# POSITIVE SOLUTION AND GROUND STATE SOLUTION FOR A KIRCHHOFF TYPE EQUATION WITH CRITICAL GROWTH 

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Abstract. In this paper, we consider the following Kirchhoff type equation on the whole space

$$
\left\{\begin{array}{l}
-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u=u^{5}+\lambda k(x) g(u), x \in \mathbb{R}^{3} \\
u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)
\end{array}\right.
$$

where $\lambda>0$ is a real number and $k, g$ satisfy some conditions. We mainly investigate the existence of ground state solution via variational method and concentration-compactness principle.

## 1. Introduction

In this paper, we are concerned with the following Kirchhoff type problem

$$
\left\{\begin{array}{l}
-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u=u^{5}+\lambda k(x) g(u), x \in \mathbb{R}^{3},  \tag{1.1}\\
u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)
\end{array}\right.
$$

where the nonlinear growth $u^{5}$ reaches the Sobolev critical exponent since the critical exponent $2^{*}=6$ in three spatial dimensions. In recent years, because of the strong physical meaning in mechanics models, the following Kirchhoff type problem involving the critical Sobolev exponent has attracted a lot of attention,

$$
\begin{cases}-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u=f(x, u), & \text { in } \Omega  \tag{1.2}\\ u=0, & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a smooth domain in $\mathbb{R}^{3}$. Therefore many results have been obtained, including the existence of positive solutions, multiple solutions, sign-changing

[^0]solutions and so on, see for example $[2,5,7,8,16]$ and the reference therein on bounded domain, $[3,9,11,19]$ and the reference therein on unbounded domains.

The existence of positive ground state solution for Kirchhoff equation has also been widely investigated in recent years. Wang et al. in [19] showed the existence of positive ground state solutions by using the variational method, where the subcritical nonlinear function $f(u)$ satisfies some stronger conditions. By a monotonicity trick and a new version of global compactness lemma, Li and Ye in [10] considered the following Kirchhoff type problem with pure power nonlinearities

$$
\left\{\begin{array}{l}
-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u+V(x) u=|u|^{p-1}, x \in \mathbb{R}^{3} \\
u \in \mathrm{H}^{1}\left(\mathbb{R}^{3}\right), u>0
\end{array}\right.
$$

and gave the existence of positive ground state solution for $2<p<5$. In [4], Hu and Lu obtained the multiplicity of positive solutions for the following Kirchhoff type problem with pure power nonlinearities

$$
\left\{\begin{array}{l}
-\left(\varepsilon^{2} a+\epsilon b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u+u=Q(x)|u|^{p-2} u, x \in \mathbb{R}^{3} \\
u \in \mathrm{H}^{1}\left(\mathbb{R}^{3}\right), u>0
\end{array}\right.
$$

with $p \in(2,6)$. Recently, Lei et al. in [9] studied the following Kirchhoff type problem involving critical growth

$$
\left\{\begin{array}{l}
-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \triangle u=u^{5}+\lambda k(x) u^{q-1}, x \in \mathbb{R}^{3}, \\
u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)
\end{array}\right.
$$

with $2<q<6$.
In the present paper, we are concerned with a more general nonlinearity $\lambda k(x) g(u)$, where $g(u)$ is a nonlinear function with superquadratic growth both at zero and at infinity. Besides, we use a new cut-off technique together with critical point theorems to investigate the ground state solutions of (1.1). Nowadays, it has become a classical variational method due to its useful features. It is highlighted in the recent contribution $[1,8,15]$ and so on.

Before stating our results, we assume that $k(x)$ satisfies the following conditions.
$\left(k_{1}\right) k(x) \in L^{\frac{6}{6-q}}\left(\mathbb{R}^{3}\right) \bigcap L^{\frac{6}{6-p}}\left(\mathbb{R}^{3}\right), k(x) \geq 0$ for any $x \in \mathbb{R}^{3}, 4<p, q<6$ and $k(x) \not \equiv 0$;
$\left(k_{2}\right)$ There exist $x_{0} \in \mathbb{R}^{3}$ and $\delta_{1}, \rho_{1}>0$ such that $k(x) \geq \delta_{1}\left|x-x_{0}\right|^{-\beta}$ for $\left|x-x_{0}\right|<\rho_{1}$ with $3-\frac{p}{2}<\beta<3$.
Moreover, we assume the nonlinearity $g(u) \in C(\mathbb{R}, \mathbb{R})$ satisfies the following hypotheses.
$\left(G_{1}\right)$ There is a $q \in \mathbb{R}$ with $4<q<6$ such that $\lim _{|u| \rightarrow 0} \frac{g(u)}{|u|^{q-2} u}=1$;
$\left(G_{2}\right)$ There is a $p \in \mathbb{R}$ with $4<p<6$ such that $\lim _{|u| \rightarrow \infty} \frac{g(u)}{|u|^{p-2} u}=1$;
$\left(G_{3}\right) g(u)>0$ for all $u>0$.
Since our aim is to find the positive solutions, it is only necessary to consider $u>0$ for the equation (1.1). Then throughout the paper we assume, without loss of generality, that $g(u)$ is defined in $\mathbb{R}$ as an odd function.

Now the main result of the present paper reads as follows.
Theorem 1.1. Assume $\left(k_{1}\right)-\left(k_{2}\right)$ and $\left(G_{1}\right)-\left(G_{3}\right)$ hold. Then there exists $\lambda_{*}>0$ such that problem (1.1) has at least one positive ground state solution for any $0<\lambda<\lambda_{*}$.

Remark 1.2. From the hypotheses $\left(G_{1}\right)-\left(G_{3}\right)$, we know the nonlinear term $g(u)$ is more general than the specific power-type nonlinearity $u^{q-1}$ for $q \in(4,6)$. Furthermore, under some suitable assumptions, we can still prove the existence of positive state ground solution. Therefore, we generalize some corresponding results in the relative references.

Hereafter we use the following notations.

- $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ is the usual Sobolev space endowed with the standard norm $\|u\|^{2}=$ $\int_{\mathbb{R}^{3}}|\nabla u|^{2} d x ;$
- $L^{p}\left(\mathbb{R}^{3}\right)$ and $L^{q}\left(\mathbb{R}^{3}\right)(1 \leq q, p \leq \infty)$ denote Lebesgue spaces, the norm in $L^{p}\left(\mathbb{R}^{3}\right)$ and $L^{q}\left(\mathbb{R}^{3}\right)$ are denoted by $|\cdot|_{p}$ and $|\cdot|_{q}$, respectively;
- $C, C_{0}, \hat{C}, C_{1}, \hat{C_{1}}, C_{2}, \ldots$ denote various positive constants, which may vary from lines to lines;
- $S_{r}$ (respectively, $B_{r}$ ) is the sphere (respectively, the closed ball) of center zero and radius $r$, i.e., $S_{r}=\left\{u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right):\|u\|=r\right\}, B_{r}=\left\{u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)\right.$ : $\|u\| \leq r\}$;
- $S$ is the best Sobolev constant for the embedding of $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ in $L^{6}\left(\mathbb{R}^{3}\right)$, that is

$$
\begin{equation*}
S=\inf _{u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right) \backslash\{0\}} \frac{\int_{\mathbb{R}^{3}}|\nabla u|^{2} d x}{\left(\int_{\mathbb{R}^{3}}|u|^{6} d x\right)^{\frac{1}{3}}} ; \tag{1.3}
\end{equation*}
$$

- $\rightarrow(\rightharpoonup)$ means strong (weak) convergence.

This paper is organized as follows. After introducing some preliminary results in Section 2, we shall demonstrate the proof of Theorem 1.1 in Section 3.

## 2. Some preliminaries

The solution of (1.1) corresponds to critical points of the following energy functional

$$
I_{\lambda}(u)=\frac{a}{2}\|u\|^{2}+\frac{b}{4}\|u\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}|u|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G(u) d x
$$

with $G(u)=\int_{0}^{u} g(t) d t$. The hypotheses $\left(G_{1}\right)-\left(G_{2}\right)$ imply that

$$
\begin{equation*}
|g(t)| \leq b_{1}|t|^{q-1}+b_{2}|t|^{p-1}, \quad|G(t)| \leq b_{1}|t|^{q}+b_{2}|t|^{p} \quad \text { for all } t \in \mathbb{R}, \tag{2.1}
\end{equation*}
$$

and

$$
\left.\begin{array}{ll}
b_{3}|t|^{q} \leq G(t), & b_{3}|t|^{q} \leq g(t) t, \\
b_{4}|t|^{p} \leq G(t), & \text { if }|t| \leq \delta_{0}  \tag{2.2}\\
b_{4}
\end{array}\right|^{p} \leq g(t) t, \quad \text { if }|t| \geq \delta_{0},
$$

for some $b_{1}, b_{2}, b_{3}, b_{4}, \delta_{0}>0$ (see e.g. [8]).
It follows from $\left(G_{2}\right)$ that there exist $r \geq 4$ and $M>0$ such that

$$
\begin{equation*}
|u| \geq M \Longrightarrow 0<r G(u) \leq u g(u) \tag{2.3}
\end{equation*}
$$

Lemma 2.1 ([6]). Under the assumption $\left(k_{1}\right)$, the function $\mathcal{K}: \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right) \rightarrow \mathbb{R}$ given by

$$
\mathcal{K}(u)=\int_{\mathbb{R}^{3}} k(x) g(u) u d x
$$

is weakly continuous.
Lemma 2.2. Suppose that $\left(k_{1}\right)-\left(k_{2}\right)$ hold. Then
(i) There are two constants $\alpha, \rho>0$ such that $\left.I_{\lambda}\right|_{S_{\rho}} \geq \alpha$;
(ii) There exists $u_{0} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ with $\left\|u_{0}\right\|>\rho$ satisfying $I_{\lambda}\left(u_{0}\right)<0$.

Proof. (i) For any $u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right) \backslash\{0\}, 4<q, p<6$, it follows from (1.3) that

$$
\begin{aligned}
I_{\lambda}(u)= & \frac{a}{2}\|u\|^{2}+\frac{b}{4}\|u\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}|u|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G(u) d x \\
\geq & \frac{a}{2}\|u\|^{2}+\frac{b}{4}\|u\|^{4}-\frac{1}{6 S^{3}}\|u\|^{6}-\lambda \int_{\mathbb{R}^{3}} k(x)\left(b_{1}|u|^{q}+b_{2}|u|^{p}\right) d x \\
\geq & \frac{a}{2}\|u\|^{2}+\frac{b}{4}\|u\|^{4}-\frac{1}{6 S^{3}}\|u\|^{6} \\
& -\lambda b_{1}|k(x)|_{\frac{6}{6-q}} S^{-\frac{q}{2}}\|u\|^{q}-\lambda b_{2}|k(x)|_{\frac{6}{6-p}} S^{-\frac{p}{2}}\|u\|^{p} .
\end{aligned}
$$

Let $\rho=\|u\|$ be sufficiently small such that

$$
\frac{a}{2} \rho^{2}+\frac{b}{4} \rho^{4}-\frac{1}{6 S^{3}} \rho^{6}-\lambda b_{1}|k(x)|_{\frac{6}{6-q}} S^{-\frac{q}{2}} \rho^{q}-\lambda b_{2}|k(x)|_{\frac{6}{6-p}} S^{-\frac{p}{2}} \rho^{p}>\frac{a}{4} \rho^{2}
$$

Therefore we get

$$
\left.I_{\lambda}\right|_{S_{\rho}} \geq \frac{a}{4} \rho^{2}=\alpha
$$

(ii) $\left(k_{1}\right)$ and $\left(k_{2}\right)$ imply that

$$
I_{\lambda}(t u)=\frac{a}{2} t^{2}\|u\|^{2}+\frac{b}{4} t^{4}\|u\|^{4}-\frac{t^{6}}{6} \int_{\mathbb{R}^{3}}|u|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G(t u) d x \rightarrow-\infty
$$

as $t \rightarrow+\infty$.
Therefore there exists $u_{0} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ with $\left\|u_{0}\right\|>\rho$ such that $I_{\lambda}\left(u_{0}\right)<0$. Then (ii) follows and the proof of Lemma 2.2 is complete.

Denote $\mathcal{M}^{+}$as a space of positive finite Radon measures on $\mathbb{R}^{3}$, and $\delta_{x}$ as the Dirac mass at point $x$.

Lemma 2.3 ( $[12,13])$. Let $\left\{u_{n}\right\} \subset \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ be a bounded sequence, due to Hardy-Sobolev inequality, passing to a subsequence if necessary, we may assume that $u_{n} \rightharpoonup u$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right),\left|\nabla u_{n}\right|^{2} \rightharpoonup \mu$ in $\mathcal{M}^{+},\left|u_{n}\right|^{6} \rightharpoonup \nu$ in $\mathcal{M}^{+}$. Define

$$
\begin{aligned}
\mu_{\infty} & :=\lim _{R \rightarrow \infty} \varlimsup_{n \rightarrow \infty} \int_{\mathbb{R}^{3} \cap|x|>R}\left|\nabla u_{n}\right|^{2} d x \\
\nu_{\infty} & :=\lim _{R \rightarrow \infty} \varlimsup_{n \rightarrow \infty} \int_{\mathbb{R}^{3} \cap|x|>R}\left|u_{n}\right|^{6} d x
\end{aligned}
$$

Then for every $j$ in an at most countable set $J$, there hold
(1) $\mu_{\infty} \geq S \nu_{\infty}^{\frac{1}{3}}$;
(2) $\nu=|u|^{6}+\nu_{0} \delta_{0}+\sum \delta_{x_{j}} \nu_{j}>0, \mu \geq\|\nabla u\|^{2}+\mu_{0} \delta_{0}+\sum \delta_{x_{j}} \mu_{j}$;
(3) $\mu_{j} \geq S \nu_{j}^{\frac{1}{3}}$;
(4) $\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x=\int_{\mathbb{R}^{3}}|u|^{6} d x+\|\nu\|+\nu_{\infty}$.

Next, we define

$$
\Lambda=\frac{a b S^{3}}{4}+\frac{b^{3} S^{6}}{24}+\frac{\left(b^{2} S^{4}+4 a S\right)^{\frac{3}{2}}}{24}
$$

Lemma 2.4. Suppose $4<p, q<6$. Let $\left\{u_{n}\right\}$ be a $(P S)_{c}$ sequence of $I_{\lambda}$ with $c<\Lambda-C_{0} \lambda$. Then there exists $u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ such that $\left|u_{n}\right|_{6}^{6} \rightarrow|u|_{6}^{6}$ as $n \rightarrow \infty$.
Proof. For $4<p, q<6$, let $\left\{u_{n}\right\} \subset \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ be a $(P S)_{c}$ sequence for $I_{\lambda}$ at level $c<\Lambda-C_{0} \lambda$, i.e.,

$$
\begin{equation*}
I_{\lambda}\left(u_{n}\right) \rightarrow c, \quad I_{\lambda}^{\prime}\left(u_{n}\right) \rightarrow 0 \quad \text { as } n \rightarrow \infty \tag{2.4}
\end{equation*}
$$

We firstly claim that $\left\{u_{n}\right\}$ is bounded in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. It follows from (2.1) and Hölder inequality that there exists $C_{0}$ such that

$$
\int_{\left\{x:\left|u_{n}\right| \leq M\right\}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x>-C_{0} .
$$

For $n$ large enough, from (2.1) and (2.3), we conclude that

$$
\begin{aligned}
& 1+o\left(\left\|u_{n}\right\|\right)+c \\
\geq & I_{\lambda}\left(u_{n}\right)-\frac{1}{4}\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), u_{n}\right\rangle \\
= & \frac{a}{2}\left\|u_{n}\right\|^{2}+\frac{b}{4}\left\|u_{n}\right\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(u_{n}\right) d x \\
& -\frac{1}{4}\left\{a\left\|u_{n}\right\|^{2}+b\left\|u_{n}\right\|^{4}-\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) u_{n} d x\right\} \\
= & \frac{a}{4}\left\|u_{n}\right\|^{2}+\frac{1}{12} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x+\lambda \int_{\mathbb{R}^{3}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x \\
= & \frac{a}{4}\left\|u_{n}\right\|^{2}+\frac{1}{12} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x+\lambda \int_{\left\{x:\left|u_{n}\right| \leq M\right\}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x
\end{aligned}
$$

$$
\begin{aligned}
& +\lambda \int_{\left\{x:\left|u_{n}\right| \geq M\right\}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x \\
\geq & \frac{a}{4}\left\|u_{n}\right\|^{2}+\frac{1}{12} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x+\lambda \int_{\left\{x:\left|u_{n}\right| \leq M\right\}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x \\
\geq & \frac{a}{4}\left\|u_{n}\right\|^{2}+\frac{1}{12} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x-C_{0} \lambda .
\end{aligned}
$$

Thus $\left\{u_{n}\right\}$ is bounded in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. Since $g(u)$ is odd, we get $G(u)$ is even and $I_{\lambda}\left(u_{n}\right)=I_{\lambda}\left(\left|u_{n}\right|\right)$. Here, we suppose straight away that $u_{n}(x) \geq 0$ a.e. in $\mathbb{R}^{3}$ for all $n$. Then there exist $u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ and a subsequence (still denoted $\left\{u_{n}\right\}$ ) satisfying

$$
\left\{\begin{array}{l}
u_{n} \rightharpoonup u, \text { in } \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right), \\
u_{n}(x) \rightarrow u(x), \quad \text { a.e. in } \mathbb{R}^{3}, \\
\left|\nabla u_{n}\right| \rightharpoonup \mu, \quad \text { in } \mathcal{M}^{+}, \\
\left|u_{n}\right|^{6} \rightharpoonup \nu, \text { in } \mathcal{M}^{+} .
\end{array}\right.
$$

Therefore $u(x) \geq 0$ a.e. in $\mathbb{R}^{3}$.
Let $x_{j}$ be a singular point of the measure $\mu$ and $\nu$. For any $\epsilon>0$ small enough, we define a cut-off function $\phi_{\epsilon, j} \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{3},[0,1]\right)$ such that

$$
\left\{\begin{array}{l}
\phi_{\epsilon, j}(x)=1, \quad \text { in } B\left(x_{j}, \epsilon\right), \\
\phi_{\epsilon, j}(x)=0, \quad \text { in } \mathbb{R}^{3} \backslash B\left(x_{j}, 2 \epsilon\right), \\
\left|\nabla \phi_{\epsilon, j}(x)\right| \leq \frac{4}{\epsilon}, \quad \text { in } \mathbb{R}^{3} .
\end{array}\right.
$$

It is easy to show that $\left\{\phi_{\epsilon, j} u_{n}\right\}$ is bounded in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. Then by (2.4) we get that

$$
\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), \phi_{\epsilon, j} u_{n}\right\rangle \rightarrow 0,
$$

which implies

$$
\begin{aligned}
\left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla\left(\phi_{\epsilon, j} u_{n}\right)\right) d x & -\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} \phi_{\epsilon, j} d x \\
& -\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) \phi_{\epsilon, j} u_{n} d x \rightarrow 0 .
\end{aligned}
$$

Therefore

$$
\begin{align*}
& \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} \phi_{\epsilon, j} d x+\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) \phi_{\epsilon, j} u_{n} d x \\
= & \left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla \phi_{\epsilon, j}\right) u_{n} d x  \tag{2.5}\\
& +\left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left|\nabla u_{n}\right|^{2} \phi_{\epsilon, j} d x+o(1) .
\end{align*}
$$

Next we claim that

$$
\lim _{\epsilon \rightarrow 0} \lim _{n \rightarrow \infty}\left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla \phi_{\epsilon, j}\right) u_{n} d x=0 .
$$

Actually, since $\left\{u_{n}\right\}$ is bounded, for any $\epsilon>0$, combining Hölder inequality with the definition of $\phi_{\epsilon, j}$, we have

$$
\begin{aligned}
\left|\limsup _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla \phi_{\epsilon, j}\right) u_{n} d x\right| & \leq \limsup _{n \rightarrow \infty}\left|\int_{B\left(x_{j}, 2 \epsilon\right)}\left(\nabla u_{n}, \nabla \phi_{\epsilon, j}\right) u_{n} d x\right| \\
& \leq \limsup _{n \rightarrow \infty} \frac{4}{\epsilon} \int_{B\left(x_{j}, 2 \epsilon\right)}\left|\nabla u_{n}\right| \cdot\left|u_{n}\right| \cdot 1 d x \\
& \leq \frac{4}{\epsilon} C_{1}\left(\int_{B\left(x_{j}, 2 \epsilon\right)}|u|^{6} d x\right)^{\frac{1}{6}}\left(\int_{B\left(x_{j}, 2 \epsilon\right)} 1^{3} d x\right)^{\frac{1}{3}} \\
& \leq 4 C_{2}\left(\int_{B\left(x_{j}, 2 \epsilon\right)}|u|^{6} d x\right)^{\frac{1}{6}}
\end{aligned}
$$

with $C_{1}, C_{2}>0$, which implies that

$$
\lim _{\epsilon \rightarrow 0} \lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla \phi_{\epsilon, j}\right) u_{n} d x=0 .
$$

Now by Lemma 2.3(2)-(3), we know that

$$
\lim _{\epsilon \rightarrow 0} \lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} u_{n}^{6} \phi_{\epsilon, j}(x) d x=\lim _{\epsilon \rightarrow 0} \int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x) d \nu=\nu_{j}
$$

and

$$
\begin{aligned}
\limsup _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}|\nabla u|^{2} \phi_{\epsilon, j}(x) d x & =\int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x) d \mu \\
& \geq \int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x)|\nabla u|^{2} d x+\sum \delta_{j} \phi_{\epsilon, j}(x) \mu_{j} \geq \mu_{j} .
\end{aligned}
$$

Thus

$$
\begin{aligned}
& \limsup _{n \rightarrow \infty}\left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left|\nabla u_{n}\right|^{2} \phi_{\epsilon, j}(x) d x \\
\geq & \limsup _{n \rightarrow \infty}\left(a+b \int_{\mathbb{R}^{3}}\left|\nabla u_{n}\right|^{2} \phi_{\epsilon, j}(x) d x\right) \int_{\mathbb{R}^{3}}\left|\nabla u_{n}\right|^{2} \phi_{\epsilon, j}(x) d x \geq\left(a+b \mu_{j}\right) \mu_{j} .
\end{aligned}
$$

By (2.1), one has

$$
\begin{aligned}
& \left|\lim _{\epsilon \rightarrow 0} \limsup _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x) k(x) g\left(u_{n}\right) u_{n} d x\right| \\
= & \left|\lim _{\epsilon \rightarrow 0} \int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x) k(x) g(u) u d x\right| \\
\leq & \left|\lim _{\epsilon \rightarrow 0} \int_{\mathbb{R}^{3}} \phi_{\epsilon, j}(x) k(x)\left(b_{1}|u|^{q-1} u+b_{2}|u|^{p-1} u\right) d x\right|
\end{aligned}
$$

$$
\begin{aligned}
\leq & \lim _{\epsilon \rightarrow 0} \int_{B\left(x_{j}, 2 \epsilon\right)} k(x) b_{1}|u|^{q} d x+\lim _{\epsilon \rightarrow 0} \int_{B\left(x_{j}, 2 \epsilon\right)} k(x) b_{2}|u|^{p} d x \\
\leq & b_{1}|k(x)|_{\frac{6}{6-q}} S^{-\frac{q}{2}} \lim _{\epsilon \rightarrow 0}\left(\int_{B\left(x_{j}, 2 \epsilon\right)}|\nabla u|^{2} d x\right)^{\frac{q}{2}} \\
& +b_{2}|k(x)|_{\frac{6}{6-p}} S^{-\frac{p}{2}} \lim _{\epsilon \rightarrow 0}\left(\int_{B\left(x_{j}, 2 \epsilon\right)}|\nabla u|^{2} d x\right)^{\frac{p}{2}} \\
= & 0 .
\end{aligned}
$$

Then by (2.5), we have

$$
\nu_{j} \geq a \mu_{j}+b \mu_{j}^{2}
$$

Combining this with Lemma 2.3(3), a direct computation shows that either
(i) $\mu_{j}=0 \quad$ or
(ii) $\mu_{j} \geq \frac{b S^{3}+\sqrt{b^{2} S^{6}+4 a S^{3}}}{2}:=A$.

Now, we define another cut-off function $\phi_{R} \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{3},[0,1]\right)$ such that

$$
\begin{cases}\phi_{R}(x)=0, & \text { on }|x|<R, \\ \phi_{R}(x)=1, & \text { on }|x|>2 R, \\ \left|\nabla \phi_{R}(x)\right| \leq \frac{4}{R}, & \text { in } \mathbb{R}^{3} .\end{cases}
$$

By the same argument as above, we can obtain

$$
\nu_{\infty} \geq a \mu_{\infty}+b \mu_{\infty}^{2}
$$

Then by Lemma 2.3(1), one has that

$$
\text { (iii) } \mu_{\infty}=0 \quad \text { or } \quad \text { (iv) } \mu_{\infty} \geq \frac{b S^{3}+\sqrt{b^{2} S^{6}+4 a S^{3}}}{2}=A \text {. }
$$

Next we claim that (ii) and (iv) cannot hold. Otherwise, we suppose that there exists $j \in J$ such that (iv) holds. By the weak lower semicontinuity of the norm, (2.3) and (2.4), we conclude that

$$
\begin{align*}
c= & \lim _{n \rightarrow \infty}\left\{I_{\lambda}\left(u_{n}\right)-\frac{1}{4}\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), u_{n}\right\rangle\right\} \\
= & \lim _{n \rightarrow \infty}\left\{\frac{a}{2}\left\|u_{n}\right\|^{2}+\frac{b}{4}\left\|u_{n}\right\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(u_{n}\right) d x\right. \\
& \left.-\frac{1}{4}\left(a\left\|u_{n}\right\|^{2}+b\left\|u_{n}\right\|^{4}-\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) u_{n} d x\right)\right\} \\
= & \lim _{n \rightarrow \infty}\left\{\left(\frac{1}{2}-\frac{1}{4}\right) a\left\|u_{n}\right\|^{2}+\left(\frac{1}{4}-\frac{1}{4}\right) b\left\|u_{n}\right\|^{4}+\frac{1}{12} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x\right.  \tag{2.6}\\
& \left.+\lambda \int_{\mathbb{R}^{3}} k(x)\left(\frac{1}{4} g\left(u_{n}\right) u_{n}-G\left(u_{n}\right)\right) d x\right\}
\end{align*}
$$

$$
\begin{aligned}
& \geq\left(\frac{1}{2}-\frac{1}{4}\right) a \mu_{\infty}+\left(\frac{1}{4}-\frac{1}{4}\right) b \mu_{\infty}^{2}+\frac{1}{12} \nu_{\infty}+\frac{1}{12} \int_{\mathbb{R}^{3}}|u|^{6} d x-C_{0} \lambda \\
& \geq\left(\frac{1}{2}-\frac{1}{4}\right) a A+\left(\frac{1}{4}-\frac{1}{4}\right) b A^{2}+\frac{a A+b A^{2}}{12}-C_{0} \lambda .
\end{aligned}
$$

Here we show that

$$
\frac{a A}{2}+\frac{b}{4} A^{2}-\frac{a A+b A^{2}}{6}=\Lambda
$$

Indeed,

$$
\begin{aligned}
& \frac{a A}{2}+\frac{b}{4} A^{2}-\frac{a A+b A^{2}}{6}=\frac{a A}{3}+\frac{b}{12} A^{2} \\
= & \frac{a b S^{3}+a \sqrt{b^{2} S^{6}+4 a S^{3}}}{6}+\frac{b^{3} S^{6}+2 a b S^{3}+b^{2} S^{3} \sqrt{b^{2} S^{6}+4 a S^{3}}}{24} \\
= & \frac{a b S^{3}}{4}+\frac{b^{3} S^{6}}{24}+\frac{\left(4 a+b^{2} S^{3}\right) \sqrt{b^{2} S^{6}+4 a S^{3}}}{24} \\
= & \Lambda .
\end{aligned}
$$

Consequently $\Lambda-C_{0} \lambda \leq c<\Lambda-C_{0} \lambda$, we deduce the contradiction.
Similarly (ii) cannot hold for any $j$. This implies that $J$ is empty.
Up to now, we have proved that

$$
\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{6} d x=\int_{\mathbb{R}^{3}}|u|^{6} d x
$$

This completes the proof.
Moreover, it is well known that $S$ is attained by the function

$$
U_{\epsilon, x_{0}}(x)=C \frac{\epsilon^{\frac{1}{4}}}{\left(\epsilon+\left|x-x_{0}\right|^{2}\right)^{\frac{1}{2}}}
$$

where $C$ is a normalizing constant and $x_{0}$ is defined in $\left(k_{2}\right)$.
Next, let a cut-off function $\varphi \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{3}\right)$ be such that $0 \leq \varphi \leq 1,\left.\varphi\right|_{B_{r}} \equiv 1$ and $\operatorname{supp} \varphi \subset B_{2 r}$ for some $r>0$. Set $u_{\epsilon}(x)=\varphi U_{\epsilon, x_{0}}(x)$, then $u_{\epsilon} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ and $u_{\epsilon} \geq 0$ for all $x \in \mathbb{R}^{3}$. Let $\epsilon$ be small enough, it follows from [20] that

$$
\left\{\begin{array}{l}
\left|\nabla u_{\epsilon}\right|_{2}^{2}=K_{1}+O\left(\epsilon^{\frac{1}{2}}\right), \quad\left|u_{\epsilon}\right|_{6}^{2}=K_{2}+O(\epsilon),  \tag{2.7}\\
\int_{\mathbb{R}^{3}} u_{\epsilon}^{2} d x=O\left(\epsilon^{\frac{1}{2}}\right)
\end{array}\right.
$$

where $K_{1}, K_{2}$ are positive constants. Moreover,

$$
\begin{equation*}
\frac{K_{1}}{K_{2}}=S \tag{2.8}
\end{equation*}
$$

Lemma 2.5. Suppose that $\left(k_{1}\right)-\left(k_{2}\right)$ hold. Then there exists $u_{1} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ such that

$$
\begin{equation*}
\sup _{t \geq 0} I_{\lambda}\left(t u_{1}\right)<\Lambda-C_{0} \lambda \tag{2.9}
\end{equation*}
$$

Proof. We first claim that there exist $t_{\epsilon}>0$ and positive constants $t_{0}, T_{1}$ independent of $\epsilon, \lambda$, such that $\sup _{t \geq 0} I_{\lambda}\left(t u_{\epsilon}\right)=I_{\lambda}\left(t_{\epsilon} u_{\epsilon}\right)$ and

$$
\begin{equation*}
0<t_{0} \leq t_{\epsilon} \leq T_{1}<\infty \tag{2.10}
\end{equation*}
$$

Indeed, since

$$
\begin{aligned}
& \lim _{t \rightarrow+\infty} I_{\lambda}\left(t u_{\epsilon}\right) \\
= & \lim _{t \rightarrow+\infty}\left(\frac{a}{2} t^{2}\left\|u_{\epsilon}\right\|^{2}+\frac{b}{4} t^{4}\left\|u_{\epsilon}\right\|^{4}-\frac{1}{6} t^{6} \int_{\mathbb{R}^{3}}\left|u_{\epsilon}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(t u_{\epsilon}\right) d x\right) \\
= & -\infty,
\end{aligned}
$$

$I_{\lambda}\left(t u_{\epsilon}\right)=0$ for $t=0$ and $I_{\lambda}\left(t u_{\epsilon}\right)>0$ for $t$ small enough, there exists $t_{\epsilon}>0$ such that

$$
\begin{equation*}
I_{\lambda}\left(t_{\epsilon} u_{\epsilon}\right)=\sup _{t \geq 0} I_{\lambda}\left(t u_{\epsilon}\right) \text { and }\left.\frac{d I_{\lambda}\left(t u_{\epsilon}\right)}{d t}\right|_{t=t_{\epsilon}}=0 \tag{2.11}
\end{equation*}
$$

It follows from (2.11) and (2.1) that

$$
\begin{align*}
0 \geq & t_{\epsilon} a\left\|u_{\epsilon}\right\|^{2}+t_{\epsilon}^{3} b\left\|u_{\epsilon}\right\|^{4}-t_{\epsilon}^{5} \int_{\mathbb{R}^{3}}\left|u_{\epsilon}\right|^{6} d x \\
& -\lambda \int_{\mathbb{R}^{3}} k(x)\left(b_{1}\left|t_{\epsilon} u_{\epsilon}\right|^{q-1}+b_{2}\left|t_{\epsilon} u_{\epsilon}\right|^{p-1}\right) u_{\epsilon} d x \tag{2.12}
\end{align*}
$$

or

$$
\begin{align*}
0 \leq & t_{\epsilon} a\left\|u_{\epsilon}\right\|^{2}+t_{\epsilon}^{3} b\left\|u_{\epsilon}\right\|^{4}-t_{\epsilon}^{5} \int_{\mathbb{R}^{3}}\left|u_{\epsilon}\right|^{6} d x \\
& +\lambda \int_{\mathbb{R}^{3}} k(x)\left(b_{1}\left|t_{\epsilon} u_{\epsilon}\right|^{q-1}+b_{2}\left|t_{\epsilon} u_{\epsilon}\right|^{p-1}\right) u_{\epsilon} d x \tag{2.13}
\end{align*}
$$

On one hand, as $4<p, q<6$, by (2.12) and

$$
\begin{aligned}
& a\left\|u_{\epsilon}\right\|^{2}+3 t_{\epsilon}^{2} b\left\|u_{\epsilon}\right\|^{4}-5 t_{\epsilon}^{4} \int_{\mathbb{R}^{3}}\left|u_{\epsilon}\right|^{6} d x \\
& -\lambda \int_{\mathbb{R}^{3}} k(x)\left\{b_{1}(q-1) t_{\epsilon}^{q-2}\left|u_{\epsilon}\right|^{q} d x+b_{2}(p-1) t_{\epsilon}^{p-2}\left|u_{\epsilon}\right|^{p}\right\} d x \leq 0
\end{aligned}
$$

we can obtain easily that $t_{\epsilon}$ is bounded from below. Therefore, there exists a positive constant $t_{0}$ independent of $\epsilon$ and $\lambda$, satisfying $0<t_{0} \leq t_{\epsilon}$.

On the other hand, by (2.13) and
$\frac{a\left\|u_{\epsilon}\right\|^{2}}{t_{\epsilon}^{2}}+b\left\|u_{\epsilon}\right\|^{4}-t_{\epsilon}^{2} \int_{\mathbb{R}^{3}}\left|u_{\epsilon}\right|^{6} d x+\lambda \int_{\mathbb{R}^{3}} k(x)\left(b_{1} t_{\epsilon}^{q-4}\left|u_{\epsilon}\right|^{q}+b_{2} t_{\epsilon}^{p-4}\left|u_{\epsilon}\right|^{p}\right) d x \geq 0$,
we see that $t_{\epsilon}$ is bounded from above for all $\epsilon>0$ small enough. Consequently, we can conclude that (2.10) holds.

Set

$$
h\left(t_{\epsilon} u_{\epsilon}\right)=\frac{a}{2} t_{\epsilon}^{2}\left\|u_{\epsilon}\right\|^{2}+\frac{b}{4} t_{\epsilon}^{4}\left\|u_{\epsilon}\right\|^{4}-\frac{1}{6} t_{\epsilon}^{6} \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x .
$$

We claim that

$$
\begin{equation*}
h\left(t_{\epsilon} u_{\epsilon}\right) \leq \Lambda+C_{3} \epsilon^{\frac{1}{2}}, \tag{2.14}
\end{equation*}
$$

where $C_{3}$ is independent of $\epsilon, \lambda$.
Indeed define

$$
g(t)=\frac{a}{2} t^{2}\left\|u_{\epsilon}\right\|^{2}+\frac{b}{4} t^{4}\left\|u_{\epsilon}\right\|^{4}-\frac{1}{6} t^{6} \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x .
$$

It follows from

$$
\lim _{t \rightarrow \infty} g(t)=-\infty, g(0)=0 \text { and } \lim _{t \rightarrow 0^{+}} g(t)>0
$$

that $\sup _{t \geq 0} g(t)$ is achieved at $T_{\epsilon}>0$, that is

$$
\left.g^{\prime}(t)\right|_{T_{\epsilon}}=a T_{\epsilon}\left\|u_{\epsilon}\right\|^{2}+b T_{\epsilon}^{3}\left\|u_{\epsilon}\right\|^{4}-T_{\epsilon}^{5} \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x=0 .
$$

A direct computation implies

$$
T_{\epsilon}=\left(\frac{b\left\|u_{\epsilon}\right\|^{4}+\sqrt{b^{2}\left\|u_{\epsilon}\right\|^{8}+4 a\left\|u_{\epsilon}\right\|^{2} \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x}}{2 \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x}\right)^{\frac{1}{2}} .
$$

Note that $g(t)$ is increasing in the interval $\left[0, T_{\epsilon}\right]$, then by (2.7) and (2.8), we obtain

$$
\begin{aligned}
h\left(t_{\epsilon} u_{\epsilon}\right) & \leq g\left(T_{\epsilon}\right) \\
& =\frac{a b\left\|u_{\epsilon}\right\|^{6}}{4 \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x}+\frac{b^{3}\left\|u_{\epsilon}\right\|^{12}}{24\left(\int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x\right)^{2}}+\frac{\left(b^{2}\left\|u_{\epsilon}\right\|^{8}+4 a\left\|u_{\epsilon}\right\|^{2} \int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x\right)^{\frac{3}{2}}}{24\left(\int_{\mathbb{R}^{3}} u_{\epsilon}^{6} d x\right)^{2}} \\
& =\frac{a b S^{3}}{4}+\frac{b^{3} S^{6}}{24}+\frac{\left(b^{2} S^{4}+4 a S\right)^{\frac{3}{2}}}{24}+O\left(\epsilon^{\frac{1}{2}}\right) \\
& =\Lambda+O\left(\epsilon^{\frac{1}{2}}\right) .
\end{aligned}
$$

Hence there exists $C_{3}>0$ (independent of $\epsilon, \lambda$ ) such that (2.14) holds.
It is easy to show that $\left\{x\left|\left|x-x_{0}\right|<\rho_{1}\right\} \subset\left\{x\left|\left|t_{\epsilon} u_{\epsilon}(x)\right| \geq \delta_{0}\right\}\right.\right.$. Since $4<$ $p, q<6$, together with $\left(k_{2}\right)$ and (2.2), when $0<\epsilon<\min \left\{\left(\frac{t_{0} \varphi\left(x_{0}\right) \cdot c}{\delta_{0}}\right)^{4}, \rho_{1}^{2}\right\}$, we get
$\int_{\mathbb{R}^{3}} k(x) G\left(t_{\epsilon} u_{\epsilon}\right) d x=\int_{\left|t_{\epsilon} u_{\epsilon}\left(x_{0}\right) \leq \delta_{0}\right|} k(x) G\left(t_{\epsilon} u_{\epsilon}\right) d x+\int_{\left|t_{\epsilon} u_{\epsilon}\left(x_{0}\right) \geq \delta_{0}\right|} k(x) G\left(t_{\epsilon} u_{\epsilon}\right) d x$

$$
\begin{align*}
& \geq \int_{\left|t_{\epsilon} u_{\epsilon}\left(x_{0}\right) \leq \delta_{0}\right|} k(x) b_{3}\left|t_{\epsilon} u_{\epsilon}\right|^{q} d x+\int_{\left|t_{\epsilon} u_{\epsilon}\left(x_{0}\right) \geq \delta_{0}\right|} k(x) b_{4}\left|t_{\epsilon} u_{\epsilon}\right|^{p} d x \\
& \geq \int_{\left|t_{\epsilon} u_{\epsilon}\left(x_{0}\right) \geq \delta_{0}\right|} k(x) b_{4}\left|t_{\epsilon} u_{\epsilon}\right|^{p} d x  \tag{2.15}\\
& \geq b_{4} \cdot C^{p} \cdot \delta_{1} \cdot t_{\epsilon}^{p} \int_{\left|x-x_{0}\right|<\rho_{1}} \frac{\varphi^{p}\left|x-x_{0}\right|^{-\beta} \epsilon^{\frac{p}{4}}}{\left(\epsilon+\left|x-x_{0}\right|^{2}\right)^{\frac{p}{2}}} d x
\end{align*}
$$

$$
\begin{aligned}
& \geq C_{4} \cdot \epsilon^{\frac{p}{4}} \cdot t_{\epsilon}^{p} \int_{0}^{\rho_{1}} \frac{r^{2}}{r^{\beta}\left(\epsilon+r^{2}\right)^{\frac{p}{2}}} d r \\
& \geq C_{5} \cdot \epsilon^{\frac{3}{2}-\frac{p}{4}-\frac{\beta}{2}} \cdot t_{\epsilon}^{p}
\end{aligned}
$$

where $C_{4}, C_{5}$ are independent of $\epsilon, \lambda$. Since $3-\frac{p}{2}<\beta<3$, then $\frac{6-p-2 \beta}{2}<0$. Let $\epsilon=\lambda^{2}, 0<\lambda<\lambda_{0}=\left(\frac{C_{5} T_{1}^{2}}{C_{0}+C_{3}}\right)^{\frac{6-p-2 \beta}{2}}$, by using (2.14) and (2.15), we deduce

$$
\begin{aligned}
I_{\lambda}\left(t_{\epsilon} u_{\epsilon}\right) & =h\left(t_{\epsilon} u_{\epsilon}\right)-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(t_{\epsilon} u_{\epsilon}\right) d x \\
& \leq \Lambda+C_{3} \epsilon^{\frac{1}{2}}-\lambda C_{5} \cdot \epsilon^{\frac{3}{2}-\frac{p}{4}-\frac{\beta}{2}} \cdot T_{1}^{2} \\
& <\Lambda-C_{0} \lambda .
\end{aligned}
$$

Then $I_{\lambda}\left(t_{\epsilon} u_{\epsilon}\right)<\Lambda-C_{0} \lambda$. Consequently, there exists $u_{1} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ such that (2.9) holds. This completes the proof.

Theorem 2.6. Under the hypotheses of Theorem 1.1, the problem (1.1) has at least a positive solution.

Proof. For $4<p, q<6$, there exists $\delta_{2}>0$ such that $\Lambda-C_{0} \lambda>0$ for every $\lambda \in\left(0, \delta_{2}\right)$. Set $\lambda_{*}=\min \left\{\delta_{2}, \lambda_{0}\right\}$, then Lemmas 2.1-2.5 hold when $\lambda \in\left(0, \lambda_{*}\right)$. By Lemma 2.2, we can conclude that $I_{\lambda}$ satisfies the mountain-pass geometry, so there exists a $(P S)_{c}$ sequence $\left\{u_{n}\right\} \subset \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$, such that

$$
\begin{equation*}
I_{\lambda}\left(u_{n}\right) \rightarrow c>\alpha, \quad I_{\lambda}^{\prime}\left(u_{n}\right) \rightarrow 0 \tag{2.16}
\end{equation*}
$$

where

$$
c=\inf _{\gamma \in \Gamma} \max _{t \in[0,1]} I_{\lambda}(\gamma(t)),
$$

and

$$
\Gamma=\left\{\gamma \in \mathrm{C}\left([0,1], \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)\right): \gamma(0)=0, \gamma(1)=u_{0}\right\} .
$$

By Lemma 2.5, we obtain that

$$
\begin{equation*}
0<\alpha<c \leq \max _{t \in[0,1]} I_{\lambda}(t \tilde{u}) \leq \sup _{t \geq 0} I_{\lambda}(t \tilde{u})<\Lambda-C_{0} \lambda . \tag{2.17}
\end{equation*}
$$

Furthermore, by Lemma 2.4, $\left\{u_{n}\right\}$ is bounded in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. Then $\left\{u_{n}\right\}$ is bounded in $L^{6}\left(\mathbb{R}^{3}\right)$ and there exists $u_{*} \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ such that

$$
u_{n} \rightharpoonup u_{*}, \quad \text { weakly in } \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)
$$

In the following, we only need to prove $u_{n} \rightarrow u_{*}$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$, then Theorem 2.6 is obtained. Let us first prove that, for all $\phi \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$, there holds

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) \cdot \phi(x) d x \rightarrow \int_{\mathbb{R}^{3}} k(x) g\left(u_{*}\right) \cdot \phi(x) d x . \tag{2.18}
\end{equation*}
$$

For any $\epsilon>0$, since $k \in L^{\frac{6}{6-q}}\left(\mathbb{R}^{3}\right) \bigcap L^{\frac{6}{6-p}}\left(\mathbb{R}^{3}\right)$, there exists $\rho_{2} \equiv \rho_{2}(\epsilon)>0$ such that

$$
|k|_{\frac{6}{6-q}, \mathbb{R}^{3} \backslash B_{\rho_{2}}(0)}<\epsilon \text { and }|k|_{\frac{6}{6-p},}, \mathbb{R}^{3} \backslash B_{\rho_{2}}(0)<\epsilon .
$$

On one hand, by using the boundedness of the sequence $\left\{u_{n}\right\}$, we deduce that

$$
\begin{equation*}
\int_{\mathbb{R}^{3} \backslash B_{\rho_{2}}(0)} k(x)\left(g\left(u_{n}\right)-g\left(u_{*}\right)\right) \cdot \phi d x \leq C(\phi) \epsilon . \tag{2.19}
\end{equation*}
$$

On the other hand, since $g$ is continuous and $u_{n} \rightarrow u_{*}$ strongly in $L_{l o c}^{p}\left(\mathbb{R}^{3}\right)$, we have

$$
g\left(u_{n}\right) \rightarrow g\left(u_{*}\right) \text { strongly in } L_{l o c}^{p}\left(\mathbb{R}^{3}\right)
$$

By the Hölder inequality, for any $\epsilon>0$, we have

$$
\begin{equation*}
\int_{B_{\rho_{2}}(0)} k(x)\left(g\left(u_{n}\right)-g\left(u_{*}\right)\right) \cdot \phi(x) d x \leq \hat{C}(\phi) \epsilon \tag{2.20}
\end{equation*}
$$

for $n$ large enough. Then from (2.19), (2.20) and the arbitrary choice of $\epsilon$, we deduce that (2.18) holds. Similarly we also get

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} u_{n}^{5} \phi(x) d x \rightarrow \int_{\mathbb{R}^{3}} u_{*}^{5} \phi(x) d x . \tag{2.21}
\end{equation*}
$$

Set $\lim _{n \rightarrow \infty}\left\|u_{n}\right\|=l$, by (2.18) and (2.21), for any $\phi \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ as $n \rightarrow \infty$ there holds

$$
\begin{aligned}
\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), \phi\right\rangle & =\left(a+b\left\|u_{n}\right\|^{2}\right) \int_{\mathbb{R}^{3}}\left(\nabla u_{n}, \nabla \phi\right) d x-\int_{\mathbb{R}^{3}} u_{n}^{5} \phi d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) \cdot \phi d x \\
& \rightarrow\left(a+b l^{2}\right) \int_{\mathbb{R}^{3}}\left(\nabla u_{*}, \nabla \phi\right) d x-\int_{\mathbb{R}^{3}} u_{*}^{5} \phi d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{*}\right) \cdot \phi d x \\
& =\left\langle I_{\lambda}^{\prime}\left(u_{*}\right), \phi\right\rangle .
\end{aligned}
$$

Thus from (2.16) we get that $\left\langle I_{\lambda}^{\prime}\left(u_{*}\right), \phi\right\rangle=0$ for all $\phi \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$.
In particular, let $u_{*}=\phi$, we have

$$
\begin{equation*}
\left(a+b l^{2}\right)\left\|u_{*}\right\|^{2}-\int_{\mathbb{R}^{3}} u_{*}^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{*}\right) u_{*} d x=0 \tag{2.22}
\end{equation*}
$$

Since $\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), u_{n}\right\rangle \rightarrow 0$, there holds

$$
\left(a+b\left\|u_{n}\right\|^{2}\right)\left\|u_{n}\right\|^{2}-\int_{\mathbb{R}^{3}} u_{n}^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{n}\right) u_{n} d x=o(1) .
$$

Combining this with Lemma 2.4, we get that

$$
\begin{equation*}
\left(a+b l^{2}\right) l^{2}-\int_{\mathbb{R}^{3}} u_{*}^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(u_{*}\right) u_{*} d x=0 \tag{2.23}
\end{equation*}
$$

Consequently, by (2.22) and (2.23), we have $\left\|u_{*}\right\|=l$. That is $\lim _{n \rightarrow \infty}\left\|u_{n}\right\|=$ $\left\|u_{*}\right\|$. Moreover, $\left\|u_{n}-u_{*}\right\| \rightarrow 0$ implies that $u_{n} \rightarrow u_{*}$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. Thus,

$$
\begin{equation*}
I_{\lambda}\left(u_{*}\right)=\lim _{n \rightarrow \infty} I_{\lambda}\left(u_{n}\right)=c>\alpha>0 . \tag{2.24}
\end{equation*}
$$

It follows from (2.24) that $u_{*} \not \equiv 0$, then $u_{*} \geq 0$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. The strong maximum principle implies that $u_{*}$ is a positive solution of (1.1). This completes the proof.

## 3. Proof of Theorem 1.1

In this section, we shall prove that problem (1.1) has at least one positive ground state solution via variational method.

Proof of Theorem 1.1. By Theorem 2.6, we have obtained the existence of positive solution for (1.1). In this section, we will consider the existence of positive ground state solution.

Let

$$
m=\inf \left\{I_{\lambda}(u): u \in \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right), u \neq 0, I_{\lambda}^{\prime}(u)=0\right\}
$$

From the definition of $m$, there exists $\left\{v_{n}\right\} \subset \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right) \backslash\{0\}$ such that

$$
\begin{equation*}
I_{\lambda}\left(v_{n}\right) \rightarrow m, \quad I_{\lambda}^{\prime}\left(v_{n}\right) \rightarrow 0, \quad n \rightarrow \infty \tag{3.1}
\end{equation*}
$$

Obviously from (3.1), we can easily deduce that $\left\{v_{n}\right\}$ is bounded in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$. Then there exist a subsequence of $\left\{v_{n}\right\}$ (still denoted by $\left\{v_{n}\right\}$ ) and $v_{*} \in$ $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ such that

$$
v_{n} \rightharpoonup v_{*} \quad \text { weakly in } \mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right) .
$$

We claim $v_{*} \neq 0$. Otherwise $v_{n} \rightharpoonup 0$ weakly in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$, then by Lemma 2.1 we get that

$$
\int_{\mathbb{R}^{3}} k(x) g\left(v_{n}\right) v_{n} d x \rightarrow 0
$$

From (3.1), it follows that

$$
a\left\|v_{n}\right\|^{2}+b\left\|v_{n}\right\|^{4}-\int_{\mathbb{R}^{3}}\left|v_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(v_{n}\right) v_{n} d x=o(1) .
$$

Therefore,

$$
\begin{equation*}
a\left\|v_{n}\right\|^{2}+b\left\|v_{n}\right\|^{4}-\int_{\mathbb{R}^{3}}\left|v_{n}\right|^{6} d x=o(1) . \tag{3.2}
\end{equation*}
$$

Set $\lim _{n \rightarrow \infty}\left\|v_{n}\right\|=l$. By (3.2) and (1.3), we can conclude that

$$
l^{2} \geq \frac{b S^{3}+\sqrt{b^{2} S^{6}+4 a S^{3}}}{2} .
$$

Next we claim that

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} k(x) G\left(v_{n}\right) d x \rightarrow 0 . \tag{3.3}
\end{equation*}
$$

Indeed, we just need to prove

$$
\int_{\mathbb{R}^{3}} k(x) b_{1}\left|v_{n}\right|^{q} d x+\int_{\mathbb{R}^{3}} k(x) b_{2}\left|v_{n}\right|^{p} d x \rightarrow 0 .
$$

Since $k \in L^{\frac{6}{6-q}}\left(\mathbb{R}^{3}\right) \bigcap L^{\frac{6}{6-p}}\left(\mathbb{R}^{3}\right)$, for any $\epsilon>0$, there exists $\rho_{3} \equiv \rho_{3}(\epsilon)>0$ such that

$$
|k|_{\frac{6}{6-q}, \mathbb{R}^{3} \backslash B_{\rho_{3}}(0)}<\epsilon \text { and }|k|_{\frac{6}{6-p},}, \mathbb{R}^{3} \backslash B_{\rho_{2}}(0)<\epsilon .
$$

On one hand, by the boundedness of the sequence $\left\{v_{n}\right\}$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ and Hölder inequality, one has

$$
\begin{equation*}
b_{1} \int_{\mathbb{R}^{3} \backslash B_{\rho_{3}}(0)} k(x)\left|v_{n}\right|^{q} d x \leq C_{6} \epsilon . \tag{3.4}
\end{equation*}
$$

On the other hand, we can conclude

$$
\begin{equation*}
b_{1} \int_{B_{\rho_{3}(0)}} k(x)\left|v_{n}\right|^{q} d x \leq \hat{C}_{6} \epsilon \tag{3.5}
\end{equation*}
$$

for large $n$. Then by (3.4), (3.5) and the arbitrary choice of $\epsilon$, one gets

$$
b_{1} \int_{\mathbb{R}^{3}} k(x)\left|v_{n}\right|^{q} d x \rightarrow 0, \quad n \rightarrow \infty
$$

Similarly, we can derive that

$$
b_{2} \int_{\mathbb{R}^{3}} k(x)\left|v_{n}\right|^{p} d x \rightarrow 0, \quad n \rightarrow \infty
$$

Therefore (3.3) holds.
By (3.1), (3.2) and (3.3), we have

$$
\begin{aligned}
m & =\lim _{n \rightarrow \infty}\left\{\frac{a}{2}\left\|v_{n}\right\|^{2}+\frac{b}{4}\left\|v_{n}\right\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}\left|v_{n}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(v_{n}\right) d x\right\} \\
& =\lim _{n \rightarrow \infty}\left\{\frac{a}{3}\left\|v_{n}\right\|^{2}+\frac{b}{12}\left\|v_{n}\right\|^{4}\right\} \\
& \geq \frac{a b S^{3}}{4}+\frac{b^{3} S^{6}}{24}+\frac{\left(b^{2} S^{4}+4 a S\right)^{\frac{3}{2}}}{24} \\
& =\Lambda
\end{aligned}
$$

Together with Lemma 2.5, $\Lambda \leq m<\Lambda-C_{0} \lambda$, this is a contradiction. Then $v_{n} \rightharpoonup v_{*} \neq 0$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ and $I_{\lambda}^{\prime}\left(v_{*}\right)=0$. From Theorem 2.6, we have concluded that $v_{n} \rightarrow v_{*}$ in $\mathcal{D}^{1,2}\left(\mathbb{R}^{3}\right)$ and $v_{*}$ is a positive solution of (1.1), which implies that $I_{\lambda}\left(v_{*}\right) \geq m$. Now to show $m \geq I_{\lambda}\left(v_{*}\right)$.

Indeed, since $I_{\lambda}^{\prime}\left(v_{*}\right)=0$ we have

$$
\begin{aligned}
I_{\lambda}\left(v_{*}\right)= & I_{\lambda}\left(v_{*}\right)-\frac{1}{6}\left\langle I_{\lambda}^{\prime}\left(v_{*}\right), v_{*}\right\rangle \\
= & \frac{a}{2}\left\|v_{*}\right\|^{2}+\frac{b}{4}\left\|v_{*}\right\|^{4}-\frac{1}{6} \int_{\mathbb{R}^{3}}\left|v_{*}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) G\left(v_{*}\right) d x \\
& -\frac{1}{6}\left\{a\left\|v_{*}\right\|^{2}+b\left\|v_{*}\right\|^{4}-\int_{\mathbb{R}^{3}}\left|v_{*}\right|^{6} d x-\lambda \int_{\mathbb{R}^{3}} k(x) g\left(v_{*}\right) v_{*} d x\right\} \\
= & \frac{a}{3}\left\|v_{*}\right\|^{2}+\frac{b}{12}\left\|v_{*}\right\|^{4}-\lambda \int_{\mathbb{R}^{3}} k(x)\left(G\left(v_{*}\right)-\frac{1}{6} g\left(v_{*}\right) v_{*}\right) d x .
\end{aligned}
$$

By $I_{\lambda}\left(v_{n}\right) \rightarrow m$, we get

$$
\begin{aligned}
m+o(1) & =I_{\lambda}\left(v_{n}\right) \\
& =\frac{a}{3}\left\|v_{n}\right\|^{2}+\frac{b}{12}\left\|v_{n}\right\|^{4}-\lambda \int_{\mathbb{R}^{3}} k(x)\left(G\left(v_{n}\right)-\frac{1}{6} g\left(v_{n}\right) v_{n}\right) d x
\end{aligned}
$$

It deduces from Lebesgue dominated convergence theorem that

$$
\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} k(x) G\left(v_{n}\right) d x=\int_{\mathbb{R}^{3}} k(x) G\left(v_{*}\right) d x
$$

Combining this with Fatou's Lemma, we obtain that

$$
m \geq \frac{a}{3}\left\|v_{*}\right\|^{2}+\frac{b}{12}\left\|v_{*}\right\|^{4}-\lambda \int_{\mathbb{R}^{3}} k(x)\left(G\left(v_{*}\right)-\frac{1}{6} g\left(v_{*}\right) v_{*}\right) d x=I_{\lambda}\left(v_{*}\right) .
$$

Thus $v_{*} \neq 0$ satisfies $I_{\lambda}^{\prime}\left(v_{*}\right)=0$ and $I_{\lambda}\left(v_{*}\right)=m$, which implies that $v_{*}$ is a positive ground state solution of (1.1). Therefore, we obtain the existence of positive ground state solution of (1.1).

Remark 3.1. In the next paper, we hope to investigate the sign-changing solution for Kirchhoff type equation as paper $[14,17,18]$ by using the method of invariant sets of descending flow or by means of a constraint variational methods.

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