GENERIC LIGHTLIKE SUBMANIFOLDS OF AN INDEFINITE KAEHLER MANIFOLD WITH A SEMI-SYMMETRIC METRIC CONNECTION

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Abstract. Depending on the characteristic vector filed ζ , a generic lightlike submanifold M in an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection has various characterizations. In this paper, when the characteristic vector filed ζ belongs to the screen distribution S(TM) of M, we provide some characterizations of (Lie-) recurrent generic lightlike submanifold M in an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection. Moreover, we characterize various generic lightlike submanifolds in an indefinite complex space form $\bar{M}(c)$ with a semi-symmetric metric connection.

1. Introduction

A lightlike submanifold M of an indefinite almost complex manifold \overline{M} , with an indefinite almost complex structure J, is called *generic* if there exists a screen distribution S(TM) of M, which is a complementary non-degenerate distribution of $Rad(TM) = TM \cap TM^{\perp}$ in TM, such that

$$(1.1) J(S(TM)^{\perp}) \subset S(TM),$$

where $S(TM)^{\perp}$ is the orthogonal complement of S(TM) in the tangent bundle $T\bar{M}$ of \bar{M} such that $T\bar{M} = S(TM) \oplus_{orth} S(TM)^{\perp}$. The notion of generic lightlike submanifolds was introduced by Jin-Lee [9] and later, studied by several authors [2, 5, 6, 10]. Moreover, Jin [8]

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studied generic lightlike submanifolds of an indefinite Kaehler manifold with a semi-symmetric non-metric connection. Lightlike hypersurfaces of an indefinite almost complex manifold are important examples of the generic lightlike submanifold. Much of the theory of generic submanifolds will be immediately generalized in a formal way to general lightlike submanifolds.

In 1924, Friedmann-Schouten [4] introduced the idea of a semi-symmetric connection as follow: A linear connection $\bar{\nabla}$ on a semi-Riemannian manifold (\bar{M}, \bar{g}) is called a *semi-symmetric connection* if its torsion tensor \bar{T} satisfies

(1.2)
$$\bar{T}(\bar{X}, \bar{Y}) = \theta(\bar{Y})\bar{X} - \theta(\bar{X})\bar{Y},$$

where θ is a 1-form associated with a smooth unit vector field ζ , which is called the *characteristic vector field* of \bar{M} , by $\theta(\bar{X}) = \bar{g}(\bar{X}, \zeta)$. In the followings, we denote by \bar{X} , \bar{Y} and \bar{Z} the smooth vector fields on \bar{M} . Moreover, if this connection is a metric one, *i.e.*, it satisfies $\bar{\nabla}\bar{g} = 0$, then $\bar{\nabla}$ is called a *semi-symmetric metric connection* on \bar{M} . The notion of a semi-symmetric metric connection on a Riemannian manifold was introduced by Yano [12].

Remark 1.1. Denote $\widetilde{\nabla}$ by the Levi-Civita connection of a semi-Riemannian manifold $(\overline{M}, \overline{g})$ with respect to \overline{g} . It is well known that a linear connection $\overline{\nabla}$ on \overline{M} is a semi-symmetric metric connection if and only if it satisfies

(1.3)
$$\bar{\nabla}_{\bar{X}}\bar{Y} = \tilde{\nabla}_{\bar{X}}\bar{Y} + \theta(\bar{Y})\bar{X} - \bar{g}(\bar{X},\bar{Y})\zeta.$$

The object of this paper is to study generic lightlike submanifolds M of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection $\bar{\nabla}$ subject to the condition that the characteristic vector field ζ of \bar{M} belongs to our screen distribution S(TM) of M. In Section 3, we provide several new results on such a generic lightlike submanifold. In Section 4, we characterize generic lightlike submanifolds of an indefinite complex space form $\bar{M}(c)$ with a semi-symmetric metric connection subject such that ζ belongs to S(TM).

2. Semi-symmetric metric connections

Let $\bar{M}=(\bar{M},\bar{g},J)$ be an indefinite Kaehler manifold, where \bar{g} is a semi-Riemannian metric and J is an indefinite almost complex structure;

(2.1)
$$J^2 \bar{X} = -\bar{X}, \qquad \bar{g}(J\bar{X}, J\bar{Y}) = \bar{g}(\bar{X}, \bar{Y}), \qquad (\tilde{\nabla}_{\bar{X}} J) \bar{Y} = 0.$$

Replacing the Levi-Civita connection $\widetilde{\nabla}$ by the semi-symmetric metric connection $\overline{\nabla}$, the third equation of three equations in (2.1) is reduced to

$$(2.2) \qquad (\bar{\nabla}_{\bar{X}}J)\bar{Y} = \theta(J\bar{Y})\bar{X} - \theta(\bar{Y})J\bar{X} - \bar{g}(\bar{X},J\bar{Y})\zeta + \bar{g}(\bar{X},\bar{Y})J\zeta.$$

Let (M,g) be an m-dimensional lightlike submanifold of an indefinite Kaehler manifold (\bar{M},\bar{g}) of dimension (m+n). Then the radical distribution $Rad(TM) = TM \cap TM^{\perp}$ of M is a subbundle of the tangent bundle TM and the normal bundle TM^{\perp} , of rank $r \ (1 \le r \le \min\{m,n\})$. In general, there exist two complementary non-degenerate distributions S(TM) and $S(TM^{\perp})$ of Rad(TM) in TM and TM^{\perp} , respectively, which are called the $screen\ distribution$ and the co- $screen\ distribution$ of M [1], such that

$$TM = Rad(TM) \oplus_{orth} S(TM), \ TM^{\perp} = Rad(TM) \oplus_{orth} S(TM^{\perp}),$$

where \oplus_{orth} denotes the orthogonal direct sum. Denote by F(M) the algebra of smooth functions on M and by $\Gamma(E)$ the F(M) module of smooth sections of a vector bundle E over M. Let X, Y, Z and W be the vector fields on M, unless otherwise specified. We use the following range of indices:

$$i, j, k, \dots \in \{1, \dots, r\}, \quad a, b, c, \dots \in \{r + 1, \dots, n\}.$$

Let tr(TM) and ltr(TM) be complementary vector bundles to TM in $T\bar{M}_{|M}$ and TM^{\perp} in $S(TM)^{\perp}$, respectively, and let $\{N_1, \dots, N_r\}$ be a null basis of $ltr(TM)_{|\mathcal{U}}$, where \mathcal{U} is a coordinate neighborhood of M, such that

$$\bar{g}(N_i, \xi_i) = \delta_{ij}, \quad \bar{g}(N_i, N_i) = 0,$$

where $\{\xi_1, \dots, \xi_r\}$ is a null basis of $Rad(TM)_{|_{\mathcal{U}}}$. Then we have

$$T\bar{M} = TM \oplus tr(TM) = \{Rad(TM) \oplus tr(TM)\} \oplus_{orth} S(TM)$$
$$= \{Rad(TM) \oplus tr(TM)\} \oplus_{orth} S(TM) \oplus_{orth} S(TM^{\perp}).$$

A lightlike submanifold $M = (M, g, S(TM), S(TM^{\perp}))$ of \bar{M} is called an r-lightlike submanifold [1, 3] if $1 \le r < \min\{m, n\}$. For an r-lightlike M, we see that $S(TM) \ne \{0\}$ and $S(TM^{\perp}) \ne \{0\}$. In the sequel, by saying that M is a lightlike submanifold we shall mean that it is an r-lightlike submanifold, with following local quasi-orthonormal field of frames of \bar{M} :

$$\{\xi_1, \dots, \xi_r, N_1, \dots, N_r, F_{r+1}, \dots, F_m, E_{r+1}, \dots, E_n\},\$$

where $\{F_{r+1}, \dots, F_m\}$ and $\{E_{r+1}, \dots, E_n\}$ are orthonormal bases of S(TM) and $S(TM^{\perp})$, respectively. Denote $\epsilon_a = \bar{g}(E_a, E_a)$. Then $\epsilon_a \delta_{ab} = \bar{g}(E_a, E_b)$.

Let P be the projection morphism of TM on S(TM). Then the local Gauss and Weingarten formulae of M and S(TM) are given respectively by

(2.3)
$$\bar{\nabla}_X Y = \nabla_X Y + \sum_{i=1}^r h_i^{\ell}(X, Y) N_i + \sum_{a=r+1}^n h_a^{s}(X, Y) E_a,$$

(2.4)
$$\bar{\nabla}_X N_i = -A_{N_i} X + \sum_{j=1}^r \tau_{ij}(X) N_j + \sum_{a=r+1}^n \rho_{ia}(X) E_a,$$

(2.5)
$$\bar{\nabla}_X E_a = -A_{E_a} X + \sum_{i=1}^r \lambda_{ai}(X) N_i + \sum_{b=r+1}^n \mu_{ab}(X) E_b;$$

(2.6)
$$\nabla_X PY = \nabla_X^* PY + \sum_{i=1}^r h_i^*(X, PY) \xi_i,$$

(2.7)
$$\nabla_X \xi_i = -A_{\xi_i}^* X - \sum_{j=1}^r \tau_{ji}(X) \xi_j,$$

where ∇ and ∇^* are induced linear connections induced from $\bar{\nabla}$ on M and S(TM), respectively, h_i^ℓ and h_a^s are called the local second fundamental forms on M, h_i^* are called the local second fundamental forms on S(TM). A_{N_i} , A_{E_a} and $A_{\xi_i}^*$ are linear operators on M, which are called the shape operators, and τ_{ij} , ρ_{ia} , λ_{ai} and μ_{ab} are 1-forms on M. Using (1.2), (1.3) and (2.3), we see that

(2.8)
$$(\nabla_X g)(Y, Z) = \sum_{i=1}^r \{ h_i^{\ell}(X, Y) \eta_i(Z) + h_i^{\ell}(X, Z) \eta_i(Y) \},$$

(2.9)
$$T(X,Y) = \theta(Y)X - \theta(X)Y,$$

where η_i 's are 1-forms such that

$$\eta_i(X) = \bar{g}(X, N_i).$$

From the facts that $h_i^{\ell}(X,Y) = \bar{g}(\bar{\nabla}_X Y, \xi_i)$ and $\epsilon_a h_a^s(X,Y) = \bar{g}(\bar{\nabla}_X Y, E_a)$, we know that h_i^{ℓ} and h_a^s are symmetric and independent of the choice of S(TM). The above local second fundamental forms are

related to their shape operators by

(2.10)
$$h_i^{\ell}(X,Y) = g(A_{\xi_i}^* X, Y) - \sum_{k=1}^r h_k^{\ell}(X, \xi_i) \eta_k(Y),$$

(2.11)
$$\epsilon_a h_a^s(X, Y) = g(A_{E_a} X, Y) - \sum_{k=1}^r \lambda_{ak}(X) \eta_k(Y),$$

(2.12)
$$h_i^*(X, PY) = g(A_{N_i}X, PY).$$

Applying $\bar{\nabla}_X$ to $\bar{g}(E_a, E_b) = \epsilon \delta_{ab}$, $g(\xi_i, \xi_j) = 0$, $\bar{g}(\xi_i, E_a) = 0$, $\bar{g}(N_i, N_j) = 0$ and $\bar{g}(N_i, E_a) = 0$ by turns, we obtain $\epsilon_b \mu_{ab} + \epsilon_a \mu_{ba} = 0$ and

(2.13)
$$h_i^{\ell}(X,\xi_j) + h_j^{\ell}(X,\xi_i) = 0,$$
 $h_a^{s}(X,\xi_i) = -\epsilon_a \lambda_{ai}(X),$ $\eta_j(A_{N_i}X) + \eta_i(A_{N_j}X) = 0,$ $\bar{g}(A_{E_a}X,N_i) = \epsilon_a \rho_{ia}(X).$

Furthermore, using $(2.13)_1$, we see that

(2.14)
$$h_i^{\ell}(X, \xi_i) = 0, \quad h_i^{\ell}(\xi_j, \xi_k) = 0, \quad A_{\xi_i}^* \xi_i = 0.$$

Here, $(2.13)_i$ denotes the *i*-th equation of (2.13). We use the same notations for any others.

Definition 2.1. We say that a lightlike submanifold M of a semi-Riemannian manifold (\bar{M}, \bar{g}) is irrotational[11] if $\bar{\nabla}_X \xi_i \in \Gamma(TM)$ for all $i \in \{1, \dots, r\}$.

Remark 2.2. From (2.3) and $(2.13)_2$, the above definition is equivalent to

(2.15)
$$h_j^{\ell}(X, \xi_i) = 0, \qquad h_a^s(X, \xi_i) = \lambda_{ai}(X) = 0.$$

3. Structure equations

Let M be a generic lightlike submanifold of \overline{M} . From (1.1) we show that J(Rad(TM)), J(ltr(TM)) and $J(S(TM^{\perp}))$ are subbundles of S(TM). Thus there exist two non-degenerate almost complex distributions H_o and H with respect to J, i.e., $J(H_o) = H_o$ and J(H) = H, such that

$$S(TM) = \{J(Rad(TM)) \oplus J(ltr(TM))\} \oplus_{orth} J(S(TM^{\perp})) \oplus_{orth} H_o,$$

$$H = Rad(TM) \oplus_{orth} J(Rad(TM)) \oplus_{orth} H_o.$$

In this case, the tangent bundle TM of M is decomposed as follow:

$$(3.1) TM = H \oplus J(ltr(TM)) \oplus_{orth} J(S(TM^{\perp})).$$

Consider r-th local null vector fields U_i and V_i , (n-r)-th local non-null unit vector fields W_a , and their 1-forms u_i , v_i and w_a defined by

$$(3.2) U_i = -JN_i, V_i = -J\xi_i, W_a = -JE_a, (3.3) u_i(X) = g(X, V_i), v_i(X) = g(X, U_i), w_a(X) = \epsilon_a g(X, W_a).$$

Denote by S the projection morphism of TM on H and by F the tensor field of type (1,1) globally defined on M by $F=J\circ S$. Then JX is expressed as

(3.4)
$$JX = FX + \sum_{i=1}^{r} u_i(X)N_i + \sum_{a=r+1}^{n} w_a(X)E_a.$$

Applying J to (3.4) and using $(2.1)_1$, (3.2) and (3.4), we have

(3.5)
$$F^{2}X = -X + \sum_{i=1}^{r} u_{i}(X)U_{i} + \sum_{a=r+1}^{n} w_{a}(X)W_{a}.$$

By using $(2.3)_2$ and (3.4), we obtain

(3.6)
$$g(FX, FY) = g(X, Y) - \sum_{i=1}^{r} \{u_i(X)v_i(Y) + u_i(Y)v_i(X)\}$$
$$- \sum_{a=r+1}^{n} \epsilon_a w_a(X)w_a(Y).$$

In the sequel, we say that F is the *structure tensor field* of M.

Now we shall assume that the characteristic vector field ζ belongs to the screen distribution S(TM) of M. Applying $\bar{\nabla}_X$ to (3.2) and (3.4) by turns and using $(2.2) \sim (2.7)$, $(2.10) \sim (2.12)$ and $(3.2) \sim (3.4)$, we get

(3.7)
$$\begin{cases} h_j^{\ell}(X, U_i) = h_i^*(X, V_j) - \theta(V_j)\eta_i(X), \\ \epsilon_a h_a^s(X, U_i) = h_i^*(X, W_a) - \theta(W_a)\eta_i(X), \\ h_j^{\ell}(X, V_i) = h_i^{\ell}(X, V_j), \quad h_a^s(X, V_i) = \epsilon_a h_i^{\ell}(X, W_a), \\ \epsilon_b h_b^s(X, W_a) = \epsilon_a h_a^s(X, W_b), \end{cases}$$

(3.8)
$$\nabla_X U_i = F(A_{N_i} X) + \sum_{j=1}^r \tau_{ij}(X) U_j + \sum_{a=r+1}^n \rho_{ia}(X) W_a + \theta(U_i) X - v_i(X) \zeta - \eta_i(X) F \zeta,$$

(3.9)
$$\nabla_{X} V_{i} = F(A_{\xi_{i}}^{*}X) - \sum_{j=1}^{r} \tau_{ji}(X) V_{j} + \sum_{j=1}^{r} h_{j}^{\ell}(X, \xi_{i}) U_{j} - \sum_{a=r+1}^{n} \epsilon_{a} \lambda_{ai}(X) W_{a} + \theta(V_{i}) X - u_{i}(X) \zeta,$$

(3.10)
$$\nabla_X W_a = F(A_{E_a} X) + \sum_{i=1}^r \lambda_{ai}(X) U_i + \sum_{b=r+1}^n \mu_{ab}(X) W_b, + \theta(W_a) X - \epsilon_a w_a(X) \zeta,$$

$$(3.11) \quad (\nabla_X F)Y = \sum_{i=1}^r u_i(Y) A_{N_i} X + \sum_{a=r+1}^n w_a(Y) A_{E_a} X$$
$$- \sum_{i=1}^r h_i^{\ell}(X, Y) U_i - \sum_{a=r+1}^n h_a^{s}(X, Y) W_a$$
$$+ \theta(FY) X - \theta(Y) FX - \bar{g}(X, JY) \zeta + g(X, Y) F\zeta.$$

4. Recurrent and Lie recurrent generic submanifolds

Theorem 4.1. There exist no generic lightlike submanifolds of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that ζ belongs to S(TM) and F is parallel with respect to the connection ∇ .

Proof. Assume that F is parallel with respect to the connection ∇ . Replacing Y by ξ_j to (3.11) and using the fact that $F\xi_j = -V_j$, we obtain

$$(4.1) \quad \sum_{k=1}^{r} h_k^{\ell}(X, \xi_j) U_k + \sum_{a=r+1}^{n} h_a^{s}(X, \xi_j) W_a + \theta(V_j) X - u_j(X) \zeta = 0.$$

Taking the scalar product with N_i to (4.1) and then, taking $X = \xi_j$, we get $\theta(V_i) = 0$. Also taking the scalar product with U_i to (4.1) and then, taking $X = U_j$ and using $\theta(V_j) = 0$, we get $\theta(U_i) = 0$. Therefore, we obtain

$$\theta(V_i) = 0,$$
 $\theta(U_i) = 0.$

Taking the scalar product with W_b to (4.1) and using $\theta(V_i) = 0$, we have

(4.2)
$$h_a^s(X,\xi_i) = \epsilon_a \theta(W_a) u_i(X).$$

Replacing Y by W_a to (3.11) such that $\nabla_X F = 0$, we have

$$A_{E_a} X = \sum_{i=1}^{r} h_i^{\ell}(X, W_a) U_i + \sum_{b=r+1}^{n} h_b^{s}(X, W_a) W_b + \theta(W_a) FX - \epsilon_a w_a(X) F\zeta.$$

Taking the scalar product with U_i to this equation, we obtain

$$(4.3) h_a^s(X, U_i) = -\epsilon_a \theta(W_a) \eta_i(X).$$

Taking $X = U_i$ to (4.2) and also, taking $X = \xi_i$ to (4.3) and then, comparing these two resulting equations, we obtain $\theta(W_a) = 0$. Taking the scalar product with ζ to (4.1) and using the facts that $\theta(V_i) = \theta(U_i) = \theta(W_a) = 0$, we have $u_j(X) = 0$ for all $X \in \Gamma(TM)$. It is a contradiction to $u_j(U_j) = 1$. Thus there exist no generic lightlike submanifolds of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection subject such that ζ belongs to S(TM) and F is parallel with respect to the connection ∇ .

Definition 4.2. The structure tensor field F of M is said to be recurrent [6] if there exists a 1-form ϖ on TM such that

$$(\nabla_X F)Y = \varpi(X)FY.$$

A generic lightlike submanifold M of an indefinite Kaehler manifold \bar{M} is called recurrent if it admits a recurrent structure tensor field F.

Theorem 4.3. There exist no recurrent generic lightlike submanifolds of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that the characteristic vector field ζ of \bar{M} belongs to S(TM).

Proof. From the above definition and (3.11), we obtain

$$(4.4) \qquad \varpi(X)FY = \sum_{i=1}^{r} u_i(Y)A_{N_i}X + \sum_{a=r+1}^{n} w_a(Y)A_{E_a}X$$
$$-\sum_{i=1}^{r} h_i^{\ell}(X,Y)U_i - \sum_{a=r+1}^{n} h_a^{s}(X,Y)W_a$$
$$+\theta(FY)X - \theta(Y)FX - \bar{g}(X,JY)\zeta + g(X,Y)F\zeta.$$

Replacing Y by ξ_j to this and using the fact that $F\xi_j = -V_j$, we get (4.5)

$$\varpi(X)V_{j} = \sum_{k=1}^{r} h_{k}^{\ell}(X,\xi_{j})U_{k} + \sum_{b=r+1}^{n} h_{b}^{s}(X,\xi_{j})W_{b} + \theta(V_{j})X - u_{j}(X)\zeta.$$

Taking the scalar product with N_i to this, we obtain $\theta(V_j)\eta_i(X) = 0$. Taking $X = \xi_j$ to this equation, we have $\theta(V_i) = 0$ for all i. Taking the scalar product with V_i and W_a to (4.5) and using $\theta(V_i) = 0$, we obtain

$$(4.6) h_i^{\ell}(X,\xi_i) = 0, h_a^s(X,\xi_i) = \epsilon_a \theta(W_a) u_i(X).$$

Replacing Y by W_a to (4.4) and using the fact that $FW_a = 0$, we have

$$A_{E_a} X = \sum_{i=1}^{r} h_i^{\ell}(X, W_a) U_i + \sum_{b=r+1}^{n} h_b^{s}(X, W_a) W_b + \theta(W_a) F X - \epsilon_a w_a(X) F \zeta.$$

Taking the scalar product with U_i to this equation, we obtain

$$(4.7) h_a^s(X, U_i) = -\epsilon_a \theta(W_a) \eta_i(X).$$

Taking $X = \xi_i$ to (4.7) and also, taking $X = U_i$ to (4.6)₂ and then, comparing two resulting equations, we get $\theta(W_a) = 0$. As $\theta(W_a) = 0$, we get

$$h_i^{\ell}(X, \xi_i) = 0,$$
 $h_a^{s}(X, \xi_i) = 0.$

Using these equations and the fact that $\theta(V_i) = 0$, Eq. (4.5) is reduced to

$$\varpi(X)V_j = -u_j(X)\zeta.$$

Taking the scalar product with ζ to this, we have $u_j(X) = 0$ for all $X \in \Gamma(TM)$. It is a contradiction to $u_j(U_j) = 1$. Thus there exist no recurrent generic lightlike submanifolds of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that ζ belongs to S(TM).

Definition 4.4. The structure tensor field F of M is said to be Lie recurrent [7] if there exists a 1-form ϑ on M such that

$$(\mathcal{L}_X F)Y = \vartheta(X)FY,$$

where \mathcal{L}_{X} denotes the Lie derivative on M with respect to X, that is,

$$(\mathcal{L}_X F)Y = [X, FY] - F[X, Y].$$

In case $\mathcal{L}_X F = 0$, we say that F is Lie parallel. A generic lightlike submanifold M of an indefinite Kaehler manifold \bar{M} is called Lie recurrent if it admits a Lie recurrent structure tensor field F.

Theorem 4.5. Let M be a Lie recurrent lightlike submanifold of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that the characteristic vector field ζ of \bar{M} belongs to S(TM). Then F is Lie parallel,

Proof. Using the above definition, (2.9) and (3.11), we obtain

(4.8)
$$\vartheta(X)FY = -\nabla_{FY}X + F\nabla_{Y}X - \bar{g}(X,JY)\zeta + g(X,Y)F\zeta + \sum_{i=1}^{r} u_{i}(Y)A_{N_{i}}X + \sum_{a=r+1}^{n} w_{a}(Y)A_{E_{a}}X - \sum_{i=1}^{r} h_{i}^{\ell}(X,Y)U_{i} - \sum_{a=r+1}^{n} h_{a}^{s}(X,Y)W_{a}.$$

Replacing Y by ξ_i and also, Y by V_i to (4.8), respectively, we have

(4.9)
$$-\vartheta(X)V_{j} = \nabla_{V_{j}}X + F\nabla_{\xi_{j}}X + u_{j}(X)\zeta$$
$$-\sum_{i=1}^{r} h_{i}^{\ell}(X,\xi_{j})U_{i} - \sum_{a=r+1}^{n} h_{a}^{s}(X,\xi_{j})W_{a},$$
$$\vartheta(X)\xi_{j} = -\nabla_{\xi_{j}}X + F\nabla_{V_{j}}X + u_{j}(X)F\zeta$$
$$-\sum_{i=1}^{r} h_{i}^{\ell}(X,V_{j})U_{i} - \sum_{a=r+1}^{n} h_{a}^{s}(X,V_{j})W_{a}.$$

Taking the scalar product with U_i to (4.9) and N_i to (4.10), we get

$$-\delta_{ij}\vartheta(X) = g(\nabla_{V_j}X, U_i) - \bar{g}(\nabla_{\xi_j}X, N_i) + \theta(U_i)u_j(X),$$

$$\delta_{ij}\vartheta(X) = g(\nabla_{V_j}X, U_i) - \bar{g}(\nabla_{\xi_j}X, N_i) + \theta(U_i)u_j(X),$$

respectively. From these two equations, we get $\vartheta=0.$ Thus F is Lie parallel. \Box

Proposition 4.6. Let M be a Lie recurrent lightlike submanifold of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that the characteristic vector field ζ of \bar{M} belongs to S(TM). Then τ_{ij} and ρ_{ia} satisfy $\tau_{ij} \circ F = 0$ and $\rho_{ia} \circ F = 0$. Moreover,

$$\tau_{ij}(X) = \sum_{k=1}^{r} u_k(X) g(A_{N_k} V_j, N_i).$$

Proof. Taking the scalar product with N_i to (4.9) such that $X = W_a$ and using (2.11), (2.13)₄ and (3.10), we get $h_a^s(U_i, V_j) = \rho_{ia}(\xi_j)$. Also, taking the scalar product with W_a to (4.10) such that $X = U_i$ and using

(3.8), we have $h_a^s(U_i, V_j) = -\rho_{ia}(\xi_j)$. Thus $\rho_{ia}(\xi_j) = 0$ and $h_a^s(U_i, V_j) = 0$.

Taking the scalar product with U_i to (4.9) such that $X = W_a$ and using (2.11), (2.13)_{2,4} and (3.10), we get $\epsilon_a \rho_{ia}(V_j) = \lambda_{aj}(U_i)$. Also, taking the scalar product with W_a to (4.9) such that $X = U_i$ and using (2.13)₂ and (3.8), we get $\epsilon_a \rho_{ia}(V_j) = -\lambda_{aj}(U_i)$. Thus $\rho_{ia}(V_j) = 0$ and $\lambda_{aj}(U_i) = 0$.

Taking the scalar product with V_i to (4.9) such that $X = W_a$ and using (2.13)₂, (3.7)₄ and (3.10), we obtain $\lambda_{ai}(V_j) = -\lambda_{aj}(V_i)$. Also, taking the scalar product with W_a to (4.9) such that $X = V_i$ and using (2.13)₂ and (3.9), we have $\lambda_{ai}(V_j) = \lambda_{aj}(V_i)$. Thus we obtain $\lambda_{ai}(V_j) = 0$.

Taking the scalar product with W_a to (4.9) such that $X = \xi_i$ and using (2.7), (2.10) and (2.13)₂, we get $h_i^{\ell}(V_j, W_a) = \lambda_{ai}(\xi_j)$. Also, taking the scalar product with V_i to (4.10) such that $X = W_a$ and using (3.10), we have $h_i^{\ell}(V_j, W_a) = -\lambda_{ai}(\xi_j)$. Thus $\lambda_{ai}(\xi_j) = 0$ and $h_i^{\ell}(V_j, W_a) = 0$.

Summarizing the above results, we obtain

$$(4.11)\rho_{ia}(\xi_j) = 0, \ \rho_{ia}(V_j) = 0, \ \lambda_{ai}(U_j) = 0, \ \lambda_{ai}(V_j) = 0, \ \lambda_{ai}(\xi_j) = 0, h_a^s(U_i, V_j) = h_i^\ell(U_i, W_a) = 0, \qquad h_i^\ell(V_j, W_a) = h_a^s(V_j, V_i) = 0.$$

Taking the scalar product with N_i to (4.8) and using (2.13)₄, we have

(4.12)
$$-\bar{g}(\nabla_{FY}X, N_i) + g(\nabla_Y X, U_i) + \theta(U_i)g(X, Y)$$

$$+ \sum_{k=1}^r u_k(Y)\bar{g}(A_{N_k}X, N_i) + \sum_{a=r+1}^n \epsilon_a w_a(Y)\rho_{ia}(X) = 0.$$

Taking $X = \xi_j$ and $Y = U_k$ to (4.12) and using (2.7) and (2.10), we have

$$h_j^{\ell}(U_k, U_i) = \eta_i(A_{N_k} \xi_j).$$

As h_j^{ℓ} are symmetric, from the last equation, we see that $\eta_i(A_{N_k}\xi_j)$ is symmetric with respect to i and k. From this result and $(2.13)_4$, we obtain

(4.13)
$$g(A_{N_k}\xi_j, N_i) = 0, \qquad h_i^*(U_k, V_j) = 0.$$

Taking $X = \xi_j$ to (4.12) and using (2.7), (2.10), (4.11)₁ and (4.13)₁, we get

$$(4.14) h_j^{\ell}(X, U_i) = \tau_{ij}(FX).$$

Taking $X = U_i$ to (4.8) and using (2.12), (3.5), (3.7)_{1,2} and (3.8), we get

$$\sum_{k=1}^{r} u_k(Y) A_{N_k} U_i + \sum_{a=r+1}^{n} w_a(Y) A_{E_a} U_i$$

$$-A_{N_i} Y + \eta_i(Y) \zeta + v_i(Y) F \zeta - F(A_{N_i} F Y)$$

$$-\sum_{j=1}^{r} \tau_{ij}(F Y) U_j - \sum_{a=r+1}^{n} \rho_{ia}(F Y) W_a = 0.$$

Taking the scalar product with V_j to (4.15) and using (2.11), (2.12), (3.7)₁, (4.11)₆ and (4.13)₂, we obtain

$$h_j^{\ell}(X, U_i) = -\tau_{ij}(FX).$$

Comparing this equation with (4.14), we obtain

(4.16)
$$\tau_{ij}(FX) = 0, \qquad h_j^{\ell}(X, U_i) = 0.$$

Taking $X = V_j$ to (4.12) and using (2.10), (3.9), (4.11)₂ and (4.16)₂, we get

$$\tau_{ij}(X) = \sum_{k=1}^{r} u_k(X) \bar{g}(A_{N_k} V_j, N_i).$$

Taking the scalar product with U_j to (4.15) and then, taking $Y = W_a$ and using (2.11), (2.12) and (3.7)₂, we have

$$(4.17) h_i^*(W_a, U_j) = \epsilon_a h_a^s(U_i, U_j) = \epsilon_a h_a^s(U_j, U_i) = h_i^*(U_j, W_a).$$

Taking the scalar product with W_a to (4.15), we have

$$\epsilon_{a}\rho_{ia}(FY) = -h_{i}^{*}(Y, W_{a}) + \theta(W_{a})\eta_{i}(Y) + \sum_{k=1}^{r} u_{k}(Y)h_{k}^{*}(U_{i}, W_{a}) + \sum_{b=r+1}^{n} \epsilon_{b}w_{b}(Y)h_{b}^{s}(U_{i}, W_{a}).$$

Taking the scalar product with U_i to (4.8) such that $X = W_a$ and using (2.11), (2.12), (2.13)₄, (3.5), (3.7)₂ and (4.17), we get

$$\epsilon_{a}\rho_{ia}(FY) = h_{i}^{*}(Y, W_{a}) - \theta(W_{a})\eta_{i}(Y) - \sum_{k=1}^{r} u_{k}(Y)h_{k}^{*}(U_{i}, W_{a}) - \sum_{k=r+1}^{n} \epsilon_{b}w_{b}(Y)h_{b}^{s}(U_{i}, W_{a}).$$

Comparing the last two equations, we obtain $\rho_{ia}(FY) = 0$.

Theorem 4.7. There exist no generic lightlike submanifolds of an indefinite Kaehler manifold \bar{M} with a semi-symmetric metric connection such that ζ belongs to S(TM), $V_i(i=1,\cdots,r)$ are parallel with respect to ∇ and $h_a^s(X,\xi_i)=0$ for any vector field X on M.

Proof. Assume that $V_i(i=1,\dots,r)$ are parallel with respect to the connection ∇ and $h_a^s(X,\xi_i)=0$ for any vector field X on M. Taking the scalar product with W_a to (3.9) and using $\lambda_{ai}(X)=h_a^s(X,\xi_i)=0$, we get

$$\epsilon_a \theta(V_i) w_a(X) = \theta(W_a) u_i(X).$$

Taking $X = W_a$ and $X = U_i$ to this equation by turns, we obtain

$$\theta(V_i) = 0,$$
 $\theta(W_a) = 0.$

Taking the scalar product with V_j to (3.9) and using $\theta(V_i) = 0$, we have

$$h_i^{\ell}(X, \xi_i) = 0.$$

Taking the scalar product with ζ and N_j to (3.9) by turns and using the last two equations, we obtain

$$h_i^{\ell}(X, F\zeta) = -u_i(X), \qquad h_i^{\ell}(X, U_j) = 0.$$

From these two equations, we have the following impossible result:

$$-\delta_{ij} = -u_i(U_j) = h_i^{\ell}(U_j, F\zeta) = h_i^{\ell}(F\zeta, U_j) = 0.$$

Thus we have our theorem

5. Indefinite complex space forms

Denote by \bar{R} , R and R^* the curvature tensor of the semi-symmetric metric connection $\bar{\nabla}$ on \bar{M} and the induced linear connections ∇ and ∇^* on M and S(TM), respectively. Using the Gauss-Weingarten formulae,

we obtain Gauss equations for M and S(TM), respectively:

$$\begin{split} (5.1) \qquad \bar{R}(X,Y)Z &= R(X,Y)Z \\ &+ \sum_{i=1}^{r} \{h_{i}^{\ell}(X,Z)A_{N_{i}}Y - h_{i}^{\ell}(Y,Z)A_{N_{i}}X\} \\ &+ \sum_{a=r+1}^{n} \{h_{a}^{s}(X,Z)A_{E_{a}}Y - h_{a}^{s}(Y,Z)A_{E_{a}}X\} \\ &+ \sum_{i=1}^{r} \{(\nabla_{X}h_{i}^{\ell})(Y,Z) - (\nabla_{Y}h_{i}^{\ell})(X,Z) \\ &+ \sum_{j=1}^{r} [\tau_{ji}(X)h_{j}^{\ell}(Y,Z) - \tau_{ji}(Y)h_{j}^{\ell}(X,Z)] \\ &+ \sum_{a=r+1}^{n} [\lambda_{ai}(X)h_{a}^{s}(Y,Z) - \lambda_{ai}(Y)h_{a}^{s}(X,Z)] \\ &- \theta(X)h_{i}^{\ell}(Y,Z) + \theta(Y)h_{i}^{\ell}(X,Z)\}N_{i} \\ &+ \sum_{a=r+1}^{n} \{(\nabla_{X}h_{a}^{s})(Y,Z) - (\nabla_{Y}h_{a}^{s})(X,Z) \\ &+ \sum_{i=1}^{r} [\rho_{ia}(X)h_{i}^{\ell}(Y,Z) - \rho_{ia}(Y)h_{i}^{\ell}(X,Z)] \\ &+ \sum_{b=r+1}^{n} [\mu_{ba}(X)h_{b}^{s}(Y,Z) - \mu_{ba}(Y)h_{b}^{s}(X,Z)] \\ &- \theta(X)h_{a}^{s}(Y,Z) + \theta(Y)h_{a}^{s}(X,Z)\}E_{a}, \end{split}$$

$$(5.2) R(X,Y)PZ = R^*(X,Y)PZ$$

$$+ \sum_{i=1}^r \{h_i^*(X,PZ)A_{\xi_i}^*Y - h_i^*(Y,PZ)A_{\xi_i}X\}$$

$$+ \sum_{i=1}^r \{(\nabla_X h_i^*)(Y,PZ) - (\nabla_Y h_i^*)(X,PZ)$$

$$+ \sum_{k=1}^r [\tau_{ik}(Y)h_k^*(X,PZ) - \tau_{ik}(X)h_k^*(Y,PZ)]$$

$$- \theta(X)h_i^*(Y,PZ) + \theta(Y)h_i^*(X,PZ)\}\xi_i.$$

Definition. An indefinite complex space form $\bar{M}(c)$ is a connected indefinite Kaehler manifold of constant holomorphic sectional curvature c;

$$(5.3) \ \widetilde{R}(\bar{X}, \bar{Y})\bar{Z} = \frac{c}{4} \{ \bar{g}(\bar{Y}, \bar{Z})\bar{X} - \bar{g}(\bar{X}, \bar{Z})\bar{Y} + \bar{g}(J\bar{Y}, \bar{Z})J\bar{X} - \bar{g}(J\bar{X}, \bar{Z})J\bar{Y} + 2\bar{g}(\bar{X}, J\bar{Y})J\bar{Z} \},$$

where \widetilde{R} is the curvature tensor of the Levi-Civita connection $\widetilde{\nabla}$ on \overline{M} .

By directed calculations from (1.2) and (1.3), we see that

$$(5.4) \ \bar{R}(\bar{X}, \bar{Y})\bar{Z} = \tilde{R}(\bar{X}, \bar{Y})\bar{Z} + \ \bar{g}(\bar{X}, \bar{Z})\bar{\nabla}_{\bar{Y}}\zeta - \ \bar{g}(\bar{Y}, \bar{Z})\bar{\nabla}_{\bar{X}}\zeta + \{(\bar{\nabla}_{\bar{X}}\theta)(\bar{Z}) - \bar{g}(\bar{X}, \bar{Z})\}\bar{Y} - \{(\bar{\nabla}_{\bar{Y}}\theta)(\bar{Z}) - \bar{g}(\bar{Y}, \bar{Z})\}\bar{X}.$$

Taking the scalar product with ξ_i and N_i to (5.4) by turns and then, substituting (5.1) and (5.3) into the resulting equation and using (5.2) and the facts that $g(\zeta, \xi_i) = \bar{g}(\zeta, N_i) = \bar{g}(\zeta, E_a) = 0$ and $\bar{\nabla}$ is metric, we obtain

$$(5.5) \qquad (\nabla_{X}h_{i}^{\ell})(Y,Z) - (\nabla_{Y}h_{i}^{\ell})(X,Z)$$

$$+ \sum_{k=1}^{r} \{\tau_{ki}(X)h_{k}^{\ell}(Y,Z) - \tau_{ki}(Y)h_{k}^{\ell}(X,Z)\}$$

$$+ \sum_{a=r+1}^{n} \{\lambda_{ai}(X)h_{a}^{s}(Y,Z) - \lambda_{ai}(Y)h_{a}^{s}(X,Z)\}$$

$$- \theta(X)h_{i}^{\ell}(Y,Z) + \theta(Y)h_{i}^{\ell}(X,Z)$$

$$- g(X,Z)h_{i}^{\ell}(Y,\zeta) + g(Y,Z)h_{i}^{\ell}(X,\zeta)$$

$$= \frac{c}{4} \{u_{i}(X)\bar{g}(JY,Z) - u_{i}(Y)\bar{g}(JX,Z) + 2u_{i}(Z)\bar{g}(X,JY)\},$$

$$(5.6) \qquad (\nabla_{X}h_{i}^{*})(Y, PZ) - (\nabla_{Y}h_{i}^{*})(X, PZ)$$

$$- \sum_{k=1}^{r} \left\{ \tau_{ik}(X)h_{k}^{*}(Y, PZ) - \tau_{ik}(Y)h_{k}^{*}(X, PZ) \right\}$$

$$- \sum_{k=1}^{r} \left\{ h_{k}^{\ell}(Y, PZ)\eta_{i}(A_{N_{k}}X) - h_{k}^{\ell}(X, PZ)\eta_{i}(A_{N_{k}}Y) \right\}$$

$$- \sum_{a=r+1}^{n} \left\{ h_{a}^{s}(Y, PZ)\eta_{i}(A_{E_{a}}X) - h_{a}^{s}(X, PZ)\eta_{i}(A_{E_{a}}Y) \right\}$$

$$-\theta(X)h_{i}^{*}(Y,PZ) + \theta(Y)h_{i}^{*}(X,PZ) -g(X,PZ)h_{i}^{*}(Y,\zeta) + g(Y,PZ)h_{i}^{*}(X,\zeta) -(\bar{\nabla}_{X}\theta)(PZ)\eta_{i}(Y) + (\bar{\nabla}_{Y}\theta)(PZ)\eta_{i}(X) =(\frac{c}{4}+1)\{g(Y,PZ)\eta_{i}(X) - g(X,PZ)\eta_{i}(Y)\} +\frac{c}{4}\{v_{i}(X)\bar{g}(JY,PZ) - v_{i}(Y)\bar{g}(JX,PZ) + 2v_{i}(PZ)\bar{g}(X,JY)\}.$$

Theorem 5.1. Let M be a Lie recurrent generic lightlike submanifold of an indefinite complex space form $\bar{M}(c)$ with a semi-symmetric metric connection such that ζ belongs to S(TM). Then c=0, i.e., $\bar{M}(c)$ is flat.

Proof. In case M is Lie recurrent. As $\tau_{ij}(FX) = 0$, from (4.14) we get

(5.7)
$$h_i^{\ell}(Y, U_i) = 0.$$

Applying ∇_X to this equation and using (3.8) and (5.7), we have

$$(\nabla_X h_i^{\ell})(Y, U_j) = -h_i^{\ell}(Y, F(A_{N_j} X)) - \sum_{a=r+1}^n \rho_{ja}(X) h_i^{\ell}(Y, W_a) - \theta(U_j) h_i^{\ell}(Y, X) + v_j(X) h_i^{\ell}(Y, \zeta) + \eta_i(X) h_i^{\ell}(Y, F\zeta).$$

Substituting the last two equations into (5.5) such that $Z = U_i$, we have

$$\begin{split} & h_i^{\ell}(X, F(A_{N_j}Y)) - h_i^{\ell}(Y, F(A_{N_j}X)) \\ & - \sum_{a=r+1}^n \{ \rho_{ja}(X) h_i^{\ell}(Y, W_a) - \rho_{ja}(Y) h_i^{\ell}(X, W_a) \} \\ & + \sum_{a=r+1}^n \{ \lambda_{ai}(X) h_a^s(Y, U_j) - \lambda_{ai}(Y) h_a^s(X, U_j) \} \\ & + \eta_j(X) h_i^{\ell}(Y, F\zeta) - \eta_j(Y) h_i^{\ell}(X, F\zeta) \\ & = \frac{c}{4} \{ u_i(Y) \eta_j(X) - u_i(X) \eta_j(Y) + 2 \delta_{ij} \bar{g}(X, JY) \}. \end{split}$$

Taking $X = \xi_j$ and $Y = U_i$ to this and using (4.11)_{3,5} and (5.7), we get

(5.8)
$$h_i^{\ell}(\xi_j, F(A_{N_j}U_i)) + \sum_{a=r+1}^n \rho_{ja}(U_i) h_i^{\ell}(\xi_j, W_a) = \frac{3}{4}c.$$

Replacing X by ξ_j to (2.10) and using (2.14)₂ and the fact that h_i^{ℓ} is symmetric, we get $h_i^{\ell}(X,\xi_j) = g(A_{\xi_i}^*\xi_j,X)$. From this result and

 $(2.13)_1$, we obtain $g(A_{\xi_i}^*\xi_j + A_{\xi_j}^*\xi_i, X) = 0$ for all X. As S(TM) is non-degenerate, we get $A_{\xi_i}^*\xi_j = -A_{\xi_j}^*\xi_i$. Thus $A_{\xi_i}^*\xi_j$ is skew-symmetric with respect to i and j.

On the other hand, taking $Y = U_i$ to (4.15), we have

$$A_{N_i}U_i = A_{N_i}U_j.$$

Applying F to this equation, we have $F(A_{N_j}U_i) = F(A_{N_i}U_j)$. Thus $F(A_{N_i}U_j)$ is symmetric with respect to i and j. Therefore, we obtain

(5.9)
$$h_i^{\ell}(\xi_j, F(A_{N_i}U_i)) = g(A_{\xi_i}^*\xi_j, F(A_{N_i}U_i)) = 0.$$

Also, from $(2.13)_2$, $(3.7)_4$, $(4.11)_4$ and the fact that h_a^s is symmetric, we get

(5.10)
$$h_i^{\ell}(\xi_j, W_a) = \epsilon_a h_a^s(\xi_j, V_i) = \epsilon_a h_a^s(V_i, \xi_j) = -\lambda_{aj}(V_i) = 0.$$
 From (5.8)~ (5.10), we obtain $c = 0$.

Definition 5.2. A lightlike submanifold M is said to be screen conformal [5] if there exist non-vanishing smooth functions φ_i on \mathcal{U} such that

$$(5.11) h_i^*(X, PY) = \varphi_i h_i^{\ell}(X, PY), \forall i.$$

Theorem 5.3. Let M be a screen conformal irrotational generic lightlike submanifold of an indefinite complex space form $\bar{M}(c)$ with a semi-symmetric metric connection such that ζ belongs to S(TM). Then c=0, i.e., $\bar{M}(c)$ is flat.

Proof. Using $(3.7)_{1.3}$ and (5.11), we get

$$h_i^{\ell}(X, U_i - \varphi_i V_i) = -\theta(V_j)\eta_i(X).$$

Replacing X by ξ_j to this equation and using $(2.14)_1$, we have

(5.12)
$$\theta(V_i) = 0, \qquad h_j^{\ell}(X, U_i - \varphi_i V_i) = 0.$$

If M is irrotational, then we have (2.15). Using (3.7)_{2,4} and (5.11), we get

$$h_a^s(X, U_i - \varphi_i V_i) = -\epsilon_a \theta(W_a) \eta_i(X).$$

Replacing X by ξ_i to this equation and using $(2.15)_2$, we obtain

(5.13)
$$\theta(W_a) = 0, \qquad h_a^s(X, U_i - \varphi_i V_i) = 0.$$

Applying $\bar{\nabla}_X$ to $\theta(V_i) = 0$ and using $(2.15)_{1,2}$, (3.9) and $(5.12)_1$, we obtain

$$(5.14) \qquad (\bar{\nabla}_X \theta)(V_i) = h_i^{\ell}(X, F\zeta) + u_i(X).$$

Applying
$$\nabla_X$$
 to $h_i^*(Y, PZ) = \varphi_i h_i^{\ell}(Y, PZ)$, we have
$$(\nabla_X h_i^*)(Y, PZ) = (X\varphi_i) h_i^{\ell}(Y, PZ) + \varphi_i(\nabla_X h_i^{\ell})(Y, PZ).$$

Substituting this equation into (4.6) and using (4.5), we have

$$\begin{split} &(X\varphi_{i})h_{i}^{\ell}(Y,PZ)-(Y\varphi_{i})h_{i}^{\ell}(X,PZ)\\ &-\sum_{j=1}^{r}\{\varphi_{i}\tau_{ji}(X)+\varphi_{j}\tau_{ij}(X)+\eta_{i}(A_{N_{j}}X)\}h_{j}^{\ell}(Y,PZ)\\ &+\sum_{j=1}^{r}\{\varphi_{i}\tau_{ji}(Y)+\varphi_{j}\tau_{ij}(Y)+\eta_{i}(A_{N_{j}}Y)\}h_{j}^{\ell}(X,PZ)\\ &-\sum_{a=r+1}^{n}\epsilon_{a}\{\rho_{ia}(X)h_{a}^{s}(Y,PZ)-\rho_{ia}(Y)h_{a}^{s}(X,PZ)\}\\ &-(\bar{\nabla}_{X}\theta)(PZ)\eta_{i}(Y)+(\bar{\nabla}_{Y}\theta)(PZ)\eta_{i}(X)\\ &=(\frac{c}{4}+1)\{\eta_{i}(X)g(Y,PZ)-\eta_{i}(Y)g(X,PZ)\}\\ &+\frac{c}{4}\{[v_{i}(X)-\varphi_{i}u_{i}(X)]g(FY,PZ)-[v_{i}(Y)-\varphi_{i}u_{i}(Y)]g(FX,PZ)\\ &+2[v_{i}(PZ)-\varphi_{i}u_{i}(PZ)]\bar{g}(X,JY)\}. \end{split}$$

Taking $Y = \xi_i$ and $PZ = V_j$ to this and using (2.15) and (5.14), we have

$$-(\xi_i \varphi_i) h_i^{\ell}(X, V_j) - h_j^{\ell}(X, F\zeta)$$

$$+ \sum_{j=1}^r \{ \varphi_i \tau_{ji}(\xi_i) + \varphi_j \tau_{ij}(\xi_i) + \eta_i(A_{N_j} \xi_i) \} h_j^{\ell}(X, V_j)$$

$$+ \sum_{a=r+1}^n \epsilon_a \rho_{ia}(\xi_i) h_a^s(X, V_j) = -\frac{3}{4} c u_j(X).$$

Taking $X = U_j + \varphi_j V_j$ to this and using $(5.12)_2$ and $(5.13)_2$, we get c = 0

Definition 5.4. [1] We say that S(TM) is totally umbilical in M if there exist smooth functions γ_i on a coordinate neighborhood \mathcal{U} such that

$$(5.15) h_i^*(X, PY) = \gamma_i q(X, PY), \forall i.$$

In case $\gamma_i = 0$ on \mathcal{U} , we say that S(TM) is totally geodesic in M.

Theorem 5.5. Let M be an irrotational generic lightlike submanifold of an indefinite complex space form $\bar{M}(c)$ with a semi-symmetric metric

connection such that ζ belongs to S(TM). If S(TM) is totally umbilical in M, then c=0 and $\gamma_i=0$, i.e., S(TM) is totally geodesic in M.

Proof. If S(TM) is totally umbilical, then, from $(3.7)_1$ and (5.15), we have

$$h_j^{\ell}(X, U_i) = \gamma_i u_j(X) - \theta(V_j) \eta_i(X).$$

Replacing X by ξ_j , V_k , U_k and ζ to this by turns and using $(2.14)_1$, we get

(5.16)
$$\theta(V_i) = 0$$
, $h_j^{\ell}(V_k, U_i) = 0$, $h_j^{\ell}(U_k, U_i) = \gamma_i \delta_{kj}$, $h_j^{\ell}(U_i, \zeta) = 0$,
(5.17) $h_j^{\ell}(X, U_i) = \gamma_i u_j(X)$.

If M is irrotational, then we have (2.15). From $(3.7)_2$ and (5.15), we get

$$h_a^s(X, U_i) = \gamma_i w_a(X) - \theta(W_a) \eta_i(X).$$

Replacing X by ξ_i , V_k , U_k and ζ to this by turns and using $(2.15)_2$, we have

(5.18)
$$\theta(W_a) = 0$$
, $h_a^s(V_k, U_i) = 0$, $h_a^s(U_k, U_i) = 0$, $h_a^s(U_i, \zeta) = 0$.

Applying $\bar{\nabla}_X$ to $\theta(V_i) = 0$ and using (2.10), (2.15), (3.4) and (3.9), we obtain

$$(\bar{\nabla}_X \theta)(V_i) = h_i^{\ell}(X, F\zeta) + u_i(X).$$

Taking $X = F\zeta$ to (5.17), we get $h_j^{\ell}(U_i, F\zeta) = 0$. Replacing X by U_j to the last equation and using the fact that $h_j^{\ell}(U_i, F\zeta) = 0$, we obtain

(5.19)
$$(\bar{\nabla}_{U_j}\theta)(V_i) = \delta_{ij}.$$

Applying ∇_X to $h_i^*(Y, PZ) = \gamma_i g(Y, PZ)$ and using (2.7), we obtain

$$(\nabla_X h_i^*)(Y, PZ) = (X\gamma_i)g(Y, PZ) + \gamma_i \sum_{j=1}^r h_j^{\ell}(X, PZ)\eta_j(Y).$$

Substituting this equation and (5.15) into (5.6), we have

$$\begin{split} &\{X\gamma_{i} - \sum_{j=1}^{r} \gamma_{j}\tau_{ij}(X) - [\frac{c}{4} + 1]\eta_{i}(X)\}g(Y, PZ) \\ &- \{Y\gamma_{i} - \sum_{j=1}^{r} \gamma_{j}\tau_{ij}(Y) - [\frac{c}{4} + 1]\eta_{i}(Y)\}g(X, PZ) \\ &+ \sum_{j=1}^{r} \{\gamma_{i}\eta_{j}(Y) + \eta_{i}(A_{N_{j}}Y)\}h_{j}^{\ell}(X, PZ) \\ &- \sum_{j=1}^{r} \{\gamma_{i}\eta_{j}(X) + \eta_{i}(A_{N_{j}}X)\}h_{j}^{\ell}(Y, PZ) \\ &- \sum_{a=r+1}^{n} \{h_{a}^{s}(Y, PZ)\eta_{i}(A_{E_{a}}X) - h_{a}^{s}(X, PZ)\eta_{i}(A_{E_{a}}Y)\} \\ &- (\bar{\nabla}_{X}\theta)(PZ)\eta_{i}(Y) + (\bar{\nabla}_{Y}\theta)(PZ)\eta_{i}(X) \\ &= \frac{c}{4} \{v_{i}(X)g(FY, PZ) - v_{i}(Y)g(FX, PZ) + 2v_{i}(PZ)\bar{g}(X, JY)\}. \end{split}$$

Replacing Y by ξ_k to this and using (2.15), (3.2) and (3.3), we have

$$(5.20) \qquad \{\xi_{k}\gamma_{i} - \sum_{j=1}^{r} \gamma_{j}\tau_{ij}(\xi_{k}) - \left[\frac{c}{4} + 1\right]\delta_{ik}\}g(X, PZ)$$

$$- \sum_{j=1}^{r} \{\gamma_{i}\delta_{jk} + \eta_{i}(A_{N_{j}}\xi_{k})\}h_{j}^{\ell}(X, PZ)$$

$$- \sum_{a=r+1}^{n} \eta_{i}(A_{E_{a}}\xi_{k})h_{a}^{s}(X, PZ)$$

$$+ (\bar{\nabla}_{X}\theta)(PZ)\delta_{ik} - (\bar{\nabla}_{\xi_{k}}\theta)(PZ)\eta_{i}(X)$$

$$= \frac{c}{4}\{v_{i}(X)u_{k}(PZ) + 2v_{i}(PZ)u_{k}(X)\}.$$

Taking $X = U_h$ and $PZ = V_h$ and using $(5.16)_2$, $(5.18)_2$ and (5.19), we have

(5.21)
$$\xi_k \gamma_i - \sum_{j=1}^r \gamma_j \tau_{ij}(\xi_k) = \frac{3}{4} c \,\delta_{ik}.$$

Applying $\bar{\nabla}_X$ to $g(\zeta,\zeta)=1$ and using the fact that $\bar{\nabla}$ is metric, we obtain

$$(5.22) \qquad (\bar{\nabla}_X \theta)(\zeta) = 0.$$

Taking $X = U_k$ and $Z = \zeta$ to (5.20) and using (5.16)₄, (5.21) and (5.22), we get $\theta(U_i) = 0$. As $\bar{g}(J\zeta, \zeta) = 0$, we see that $g(F\zeta, \zeta) = 0$. Thus

(5.23)
$$\theta(U_i) = 0, \qquad g(F\zeta, \zeta) = 0.$$

As $\theta(V_i) = \theta(U_i) = \theta(W_a) = 0$, we get $J\zeta = F\zeta \in \Gamma(S(TM))$. Applying $\bar{\nabla}_X$ to $\theta(U_i) = 0$ and using (3.8), (5.18)₁ and (5.23), we obtain

$$(\bar{\nabla}_X \theta)(U_i) = \gamma_i g(X, F\zeta) + v_i(X).$$

Taking $X = V_i$ and $X = U_i$ to this equation by turns, we obtain

$$(5.24) \qquad (\bar{\nabla}_{V_i}\theta)(U_i) = \delta_{ij}, \qquad (\bar{\nabla}_{U_i}\theta)(U_i) = 0.$$

Taking $X = V_h$ and $PZ = U_h$ to (5.20) and using (5.16)₂, (5.18)₂, (5.21) and (5.24)₁, we have c = 0. Thus $\bar{M}(c)$ is flat.

As $\eta_i(A_{N_j}\xi_k)$ is skew-symmetric with respect to i and j by $(2.13)_3$ and $h_j^{\ell}(U_i, U_k)$ is symmetric with respect to i and j by $(5.16)_3$, we see that

(5.25)
$$\eta_i(A_{N_i}\xi_k)h_j^{\ell}(U_i, U_k) = 0.$$

As c = 0, Eq. (5.20) reduces

$$\sum_{j=1}^{r} \{ \gamma_{i} \delta_{jk} + \eta_{i}(A_{N_{j}} \xi_{k}) \} h_{j}^{\ell}(X, PZ) + \sum_{a=r+1}^{n} \eta_{i}(A_{E_{a}} \xi_{k}) h_{a}^{s}(X, PZ)$$

$$= \{ (\bar{\nabla}_{X} \theta)(PZ) - g(X, PZ) \} \delta_{ik} - (\bar{\nabla}_{\xi_{k}} \theta)(PZ) \eta_{i}(X).$$

Taking $X = U_i$ and $Z = U_k$ to this and using $(5.16)_3$, $(5.18)_3$, $(5.24)_2$ and (5.25), we have $\gamma_i = 0$. Thus S(TM) is totally geodesic in M.

Theorem 5.6. Let M be a generic lightlike submanifold of an indefinite Kaehler manifold $\overline{M}(c)$ with a semi-symmetric metric connection such that ζ belongs to S(TM) and U_is are parallel with respect to the connection ∇ . If either $\rho_{ia} = 0$ or $\tau_{ij} = 0$, then c = 0, i.e., $\overline{M}(c)$ is flat.

Proof. (1) In case $\rho_{ia} = 0$. Taking the scalar product with W_a to (3.8), we get $\epsilon_a \theta(U_i) w_a(X) - \theta(W_a) v_i(X) = 0$. Taking $X = W_a$ and $X = V_i$ to this result by turns, we have

(5.26)
$$\theta(U_i) = 0, \qquad \theta(W_a) = 0.$$

Taking the scalar product with U_j , N_j , ζ and $F\zeta$ to (3.8) by turns and using (3.6), (5.26) and the fact that $g(F\zeta,\zeta) = 0$, we obtain

(5.27)
$$\bar{g}(A_{N_i}X, N_j) = 0, h_i^*(X, U_j) = 0, g(F(A_{N_i}X), \zeta) = v_i(X), h_i^*(X, \zeta) = \eta_i(X).$$

Applying $\bar{\nabla}_X$ to $\theta(U_i) = 0$ and using (3.8) and (5.27)₃, we have

$$(5.28) \qquad (\bar{\nabla}_X \theta)(U_i) = 0.$$

Applying ∇_Y to $(5.27)_2$ and using the fact that $\nabla_Y U_j = 0$, we have

$$(\nabla_X h_i^*)(Y, U_i) = 0.$$

Substituting this equation and $(5.27)_2$ into (5.6) such that $PZ = U_j$ and using $(2.13)_4$, $(5.27)_{1,2,4}$, (5.28) and the fact that $\rho_{ia} = 0$, we have

$$\frac{c}{4}\{v_j(Y)\eta_i(X) - v_j(X)\eta_i(Y) + v_i(Y)\eta_j(X) - v_i(X)\eta_j(Y)\} = 0.$$

Taking $X = \xi_i$ and $Y = V_j$ to this equation, we obtain c = 0.

(2) In case $\tau_{ij} = 0$. Taking the scalar product with V_j to (3.8), we get $\theta(U_i)u_j(X) - \theta(V_j)v_i(X) = 0$. Taking $X = U_j$ and $X = V_j$ to this equation by turns, we have

$$(5.29) \theta(U_i) = 0, \theta(V_i) = 0.$$

Taking the scalar product with U_j , N_j , $F\zeta$ and ζ to (3.8) by turns and using (3.6), (5.29) and the fact that $g(F\zeta,\zeta) = 0$, we obtain

(5.30)
$$\bar{g}(A_{N_i}X, N_j) = 0, \quad h_i^*(X, U_j) = 0, \quad h_i^*(X, \zeta) = \eta_i(X),$$

 $g(F(A_{N_i}X), \zeta) + \sum_{a=r+1}^n \theta(W_a)\rho_{ia}(X) = v_i(X).$

Applying $\bar{\nabla}_X$ to $\theta(U_i) = 0$ and using (3.8) and (5.30)₄, we have

$$(5.31) \qquad (\bar{\nabla}_X \theta)(U_i) = 0.$$

Applying ∇_Y to $(5.30)_2$ and using the fact that $\nabla_Y U_i = 0$, we have

$$(\nabla_X h_i^*)(Y, U_j) = 0.$$

Substituting this equation and $(5.30)_2$ into (5.6) with $PZ = U_j$ and using $(5.30)_{1,3}$ and (5.31), we have

$$\frac{c}{4}\{v_j(Y)\eta_i(X) - v_j(X)\eta_i(Y) + v_i(Y)\eta_j(X) - v_i(X)\eta_j(Y)\} = 0.$$

Taking $X = \xi_i$ and $Y = V_i$ to this equation, we obtain c = 0.

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