

Effects of Three Different Hip Positions in Frontal Plane on Activity of Abdominal Muscles During Active Straight-Leg Raise

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Abstract

Active straight-leg raise (ASLR) is a physical evaluation procedure to test lumbar spine stability. Several previous studies have reported various methods to control the activation of abdominal muscles during ASLR. We investigated the effects of three different hip positions in frontal plane on abdominal muscles to increase or decrease the difficulty level of lumbar spine stability exercise during ASLR in pain free subjects. Eleven young and healthy subjects voluntarily participated in this study (6 men, 5 women; mean age=24.0±1.2 years, height=160.0±7.3 cm, weight=55.0±10.6 kg, body mass index=21.5±2.3 kg/m²). The subjects had three trials on each ASLR with hip 10° adduction, neutral hip, and hip 30° abduction. Separate repeated-measures analysis of variance (ANOVA) and the post hoc Bonferroni tests (with $\alpha = .05/3 = .017$) were performed for each muscle among the three different hip positions in frontal plane (ASLR with hip 10° adduction, neutral hip, and hip 30° abduction). The ipsilateral external oblique (EO), contralateral EO, ipsilateral internal oblique/transverse abdominis (IO/TrA), and contralateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with hip 10° adduction. Also, the ipsilateral EO, contralateral EO, and ipsilateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with neutral hip. These results suggest that ASLR with hip 30° abduction and neutral would be useful method to strengthen the EO and IO/TrA. And, ASLR with hip 10° adduction would be effective in early stages of lumbar stabilization program due to low activation of EO and IO/TrA during maintaining of ASLR position with low load.

Key Words: Electromyograph; Lumbar spine stabilization; Strengthening exercise.

Introduction

Active straight-leg raise (ASLR) is a physical evaluation procedure with load transfer through the pelvis to test lumbar spine stability (Liebenson et al, 2009; Mens et al, 2001; Mens et al, 2002; Mens et al, 1999; O'Sullivan et al, 2002). A positive sign of the ASLR has been confirmed with the feeling of heaviness of the raising leg, pain in lumbopelvic region, weakness on manual resistance, or lumbar axial rotation which indicates inadequate lumbar control (Liebenson et al, 2009; Mens et al, 2001; Mens et al,

2002; O'Sullivan et al, 2002).

Various previous studies have inspected motor control strategies during ASLR to improve the understanding of the motor control mechanisms related with load transference through the pelvis (Beales et al, 2009; Hu et al, 2012; Liebenson et al, 2009; Mens et al, 1999; O'Sullivan et al, 2002; Park et al, 2013; Teyhen et al, 2009). Increased activation of abdominal muscles results in more lumbar spine stability under a given load (Brown and McGill, 2005). Particularly, rectus abdominis (RA), external oblique (EO), internal oblique (IO), and transverse abdominis

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(TrA) has been identified as key muscles for lumbar spine stability by pressing the iliac bones against the sacrum (Kim et al, 2011; Snijders et al, 1993; Vera-Garcia et al, 2007).

Several previous studies have claimed that lumbar spine stability can be enhanced with several methods (using of pelvic tilt, tactile stimulation, abdominal hollowing, weight, abdominal bracing, raising leg, gym ball, or wobble board). These methods used to control the difficulty level of lumbar spine stability exercises and compensatory movement of the lumbo-pelvic system (Garcia-Vaquero et al, 2012; Hu et al, 2012; Kavcic et al, 2004; McGill and Karpowicz, 2009; Park et al, 2013; Souza et al, 2001; Stevens et al, 2006). However, the level of lumbar spine stability was not fully investigated. And, there was no study using the three different hip positions in frontal plane (hip 10° adduction, neutral hip, and hip 30° abduction) to increase or decrease the difficulty level of lumbar spine stability exercise during ASLR.

Therefore, the purposes of this study was to investigate the effects of three different hip positions in frontal plane (hip 10° adduction, neutral hip, and hip 30° abduction) on activation of abdominal muscles in pain free subjects. This would help to clarify motor control strategies under various loads lumbar spine stability during ASLR. The hypothesis was that the three different hip positions in frontal plane would change the activation of abdominal muscles during ASLR in pain free subjects.

Methods

Subjects

Eleven young and healthy subjects voluntarily participated in this study (6 men, 5 women; mean age=24.0±1.2 years, height=160.0±7.3 cm, weight=55.0±10.6 kg, body mass index=21.5±2.3 kg/m²). The volunteers were included if they had no limitation of hip 10° adduction and hip 30° abduction. The volunteers were excluded if they had a history

of low back pain and lower extremity injuries, leg-length discrepancy, marked kyphosis or scoliosis, or neurologic disease (Kim et al, 2011; Park et al, 2013). The determining of dominance was investigated based on asking the participant to kick a soccer ball (Jacobs et al, 2005; Sung, 2013). All participants were right-leg dominant. All subjects provided written informed consent in agreement with the guidelines of the Yonsei University Wonju Institutional Review Board.

Procedure

The subjects had 20 min of familiarization session on ASLR with hip 10° adduction, neutral hip, and hip 30° abduction under the supervision of primary researcher. The EMG activity was measured three times on each ASLR with hip 10° adduction, neutral hip, and hip 30° abduction. To randomize the test order, we used three cards, each marked with one of the exercises. Each subject was asked to draw a card from a box to exclude any potential effects of measurement order. A target bar was placed 20 cm above the mat. Each subject raised their dominant leg, touched the target bar without bending the knee (Park et al, 2013), and maintained contact with the target bar for 5 s. EMG data were collected for 5 s at the end test position. The middle 3 s of collected data were averaged for statistical analysis. The participants were given a 5-min rest between test conditions to prevent muscular fatigue (Stevens et al, 2007).

ASLR with hip 10° adduction, neutral hip, and hip 30° abduction

The subject assumed a supine position on a therapeutic mat with the upper trunk, pelvis, and lower extremity in a straight line. Both arms were crossed on the subject's chest to prevent pushing the ground with their hands. The subject was asked to perform the ASLR in the supine position until they reached the target bar with condition of hip 10° adduction, neutral hip, and hip 30° abduction (Figure 1). A uni-

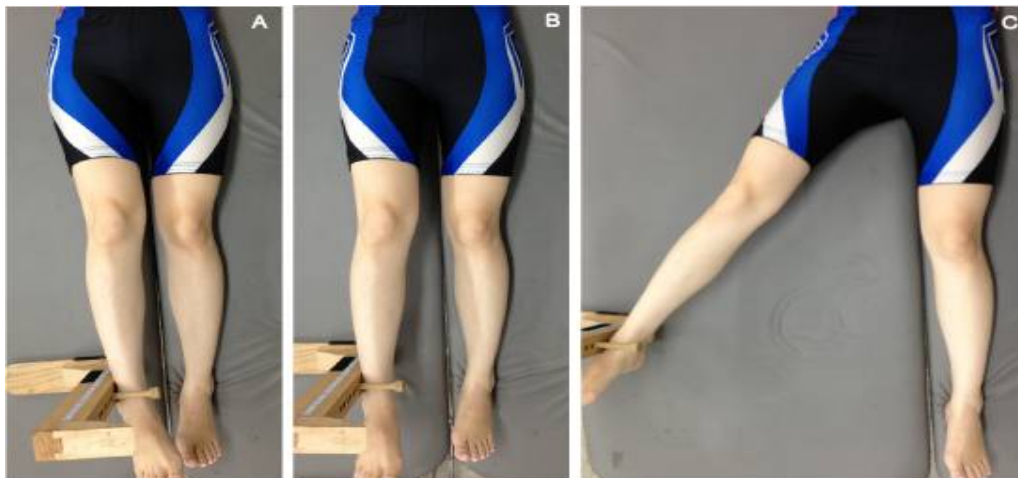


Figure 1. The active straight-leg raise in the supine position until they reached the target bar with condition in hip 10° adduction, neutral hip, and hip 30° abduction (A: hip 10° adduction, B: neutral hip, C: hip 30° abduction).

versal goniometer was used to measure the three different hip positions in frontal plane (hip 10° adduction, neutral hip, and hip 30° abduction) at the frontal plane and determine the position of target bar. Under this condition, the subjects were instructed to, “hold your position on the mat without moving your pelvis while you raise your dominant leg to touch the target bar by brushing the pillar of target bar with the later side of ankle to maintain the hip position in frontal plane” in each condition. The primary researcher was monitoring the compensation of pelvis motion.

Electromyography

Surface EMG was used to measure activity of abdominal muscles. The EMG data were collected bilaterally from the RA (2 cm lateral to the umbilicus), EO (directly above the ASIS, in direct line with the umbilicus, approximately 12~15 cm from the umbilicus), and IO/TrA muscles (halfway between the ASIS of the pelvis and the midline, just superior to the inguinal ligament) (Marshall and Murphy, 2003). The previous study stated that the EMG signal obtained from an electrode inferior to the anterior-superior iliac spine represents the combined activity of the IO and TrA (Marshall and Murphy, 2003). The signal representing IO/TrA accurately

demonstrates the functional activity of the muscle (Marshall and Murphy, 2003). The skin was shaved, sanded, and swabbed with alcohols-oaked cotton before electrode placement to minimize skin resistance. Disposable Ag/AgCl surface electrodes were positioned parallel to the muscle fibers with a center-to-center spacing of 2 cm. using the Tele-Myo 2400T EMG instrument with a wireless telemetry system (Noraxon Inc., AZ, USA). EMG data were collected at the sampling rate of 1000 Hz and analyzed with Myo-Research Master Edition 1.06 XP software (Noraxon Inc., AZ, USA). The raw signal in EMG was filtered using a digital band-pass filter (Lancosh FIR) between 20 and 400 Hz to eliminate movement artifacts, and a 60 Hz notch filter was used to minimize electrical noise. Root-mean-square (RMS) values were calculated with a moving window of 50 ms. For normalization, the RMS of a 5 s maximal voluntary isometric contraction (MVIC) was measured three times per the abdominal muscles to provide a basis for EMG signal amplitude normalization. For the RA, the subject was positioned supine in a hook-lying position with the feet supported and the thoracolumbar spine maximally flexed (curl-up position). Manual resistance was applied to the subject's shoulders in the direction of trunk extension. For the EO and the IO/TrA mus-

cles, the subject was supine in a hook-lying position with feet flat on the support surface. The trunk was maximally flexed and rotated to the left, with manual resistance at the shoulders applied in the direction of trunk extension and right rotation. For the other side, the subject was supine in a hook-lying position with the trunk flexed and maximally rotated to the right. Manual resistance was applied at the shoulders in the direction of trunk extension and left rotation (Escamilla et al., 2006).

We used middle 3 s of collected data to determine the mean amplitude of MVIC. The normalized muscle activity was presented as a percentage of the MVIC (Kim et al, 2011; Park et al, 2013).

Statistical analysis

Kolmogorov-smirnov Z-tests were performed to assess the normality of distribution. The independent variables were ASLR conditions (ASLR with hip 10° adduction, neutral hip, and hip 30° abduction). The dependent variables were EMG activity of each abdominal muscle. Statistical significance was set at .05. Separate analysis of variance (ANOVA) and the post hoc Bonferroni tests (with $\alpha=.05/3=.017$) were performed for each muscle among the three different hip positions in frontal plane (ASLR with hip 10° adduction, neutral hip, and hip 30° abduction). Statistical analysis was performed with SPSS ver. 18.0 for Windows (SPSS Inc., Chicago, IL).

Results

All dependent variables were established to approximate a normal distribution (Kolmogorov-smirnov Z-test, $p>.05$). The normalized EMG data and the results of the statistical analyses are shown in Figure 2. There was no significant difference in the ipsilateral RA ($F=3.641$, $p=.069$) and contralateral RA ($F=2.910$, $p=.106$). There were significant differences in activation of the ipsilateral EO ($F=10.362$, $p=.005$), contralateral EO ($F=10.115$, $p=.005$), the ipsilateral

IO/TrA ($F=9.868$, $p=.005$), and contralateral IO/TrA ($F=5.101$, $p=.033$) in ASLR with three different hip positions in frontal plane. The ipsilateral EO, contralateral EO, ipsilateral IO/TrA, and contralateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with hip 10° adduction. Also, the ipsilateral EO, contralateral EO, and ipsilateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with neutral hip. In all abdominal muscles, there was no significant difference between ASLR with hip 10° adduction and neutral hip.

Discussion

The aim of this study was to investigate the effects of three different hip positions in frontal plane on activation of abdominal muscles in pain free subjects. There was no significant difference in the bilateral RA. The ipsilateral EO, contralateral EO, ipsilateral IO/TrA, and contralateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with hip 10° adduction. Also, the ipsilateral EO, contralateral EO, and ipsilateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with neutral hip. In all abdominal muscles, there was no significant difference between ASLR with hip 10° adduction and neutral hip. These result partially support our hypothesis was that the three different hip positions in frontal plane would change the activation of abdominal muscles during ASLR in pain free subjects.

There was no significant difference in the bilateral RA. This result may imply that RA did not have a direct functional role in sustaining ASLR in different hip positions in frontal plane in healthy subjects. A previous study also reported that rectus abdominis showed no functional role during isometric axial rotation of the trunk (Ng et al, 2001).

The bilateral EO and IO/TrA were significantly greater in ASLR with hip 30° abduction compared

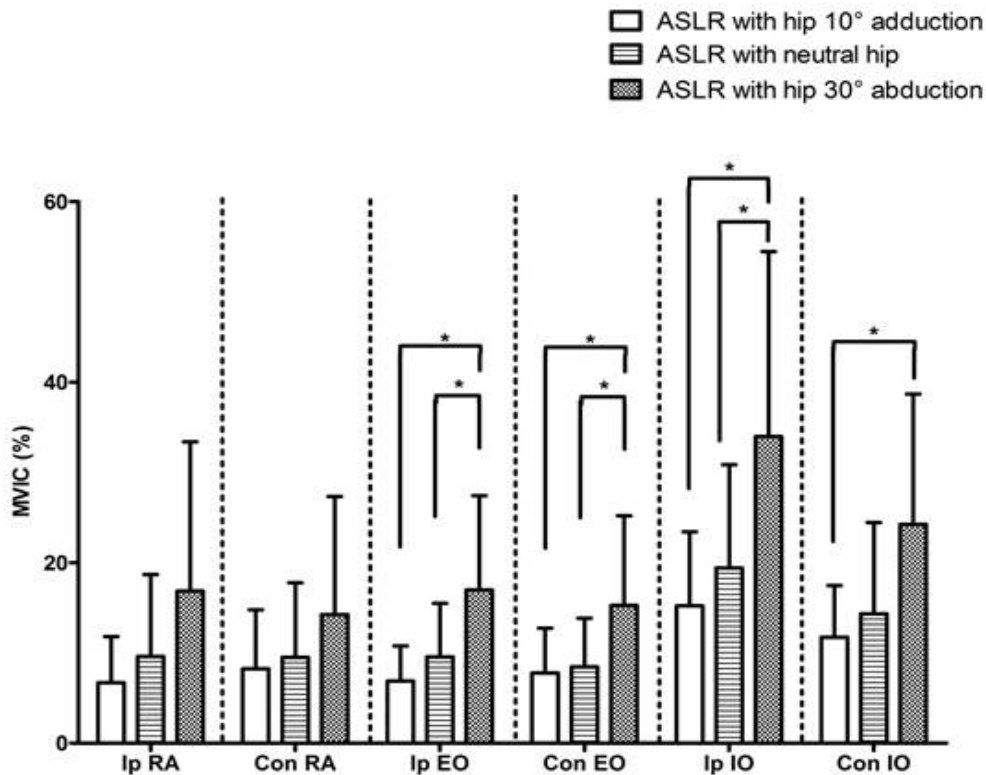


Figure 2. Maximal voluntary isometric contraction in the activity of abdominal muscles during ASLR with hip 10° adduction, neutral hip, and hip 30° abduction (RA: rectus abdominis; EO: external oblique abdominis; IO/TrA: internal oblique abdominis/transverse abdominis; Ip: ipsilateral; Con: contralateral; *significant difference at $p=0.017$).

with ASLR with hip 10° adduction. ASLR with hip 30° abduction would increase the rotational moment arm of the lifted lower limb during ASLR; thus, increased rotational moment arm from the hip joint is likely to require enhanced muscle activation of bilateral EO and IO/TrA compared with ASLR with hip 10° adduction. A previous study also presented that abdominal muscle (EO and IO/TrA) activity was significantly higher with weight load (Hu et al, 2012). The researcher claimed that the activity of abdominal muscles may also rotate the pelvis posteriorly, and thus contribute to counteracting the forward rotation of the ipsilateral ilium which is caused by load transfer from raised leg (Hu et al, 2012). Previous studies also reported that 30° hip abduction would change the location of muscle attachment and joint position which are important in effective motion production to generate the torque or a turning mo-

ment (Henderson et al, 2011; Kang et al, 2013). Therefore, our results suggest that ASLR with hip 30° abduction would be useful method to strengthen the EO and IO/TrA compared to other two conditions for later stages of lumbar stabilization program.

Besides, ASLR with hip 10° adduction produced less activation of the EO and IO/TrA when compared ASLR with hip 30° abduction. The less activation of the EO and IO/TrA would result in decrease of moment arm from the hip joint. A previous study reported that low load has benefits of reducing chance of pain and reflex inhibition, and restoring joint stabilization (Richardson and Jull, 1995). Consequently, ASLR with hip 10° adduction would be effective in early stages of lumbar stabilization program due to low activation of EO and IO/TrA during maintain ASLR position with low load.

The ipsilateral EO, contralateral EO, and ipsilateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with neutral hip. However, there was no significant difference between ASLR with hip 30° abduction and ASLR with neutral hip in contralateral IO/TrA. These results indicated that ASLR with hip 30° abduction did not influence significantly to the contralateral IO/TrA compared with ipsilateral IO/TrA. In a previous study, greater activation in ipsilateral of the abdominal wall (IO/TrA) was shown with increasing of axial load on the side of the raising leg during ASLR (Beales et al, 2009). In addition, relatively symmetrical pattern of EO activation was shown during ASLR with hip 10° adduction, neutral hip, and hip 30° abduction. A researcher insisted that EO might have not used to counteract the given axial load to pelvis in transverse plane (Hu et al, 2012).

This study has several limitations. First, we did not measure the kinematic data of pelvic motion as indications of lumbar spine stability. Second, we only recruited healthy and young Korean; thus, our findings cannot be generalized to other populations. Thirdly, no symptomatic group was used. Further studies are needed to inspect the effect of three different hip positions in frontal plane on activity of abdominal muscles during ASLR with mechanical low-back pain group. Also, longitudinal study of the effect of three different hip positions in frontal plane on activity of abdominal muscles during ASLR should be required.

Conclusion

The aim of this study was to investigate the effects of three different hip positions in frontal plane on activation of abdominal muscles in pain free subjects. The ipsilateral EO, contralateral EO, ipsilateral IO/TrA, and contralateral IO/TrA were significantly greater in ASLR with hip 30° abduction compared with ASLR with hip 10° adduction. These

results suggest that ASLR with hip 30° abduction would be useful method to strengthen the EO and IO/TrA for improving the lumbar spine stability. And, ASLR with hip 10° adduction would be effective in early stages of lumbar stabilization program due to low activation of EO and IO/TrA during maintaining ASLR position with low load.

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