| = |A_{i1}|, \quad |B_{i1}| = |A_{i2}|.$$

Thus without loss of generality, we assume that

$$(2.16) \quad B_{i2} = A_{i1}, \quad B_{i1} = -A_{i2}.$$

From the equations (2.13) and (2.16), we have

$$(\sqrt{\lambda_j} - \sqrt{\lambda_i})(A_{i1}A_{j1} + A_{i2}A_{j2}) = 0.$$

Since  $\sqrt{\lambda_j} \neq \sqrt{\lambda_i}$  while  $i \neq j$ , we obtain

$$(2.17) \quad A_{i1}A_{j1} + A_{i2}A_{j2} = 0.$$

From the equations (2.14) and (2.16), we have

$$(2.18) \quad A_{i1}A_{j2} - A_{i2}A_{j1} = 0.$$

Since  $A_{i1} \neq 0$ , from the equations (2.17) and (2.18) we obtain

$$(2.19) \quad A_{j1}^2 + A_{j2}^2 = 0.$$

Thus we have  $A_{j1} = A_{j2} = 0$  for  $j = 1, 2, \dots, k$ , a contradiction. So, this curve is 1-type.  $\square$

**Theorem 2.3.** *Let  $\gamma$  be a curve which lies in a cylinder  $N^2(r)$  in  $R^3(-3)$ . Then the curve is geodesic (minimal) in cylinder if and only if  $\theta'$  is a constant.*

*Proof.* Let  $N$  be a normal vector of the cylinder. It is known that  $N = -2\phi^2(x - x_0)$  [1]. If the curve is a geodesic curve in cylinder, then we have  $n = \lambda N$ . Thus we obtain  $g(n, \xi) = 0$  and be a constant. From Corollary 2.1, we easily see that  $\theta'$  is a constant.

Conversely, let  $\theta'$  be a constant. From Corollary 2.1 we easily see that the curve is a slant curve and

$$\sigma(s) = g(t, \xi) = \text{constant}.$$

Camci and Ozgur ([5]) showed that the binormal vector of the curve is equal to

$$b = -\frac{\beta}{\kappa} \frac{\phi t}{\sqrt{1-\sigma^2}} + \frac{\alpha}{\kappa} \frac{\xi - \sigma t}{\sqrt{1-\sigma^2}},$$

where  $\beta = \frac{\sigma'}{\sqrt{1-\sigma^2}}$  and  $\alpha^2 + \beta^2 = \kappa^2$ . Thus we have

$$b = \frac{\alpha}{\kappa} \frac{\xi - \sigma t}{\sqrt{1-\sigma^2}}.$$

From the equation above, we see that  $b$  lies on the tangent space of the cylinder. Thus the normal vector of the curve and the normal of the cylinder are collinear and the curve is geodesic (minimal).  $\square$

**Corollary 2.2.** *Let  $\gamma$  be a curve which lies in a cylinder  $N^2(r)$  in  $R^3(-3)$ . As a result of Theorem 2.1, Corollary 2.1 and Theorem 2.3, the following are equivalent:*

- i) the curve is finite type;
- ii) the curve is 1-type;
- iii) the curve is a slant curve;
- iv)  $\theta'$  is a constant;
- v) the curve is geodesic (minimal) in cylinder.

### References

- [1] C. Baikoussis and D. E. Blair, *Finite type integral submanifolds of the contact manifold  $R^{2n+1}(-3)$* , Bull. Inst. Math. Acad. Sinica **19** (1991), no. 4, 327–350.
- [2] ———, *On Legendre curves in contact 3-manifolds*, Geom. Dedicata **49** (1994), no. 2, 135–142.
- [3] D. E. Blair, *Contact Manifolds in Riemannian Geometry*, Lecture Notes in Mathematics, Vol. 509. Springer-Verlag, Berlin-New York, 1976.
- [4] C. Camci, *A curves theory in contact geometry*, Ph. D. Thesis, Ankara University, 2007.
- [5] C. Camci and C. Ozgur, *On a curve with torsion is equal to 1 in 3-dimensional Sasakian manifold*, Preprint.
- [6] B. Y. Chen, J. Dillen, F. Verstraelen, and L. Vrancken, *Curves of finite type*, Geometry and topology of submanifolds, II (Avignon, 1988), 76–110, World Sci. Publ., Teaneck, NJ, 1990.
- [7] J. T. Cho, J.-I. Inoguchi, and J.-E. Lee, *On slant curves in Sasakian 3-manifolds*, Bull. Austral. Math. Soc. **74** (2006), no. 3, 359–367.
- [8] T. Takahashi, *Minimal immersions of Riemannian manifolds*, J. Math. Soc. Japan **18** (1966), 380–385.

CETIN CAMCI  
 DEPARTMENT OF MATHEMATICS  
 ONSEKIZ MART UNIVERSITY  
 17020 ÇANAKKALE, TURKEY  
*E-mail address:* ccamci@comu.edu.tr

H. HILMI HACISALIHOGLU  
 DEPARTMENT OF MATHEMATICS  
 FACULTY OF SCIENCE  
 BILECIK UNIVERSITY  
 11210 BILECIK, TURKEY  
*E-mail address:* hacisali@science.ankara.edu.tr